

Introduction to FEA

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FEA Pitfalls

Tony Rizzo (Bell Labs) quotes:

- “Some engineers and managers look upon commercially available FEA programs as automated tools for design. In fact, nothing could be further from reality than that simplistic view of today's powerful programs. **The engineer who plunges ahead, thinking that a few clicks of the left mouse button will solve all his problems, is certain to encounter some very nasty surprises.**”
- “**With the exception of a very few trivial cases, all finite element solutions are wrong**, and they are likely to be more wrong than you think. **One experienced analysis estimates that 80% of all finite element solutions are gravely wrong, because the engineers doing the analyses make serious modeling mistakes.**”
- “Finite element analysis is a very powerful tool with which to design products of superior quality. Like all tools, it can be used properly, or it can be misused. **The keys to using this tool successfully are to understand the nature of the calculations that the computer is doing and to pay attention to the physics.**”

FEA Theory

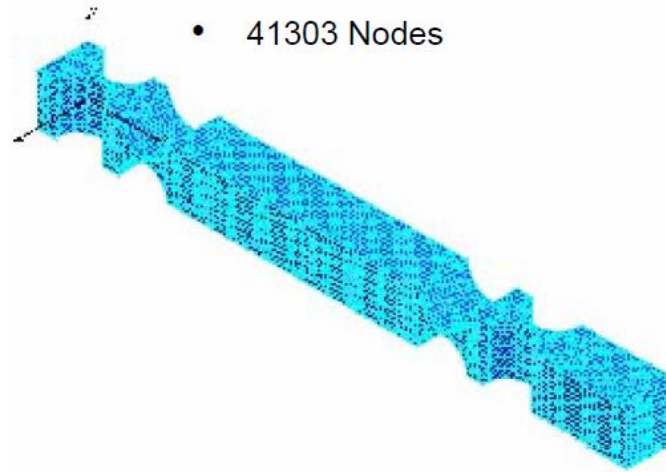
- Finite element method – numerical procedure for solving a continuum mechanics problem with acceptable accuracy.
- Subdivide a large problem into small elements connected by nodes.

Flexure Solid Model



Flexure FEA Model

- 123399 DOF
- 25795 TETA4 Elements
- 41303 Nodes



- FEM by minimizing the total potential energy of the system to obtain primary unknowns - the temperatures, stresses, flows, or other desired

FEA example for spring

❖ Equilibrium : Minimum of Potential energy

(Assume 1D problem : x axis)

$$\Pi = \textit{strain energy} - \textit{work} = \frac{1}{2} \sigma \varepsilon - Fx$$

$$\frac{\partial \Pi}{\partial x} = 0$$

For a spring,

$$\Pi = \frac{1}{2} kx^2 - Fx, \quad \frac{\partial \Pi}{\partial x} = kx - F = 0$$

$$\rightarrow \mathbf{F = kx}$$

General FEA formula

The total potential energy can be expressed as:

$$\Pi = \frac{1}{2} \int_{\Omega} \sigma^T \varepsilon dV - \int_{\Omega} d^T b dV - \int_{\Gamma} d^T q dS$$

The total potential energy of the discretized individual element:

$$\Pi_e = \frac{1}{2} \int_{\Omega_e} u^T (B^T E B)^T u dV - \int_{\Omega_e} u^T N^T p dV - \int_{\Gamma} u^T N^T q dS = 0.$$

$\frac{\partial \Pi_e}{\partial u} = 0$ gives: **F = K u**, where K is stiffness Matrix, [K].

