

The imaging formula is given by

$$
\begin{equation*}
\frac{1}{\mathrm{z}^{\prime}}-\frac{1}{\mathrm{z}}=\frac{1}{\mathrm{f}} . \tag{1}
\end{equation*}
$$

In conventional imaging, the object and image planes are parallel to one another with $\mathrm{z}=\mathrm{L}$ ( L is negative in the figure above) and $z^{\prime}=L^{\prime}$. If the object plane is tilted by an angle $\theta$, then the Scheimpflug condition says the image plane is tilted as well. The tilted object and image planes become functions of $y$, so the Lensmaker's formula becomes

$$
\begin{equation*}
\frac{1}{z^{\prime}(y)}-\frac{1}{z(y)}=\frac{1}{f} \tag{2}
\end{equation*}
$$

From the geometry in the image above, the object plane is described by a plane tilted about the x axis such that

$$
\begin{equation*}
\mathrm{z}(\mathrm{y})=\mathrm{L}-\mathrm{y} \tan \theta, \tag{3}
\end{equation*}
$$

where a counterclockwise rotation of the object plane corresponds to a positive value of $\theta$. Plugging this expression (3) into equation (2) and solving for $z^{\prime}(y)$ leads to

$$
\begin{equation*}
z^{\prime}(y)=\frac{\mathrm{f}(\mathrm{~L}-\mathrm{y} \tan \theta)}{\mathrm{f}+\mathrm{L}-\mathrm{y} \tan \theta} \cong \frac{\mathrm{f}(\mathrm{~L}-\mathrm{y} \tan \theta)}{\mathrm{f}+\mathrm{L}} \tag{4}
\end{equation*}
$$

where the assumption that $\mathrm{L} \gg \mathrm{y} \tan \theta$ has been made. Equation (4) also describes a plane tilted about the x axis.

## Location of Image Plane

The location of the image plane can be found by evaluating $z^{\prime}(0)$.

$$
\begin{align*}
& z^{\prime}(0)=\frac{f L}{f+L} \\
& \frac{f+L}{f L}=\frac{1}{z^{\prime}(0)}  \tag{5}\\
& \frac{1}{f}+\frac{1}{L}=\frac{1}{z^{\prime}(0)}
\end{align*}
$$

Equation (5) is just a statement of the Lensmaker's formula, requiring z' $(0)=\mathrm{L}$ ’.

## Intersection of the Object and Image Planes

The object and image planes intersect when $z(y)=z^{\prime}(y)$. This intersection occurs when

$$
\begin{equation*}
y=\frac{L}{\tan \theta} \tag{6}
\end{equation*}
$$

Plugging (6) back into the expressions for the object and image planes leads to

$$
\begin{equation*}
\mathrm{z}\left(\frac{\mathrm{~L}}{\tan \theta}\right)=\mathrm{L}-\mathrm{L}=0 \text { and } \mathrm{z}^{\prime}\left(\frac{\mathrm{L}}{\tan \theta}\right)=\frac{\mathrm{fL}}{\mathrm{~L}+\mathrm{f}}-\frac{\mathrm{fL}}{\mathrm{~L}+\mathrm{f}}=0 \tag{7}
\end{equation*}
$$

In other words, the object and image plane intersect at the plane of the lens.

## Image Plane Tilt

Equation (4) can be rewritten as

$$
\begin{equation*}
z^{\prime}(y)=\frac{f L}{f+L}-\frac{f \tan \theta}{f+L} y=L^{\prime}-y \tan \theta^{\prime} \tag{8}
\end{equation*}
$$

where

$$
\begin{equation*}
\tan \theta^{\prime}=\frac{\mathrm{f} \tan \theta}{\mathrm{~L}+\mathrm{f}} \tag{9}
\end{equation*}
$$

## Magnification

The magnification $\mathrm{m}_{0}$ for the axial object and image points is given by

$$
\begin{equation*}
\mathrm{m}_{\mathrm{o}}=\frac{\mathrm{L}^{\prime}}{\mathrm{L}}=\frac{\mathrm{f}}{\mathrm{~L}+\mathrm{f}} . \tag{10}
\end{equation*}
$$

To calculate the magnification $m$ as a function of $y$ for the tilted system, equation (4) without the approximation $L \gg y \tan \theta$ needs to be used.

$$
\begin{align*}
z^{\prime}(y)=\frac{f(L-y \tan \theta)}{f+L-y \tan \theta}=\frac{f z(y)}{f+L-y \tan \theta} & \Rightarrow m \\
m(y) & \frac{z^{\prime}(y)}{z(y)}=\frac{f}{(f+L)}\left[\frac{1}{1-\frac{y \tan \theta}{f+L}}\right]  \tag{12}\\
m & =\frac{m_{o}}{1-\frac{\tan \theta}{f+L} y}
\end{align*}
$$

Using a binomial expansion on equation (12) leads to

$$
\begin{equation*}
\mathrm{m}=\mathrm{m}_{\mathrm{o}}\left[1+\frac{\tan \theta}{\mathrm{f}+\mathrm{L}} \mathrm{y}+\ldots\right] \tag{13}
\end{equation*}
$$

In other words, the magnification is linear in y or there is keystone distortion in the system (at where the truncated binomial expansion closely approximates equation (12)).

