

Idealization of Supports and Distributed loads

Equilibrium: Rigid and Deformable Bodies

The following equations are the necessary conditions for equilibrium of a rigid body.

$$\sum F_x = 0$$

$$\sum F_y = 0$$

$$\sum F_z = 0$$

$$\sum M_x = 0$$

$$\sum M_y = 0$$

$$\sum M_z = 0$$

Forces and moments that act on a body are either external or internal.

External Forces

- Interaction between bodies.
- Interaction between body and earth.
- Fluid pressure.
- Cause the body to move or ensures that it remains at rest.
- External forces are divided into applied forces and reaction forces.
 - Applied forces cause a body to move or rotate.
 - Reaction forces hold the body in equilibrium.

Internal Forces

- Forces, which hold together the particles forming a rigid body.
- Stress = the intensity of the internal forces

Free Body Diagrams

Step 1. Determine which body or combination of bodies is to be isolated. The body chosen will usually involve one or more of the desired unknown quantities.

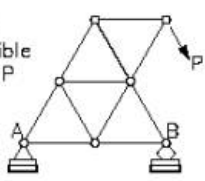
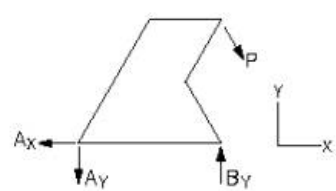
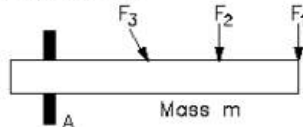
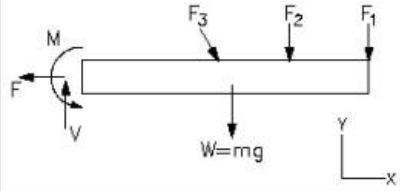
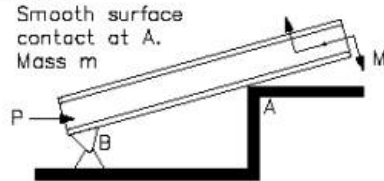
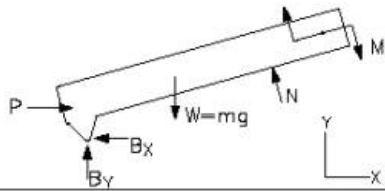
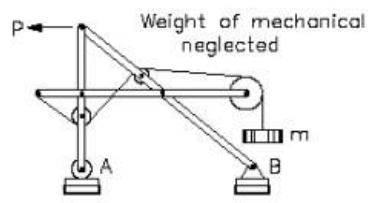
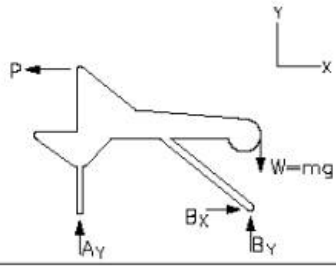
Step 2. Next, isolate the body or combination of bodies chosen with a diagram that represents its complete external boundaries.

Step 3. Represent all forces that act on the isolated body as applied by the removed contacting bodies in their proper positions in the diagram of the isolated body. Do not show the forces that the object exerts on anything else, since these forces do not affect the object itself.

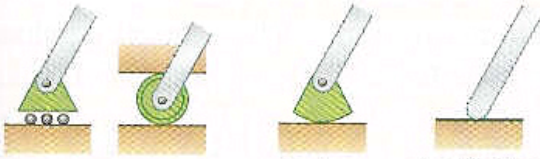

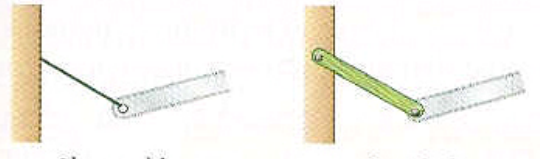
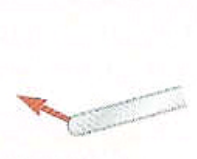
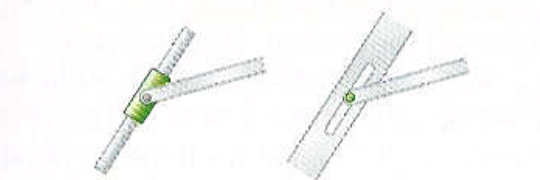
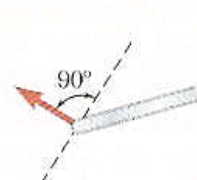