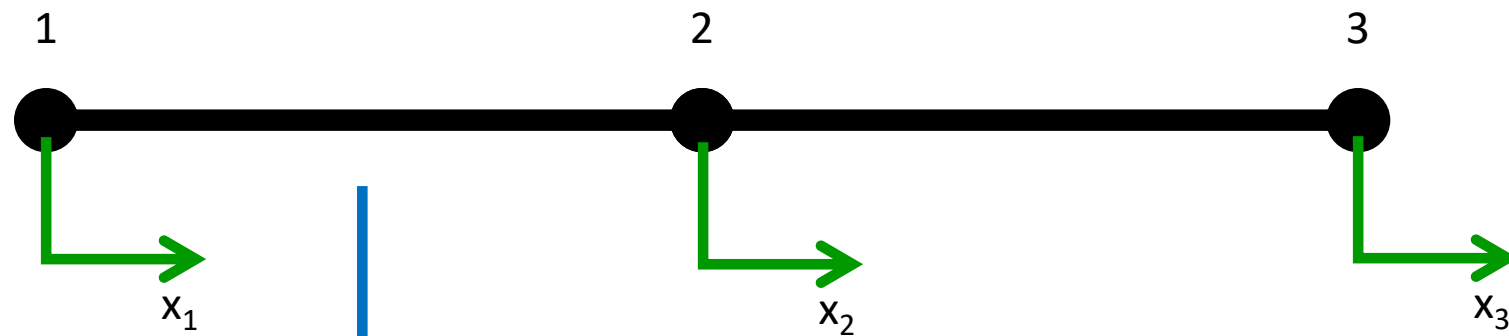
FEA Solution

❖ Simple Hook's law

$$[F] = [K] \cdot [u]$$

$$[u] = [K]^{-1} \cdot [F]$$

System stiffness matrix : 1D example

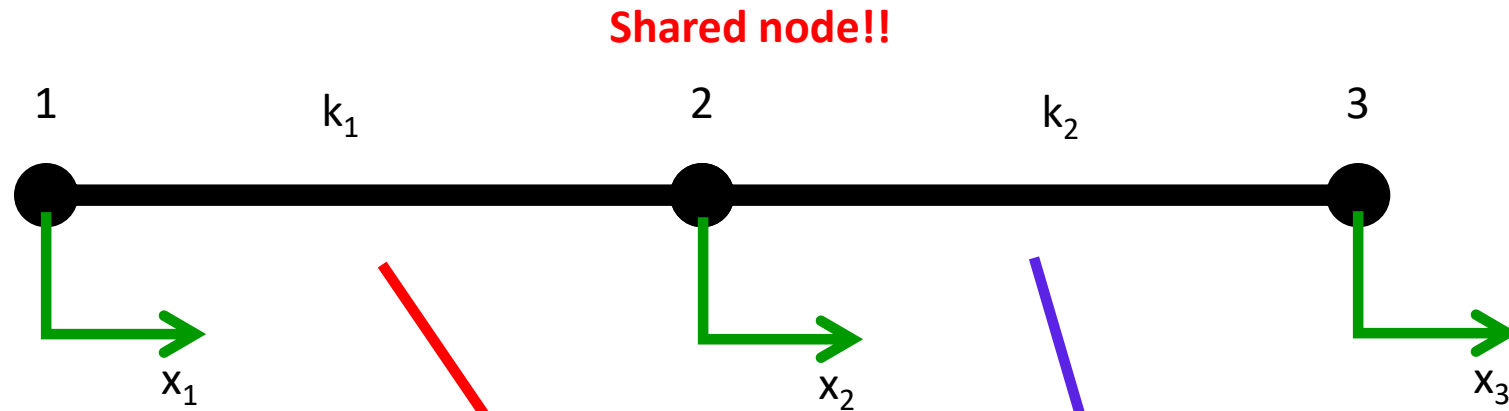


Global stiffness matrix = 3×3



Element stiffness matrix = $2 \times 2 = \begin{pmatrix} k & -k \\ -k & k \end{pmatrix}$

