# Aberration Theory



Optical systems convert the shapes of wavefronts





The wavefront error W(x,y) is the difference between a perfect spherical wave and the actual wavefront. It is usually measured in the exit pupil and W(0,0) = 0.

The axis for this system is the Line of Sight.

In general, there is no symmetry in the eye, so W(x,y) can take on any complex shape.



A reference sphere of radius R is taken as the ideal spherical wavefront. R is just the distance from the exit pupil to the image plane.

 $\delta\eta$ ' is the transverse ray error and represents the distance between where the ideal and the actual rays strike the image plane.

dl' is the longitudinal ray error and represents the distance the actual ray crosses the line of sight from the image plane.

#### Power Error

In Visual Optics, longitudinal aberrations are usually given in terms of a "power error" as opposed to a distance.



#### Power Error

The "power error" is related to the slope of the wavefront

$$\mathrm{d}\phi = \frac{1}{\mathrm{r}} \frac{\partial \mathrm{W}(\mathrm{r})}{\partial \mathrm{r}}$$

Defocus Example:  $2\lambda s$  of defocus ( $\lambda = 0.5 \mu m$ ) at edge of 6 mm pupil

W(r) = 
$$\frac{2(0.5 \times 10^{-3} \text{ mm})}{(3 \text{ mm})^2}$$
r<sup>2</sup> = 0.0001111×r<sup>2</sup>

 $d\phi = 0.0002222 \text{ mm}^{-1} = 0.2222 \text{ Diopters}$ 

## Power Error

The preceding defocus example shows that  $d\phi$  is constant, which means that dl' is the same regardless of where the ray entered the eye.



#### Measuring Defocus in the Eye



# **Differential Geometry**



- Every point on a continuous surface has two Principal Curvatures.
- ► These curvatures represent the maximum and minimum curvature through this point and
- ▶ The principal curvatures are always along orthogonal axes.
- Calculated from the Fundamental Forms)

## **Fundamental Forms**

Form  

$$E = 1 + \left(\frac{\partial f}{\partial x}\right)^2$$
  $F = \left(\frac{\partial f}{\partial x}\right) \left(\frac{\partial f}{\partial y}\right)$   $G = 1 + \left(\frac{\partial f}{\partial y}\right)$ 

Second Fundamental Form

$$L = \frac{\partial^2 f / \partial x^2}{\left[EG - F^2\right]^{1/2}} \quad M = \frac{\partial^2 f / \partial x \partial y}{\left[EG - F^2\right]^{1/2}} \quad N = \frac{\partial^2 f / \partial y^2}{\left[EG - F^2\right]^{1/2}}$$

#### Curvatures

#### Mean Curvature

$$H = \frac{EN + GL + 2FM}{2(EG - F^2)} = \frac{1}{2}(\kappa 1 + \kappa 2)$$

**Gaussian** Curvature

$$K = \frac{LN - M^2}{EG - F^2} = \kappa 1 \kappa 2$$

**Principal Curvatures** 

$$\kappa 1 = H + \sqrt{H^2 - K}$$
$$\kappa 2 = H - \sqrt{H^2 - K}$$

#### Axial Astigmatism

Since the eye is not rotationally symmetric, astigmatism can appear on-axis. This astigmatism is primarily due to the ocular surfaces having a toric or biconic shape.



Principal Curvatures are  $1/R_x$  and  $1/R_y$  at the origin

#### **Biconic Surfaces**

Computationally similar to the toric surface, but more versatile since the biconic surface can add asphericity.



#### Astigmatic Surfaces

- The axes with the maximum and minimum radii of curvature are called the Principal Meridia (any axis is called a meridian).
- There is a steep meridian corresponding to the minimum radius of curvature.
- There is a flat meridian corresponding to the maximum radius of curvature.
- > The principal meridia are always perpendicular to each other.

# Astigmatic Surfaces

In general, and in the eye, the principal meridia do not lie along the x and y axis, but are rotated through some angle  $\theta_o$ .

$$z = \frac{r^2 \cos^2(\theta - \theta_o) / R_x + r^2 \sin^2(\theta - \theta_o) / R_y}{1 + \sqrt{1 - (1 + K_x) \frac{r^2 \cos^2(\theta - \theta_o)}{R_x^2} - (1 + K_y) \frac{r^2 \sin^2(\theta - \theta_o)}{R_y^2}}}$$

# Astigmatic Power Error

$$W(r) = Ax^{2} + By^{2} = Ar^{2} \cos^{2} \theta + Br^{2} \sin^{2} \theta$$

$$d\phi = \frac{1}{r} \frac{\partial W(r)}{\partial r} = 2A\cos^2\theta + 2B\sin^2\theta$$

For a given value of  $\theta$ ,  $d\phi$  is a constant. Axial astigmatism can be thought of as defocus that depends on meridian.

# Axial Astigmatism



If a refraction is performed through a series of slits rotated at various angles, the refractive error will oscillate between a minimum and maximum value in the presence of axial astigmatism.

## Jackson Crossed Cylinder

Crossed cylinders have a power +D along one meridian and a power -D along the orthogonal meridian.





## Chromatic Aberration

Chromatic Aberration is wavelength dependent defocus

 $W(r) = A(\lambda)r^{2}$  $d\phi(\lambda) = 2A(\lambda)$ 

For a given  $\lambda$ , d $\phi$  is constant







# Wavefront Tilt or Prism



## Wavefront Tilt



Strabismus or "Lazy Eye" causes wavefront tilt

The brain sees independent images that do not fuse in the brain. The brain does not like this discrepancy, so it will start ignoring one image. If this is not fixed early, one eye will become "blind", even though it works fine from an optical standpoint.







# Spherical Aberration



If a refraction is performed through a series of annular rings, the refractive error will vary with the size of the average ring diameter, when spherical aberration is present.



## Night Myopia



There is a myopic shift of the smallest point that is formed on the retina as the pupil dilates.

## **Oblique Astigmatism**



"Off-axis" astigmatism  $\Delta$  given as the difference between the meridional and sagittal foci

> $\Delta = \alpha^{1.5} \times 10^{-2}$  Diopters where  $\alpha$  is the field angle in degrees