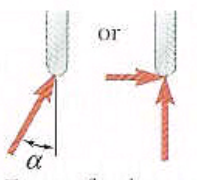
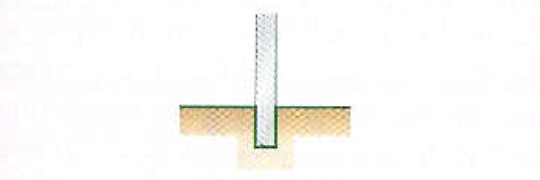
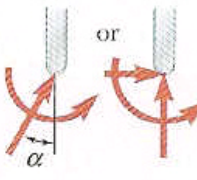
Step 4. Indicate the choice of coordinate axes directly on the diagram. Pertinent dimensions may also be represented for convenience. Note, however, that the free-body diagram serves the purpose of focusing accurate attention on the action of the

external forces; therefore, the diagram should not be cluttered with excessive information. Force arrows should be clearly distinguished from other arrows to avoid confusion.

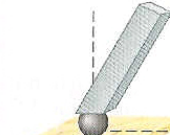
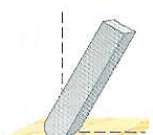


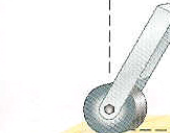
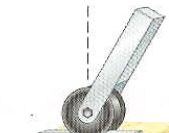
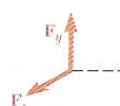
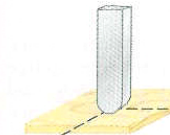
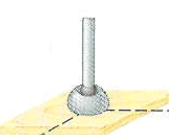
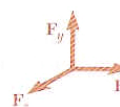

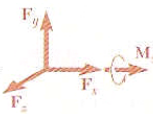

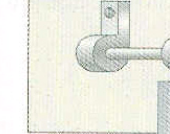

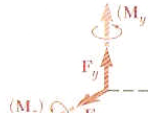


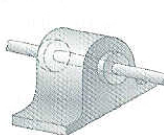

When these steps are completed a correct free-body diagram will result. Now, the appropriate equations of equilibrium may be utilized to find the proper solution.

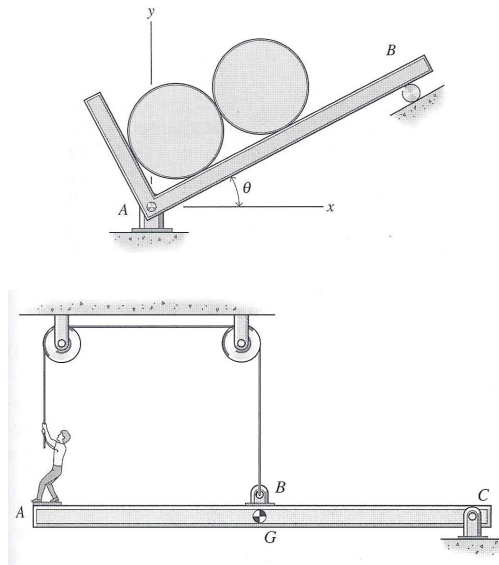
SAMPLE FREE-BODY DIAGRAMS	
Mechanical System	Free-Body Diagram of Isolated Body
<p>1. Plane truss</p> <p>Weight of truss assumed negligible compared with P</p> 	
<p>2. Cantilever beam</p> 	
<p>3. Beam</p> <p>Smooth surface contact at A.</p> <p>Mass m</p> 	
<p>4. Rigid system of interconnected bodies analyzed as a single unit</p> <p>Weight of mechanical neglected</p> 	