How to build the stiffness matrix

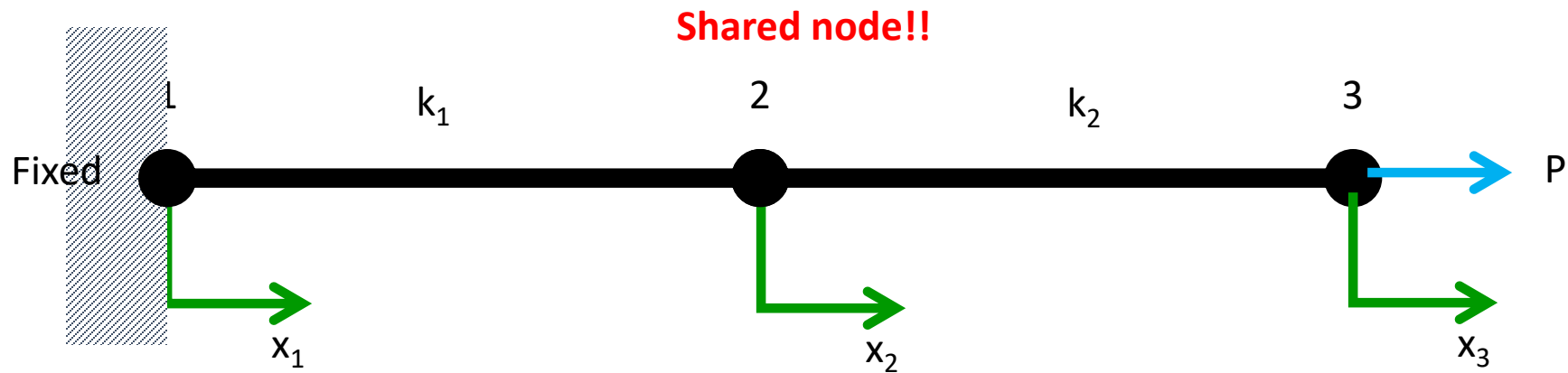


Global stiffness
matrix = 3 x 3

$$\begin{pmatrix} k_1 & -k_1 & 0 \\ -k_1 & k_1 + k_2 & -k_2 \\ 0 & -k_2 & k_2 \end{pmatrix}$$

B.C and solve

❖ Boundary condition



$$\begin{pmatrix} 0 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} k_1 & -k_1 & 0 \\ -k_1 & k_1 + k_2 & -k_2 \\ 0 & -k_2 & k_2 \end{pmatrix}^{-1} \begin{pmatrix} 0 \\ 0 \\ P \end{pmatrix}$$

Nodes

“What are they”

A node is simply a coordinate location in space where a DOF (degree of freedom) is defined.

Nodes – Properties and Characteristics

- Infinitesimally small
- Defined with reference to a global coordinate system
- Typically nodes are defined on the surface and in the interior of the component you are modeling
- Form a grid work within component as a result of the mesh
- Typically define the corners of elements
- Where we define loads and boundary conditions
- Location of our results (deformation, stress, etc.)
- Nodes are the byproduct of defining elements

Elements

“What are they”

An element is a mathematical relation that defines how a DOF of a node relates to the next.

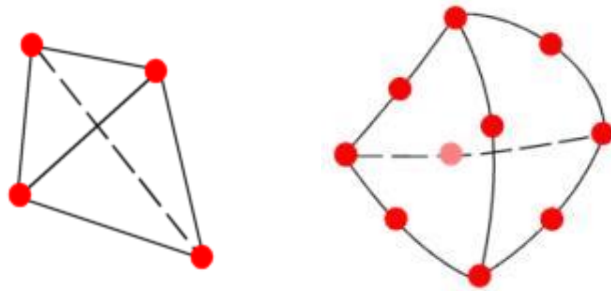
Elements – Properties and Characteristics

- Point, 2D and 3D elements
- Define a line (1D), area (2D) or volume (3D) on or within our model
- Dimensions define an “Aspect Ratio”
- A set of elements is know as the “mesh”
- Mesh shape and density is critical to the analysis
- Typically have many options that may be preset for the user
- Elements are typically what we define

SolidWorks Simulation

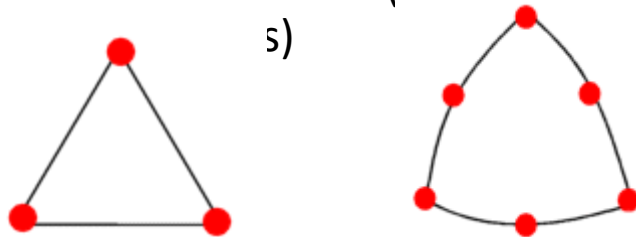
Solid Mesh

- TETRA4 and TETRA10 (4 & 10 node tetrahedron solid elements)



Shell Mesh

- SHELL3 and SHELL6 (3 & 6 node thin s)



Problems, Pitfalls and Tips

Requires planning and element / DOF knowledge

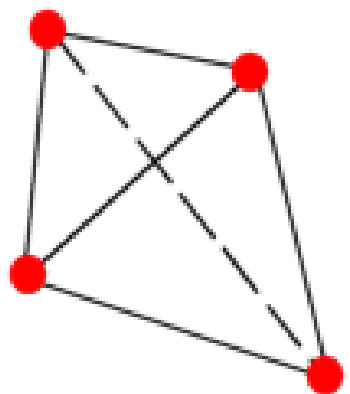
- The element defines the number of active DOFs.

TETRA4 & TETRA10 Elements

- 3 translational DOF per node
- 1 DOF per node for thermal
- TETRA4 (linear) TETRA10 (parabolic)
- Supports adaptive "P" method

SHELL3 & SHELL6 Elements

- 6 DOF per node (3 translational + 3 rotational)
- 1 DOF per node for thermal
- Membrane and bending capabilities
- Uniform thickness element
- SHELL3 (linear) SHELL6 (parabolic)
- Supports adaptive "P" method

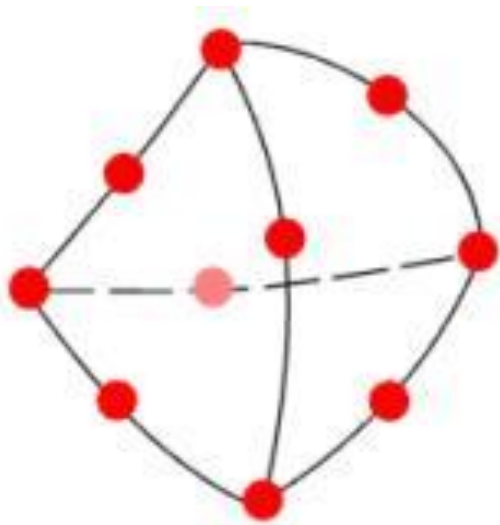


4-node tetrahedral mesh

The *unit reference tetrahedron* has corners at $\{0,0,0\}$, $\{1,0,0\}$, $\{0,1,0\}$, $\{0,0,1\}$