Idealization of 2D supports

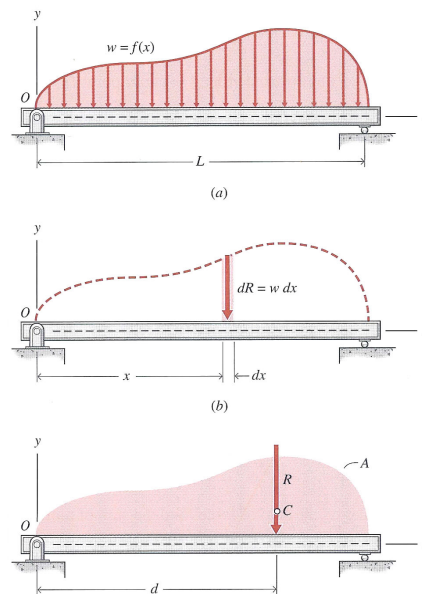
Support or Connection	Reaction	Number of Unknowns
 <p>Rollers Rocker Frictionless surface</p>	 <p>Force with known line of action</p>	1
 <p>Short cable Short link</p>	 <p>Force with known line of action</p>	1
 <p>Collar on frictionless rod Frictionless pin in slot</p>	 <p>Force with known line of action</p>	1
 <p>Frictionless pin or hinge Rough surface</p>	 <p>Force of unknown direction</p>	2
 <p>Fixed support</p>	 <p>Force and couple</p>	3

Idealization of 3D supports

 <p>Ball</p>	 <p>Frictionless surface</p>	 <p>Force with known line of action (one unknown)</p>	 <p>Cable</p> <p>Force with known line of action (one unknown)</p>
 <p>Roller on rough surface</p>	 <p>Wheel on rail</p>	 <p>Two force components</p>	
 <p>Rough surface</p>	 <p>Ball and socket</p>	 <p>Three force components</p>	
 <p>Universal joint</p>	 <p>Three force components and one couple</p>		 <p>Fixed support</p> <p>Three force components and three couples</p>
		 <p>Two force components (and two couples)</p>	
 <p>Pin and bracket</p>			 <p>Three force components (and two couples)</p>

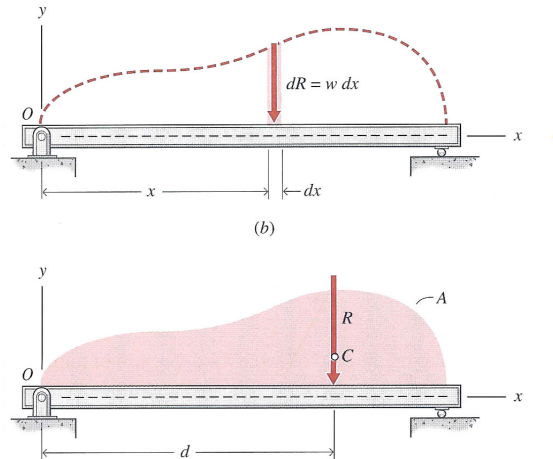
Free-Body Examples**Distributed Loads on Beams**

Beam – Structural member whose length is large compared to its cross sectional area which is loaded and supported in the direction transverse to its axis.



w = distributed line load (N/m or lb/ft)

$R = \int w dx$ = area under curve



$$M_o = \int x(w \, dx)$$

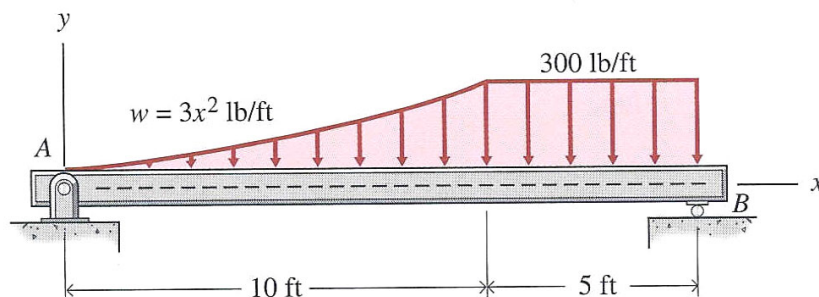
$$d = M_o/R$$

A distributed load on a beam can be replaced by a concentrated load; the magnitude of this single load is equal to the area under the load curve and its line of action passes through the centroid of that area.

Note:

The concentrated load is equivalent to the distributed load **only as far as external forces are concerned**. It can be used to determine reactions, but **should not** be used to determine internal forces and deflections.

Example Problem – Distributed loads



Determine the following:

1. The resultant force.
2. Its line of action with respect to A.
3. The reaction forces at A and B.