$$\mathbf{K}^e = \hat{E} \begin{bmatrix} 4-6\nu & 1 & 1 & -2\hat{\nu} & -\tilde{\nu} & -\tilde{\nu} & -\tilde{\nu} & -2\nu & 0 & -\tilde{\nu} & 0 & -2\nu \\ 1 & 4-6\nu & 1 & -2\nu & -\tilde{\nu} & 0 & -\tilde{\nu} & -2\hat{\nu} & -\tilde{\nu} & 0 & -\tilde{\nu} & -2\nu \\ 1 & 1 & 4-6\nu & -2\nu & 0 & -\tilde{\nu} & 0 & -2\nu & -\tilde{\nu} & -\tilde{\nu} & -\tilde{\nu} & -2\hat{\nu} \\ -2\hat{\nu} & -2\nu & -2\nu & 2\hat{\nu} & 0 & 0 & 0 & 2\nu & 0 & 0 & 0 & 2\nu \\ -\tilde{\nu} & -\tilde{\nu} & 0 & 0 & \tilde{\nu} & 0 & \tilde{\nu} & 0 & 0 & 0 & 0 & 0 \\ -\tilde{\nu} & 0 & -\tilde{\nu} & 0 & 0 & \tilde{\nu} & 0 & 0 & 0 & \tilde{\nu} & 0 & 0 \\ -\tilde{\nu} & -\tilde{\nu} & 0 & 0 & \tilde{\nu} & 0 & \tilde{\nu} & 0 & 0 & 0 & 0 & 0 \\ -2\nu & -2\hat{\nu} & -2\nu & 2\nu & 0 & 0 & 0 & 2\hat{\nu} & 0 & 0 & 0 & 2\nu \\ 0 & -\tilde{\nu} & -\tilde{\nu} & 0 & 0 & 0 & 0 & 0 & \tilde{\nu} & 0 & \tilde{\nu} & 0 \\ -\tilde{\nu} & 0 & -\tilde{\nu} & 0 & 0 & \tilde{\nu} & 0 & 0 & 0 & \tilde{\nu} & 0 & 0 \\ 0 & -\tilde{\nu} & -\tilde{\nu} & 0 & 0 & 0 & 0 & 0 & \tilde{\nu} & 0 & \tilde{\nu} & 0 \\ -2\nu & -2\nu & -2\hat{\nu} & 2\nu & 0 & 0 & 0 & 2\nu & 0 & 0 & 0 & 2\hat{\nu} \end{bmatrix}$$

$$\hat{E} = E/(12(1-2\nu)(1+\nu)), \quad \tilde{\nu} = 1 - 2\nu \text{ and } \hat{\nu} = 1 - \nu$$



10-node tetrahedral mesh

Ke=

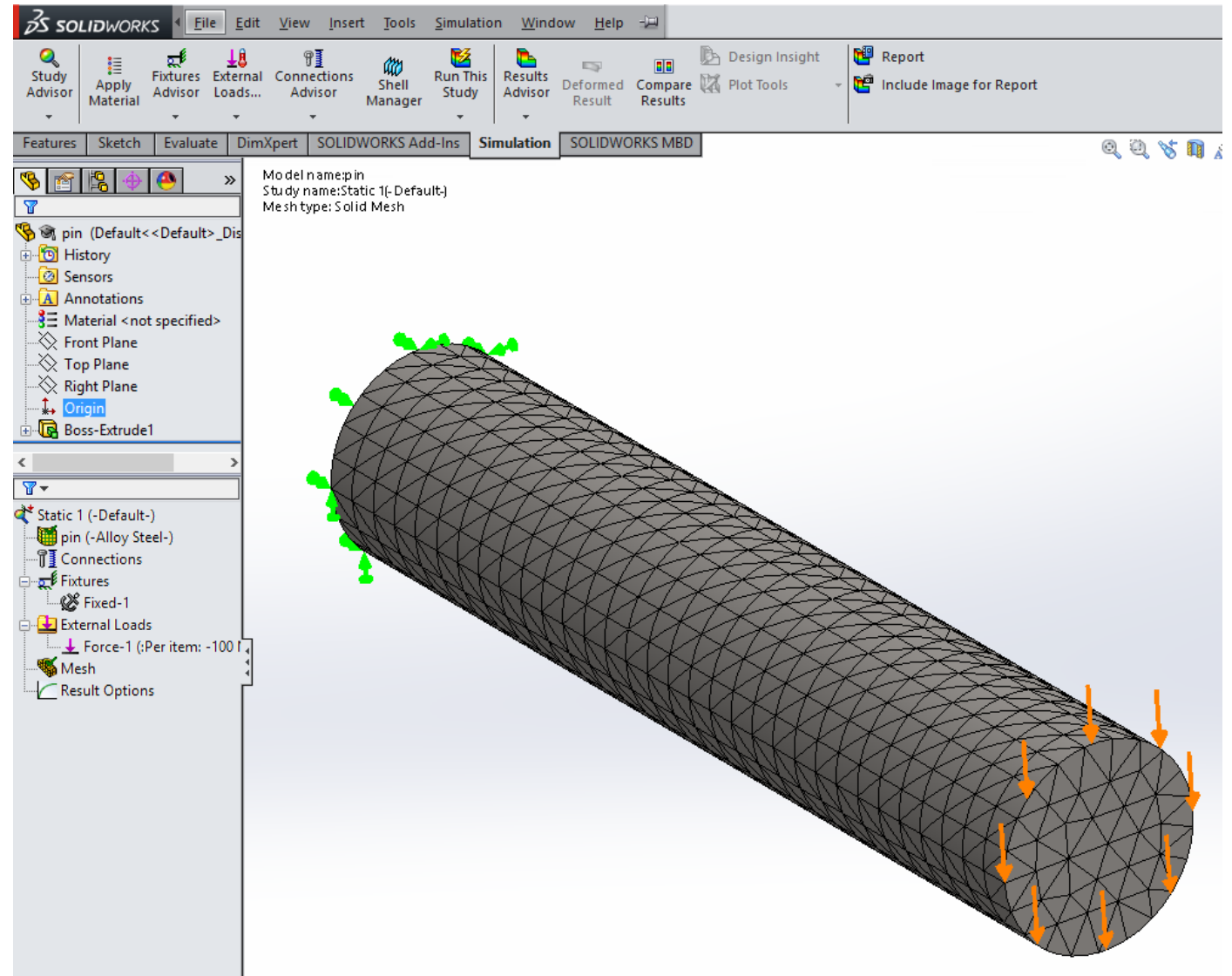
447	324	72	1	-6	-12	54	48	0	94	66	36	-152	-90	12
324	1032	162	24	-104	-42	24	216	12	60	232	84	-180	-32	72
72	162	339	0	-30	-35	0	24	54	24	60	94	-24	36	-8
1	24	0	87	-54	-36	18	-24	0	10	-18	-12	-32	-54	12
-6	-104	-30	-54	132	54	-12	72	12	0	76	36	36	268	72
-12	-42	-35	-36	54	87	0	24	18	0	36	46	48	108	76
54	24	0	18	-12	0	108	0	0	-36	-12	0	72	12	0
48	216	24	-24	72	24	0	432	0	-24	-144	-48	24	288	48
0	12	54	0	12	18	0	0	108	0	-24	-36	0	24	72
94	60	24	10	0	0	-36	-24	0	204	108	72	104	60	24
66	232	60	-18	76	36	-12	-144	-24	108	492	216	48	308	96
36	84	94	-12	36	46	0	-48	-36	72	216	312	24	120	140
-152	-180	-24	-32	36	48	72	24	0	104	48	24	1416	648	144
-90	-32	36	-54	268	108	12	288	24	60	308	120	648	3936	864
12	72	-8	12	72	76	0	48	72	24	96	140	144	864	1416
55	48	0	-83	54	12	-90	72	0	-26	-30	-12	-392	-312	-48
42	112	-6	90	-260	-90	36	-360	-36	-24	-68	-12	-336	-1424	-96
-12	-30	19	12	-54	-83	0	-72	-90	0	12	10	0	96	-248
-311	-180	-24	19	-18	-12	-198	-144	0	58	54	36	232	456	144
-252	-992	-126	0	-32	-18	-72	-792	-36	36	88	36	336	352	96
-24	-90	-275	0	-18	-17	0	-72	-198	24	36	58	96	192	232
-431	-288	-96	11	-6	-12	18	24	0	-350	-234	-132	136	216	48
-306	-1040	-234	6	-28	-6	12	72	-12	-216	-860	-324	216	256	-144
-132	-306	-395	-12	6	11	0	-24	18	-96	-252	-386	48	-288	-152
95	84	24	-59	18	12	-18	-48	0	-98	18	12	-680	-648	-240
60	128	30	72	-272	-126	-24	-72	-12	-36	-392	-180	-504	-1568	-432
24	42	59	48	-126	-167	0	-24	-18	-24	-180	-242	-240	-576	-680
148	84	24	28	-12	0	72	72	0	40	0	-24	-704	-288	-96
114	448	84	-42	148	60	36	288	72	36	268	72	-288	-2384	-576
36	96	148	-12	48	64	0	144	72	-24	0	4	-96	-576	-848
55	42	-12	-311	-252	-24	-431	-306	-132	95	60	24	148	114	36
48	112	-30	-180	-992	-90	-288	-1040	-306	84	128	42	84	448	96
0	-6	19	-24	-126	-275	-96	-234	-395	24	30	59	24	84	148
-83	90	12	19	0	0	11	6	-12	-59	72	48	28	-42	-12
54	-260	-54	-18	-32	-18	-6	-28	6	18	-272	-126	-12	148	48
12	-90	-83	-12	-18	-17	-12	-6	11	12	-126	-167	0	60	64
-90	36	0	-198	-72	0	18	12	0	-18	-24	0	72	36	0
72	-360	-72	-144	-792	-72	24	72	-24	-48	-72	-24	72	288	144
0	-36	-90	0	-36	-198	0	-12	18	0	-12	-18	0	72	72
-26	-24	0	58	36	24	-350	-216	-96	-98	-36	-24	40	36	-24
-30	-68	12	54	88	36	-234	-860	-252	18	-392	-180	0	268	0
-12	-12	10	36	36	58	-132	-324	-386	12	-180	-242	-24	72	4
-392	-336	0	232	336	96	136	216	48	-680	-504	-240	-704	-288	-96
-312	-1424	96	456	352	192	216	256	-288	-648	-1568	-576	-288	-2384	-576
-48	-96	-248	144	96	232	48	-144	-152	-240	-432	-680	-96	-576	-848
376	0	-96	-152	-192	0	-116	-72	48	292	144	0	136	288	96
0	928	0	-96	256	96	-72	-176	72	216	736	216	144	256	-144
-96	0	376	96	192	136	48	72	-116	-48	72	148	0	-288	-152
-152	-96	96	1048	576	192	292	168	-48	-308	-144	-96	-680	-672	-288
-192	256	192	576	2176	288	192	736	168	-144	-224	-72	-480	-1568	-528
0	96	136	192	288	760	0	120	148	-96	-72	-164	-192	-480	-680
-116	-72	48	292	192	0	984	648	144	-152	-72	48	-392	-408	-48
-72	-176	72	168	736	120	648	2208	432	-216	256	144	-240	-1424	-48
48	72	-116	-48	168	148	144	432	984	48	144	136	0	48	-248
292	216	-48	-308	-144	-96	-152	-216	48	696	216	144	232	504	144
144	736	72	-144	-224	-72	-72	256	144	216	1056	432	288	352	144
0	216	148	-96	-72	-164	48	144	136	144	432	696	96	144	232
136	144	0	-680	-480	-192	-392	-240	0	232	288	96	1120	432	192
288	256	-288	-672	-1568	-480	-408	-1424	48	504	352	144	432	3616	864
96	-144	-152	-288	-528	-680	-48	-248	144	144	232	192	864	1408	

eigs of Ke = {8809.45, 4936.01, 2880.56, 2491.66, 2004.85, 1632.49, 1264.32, 1212.42, 817.907, 745.755, 651.034, 517.441, 255.100, 210.955, 195.832, 104.008, 72.7562, 64.4376, 53.8515, 23.8417, 16.6354, 9.54682, 6.93361, 2.22099, 0, 0, 0, 0, 0, 0}

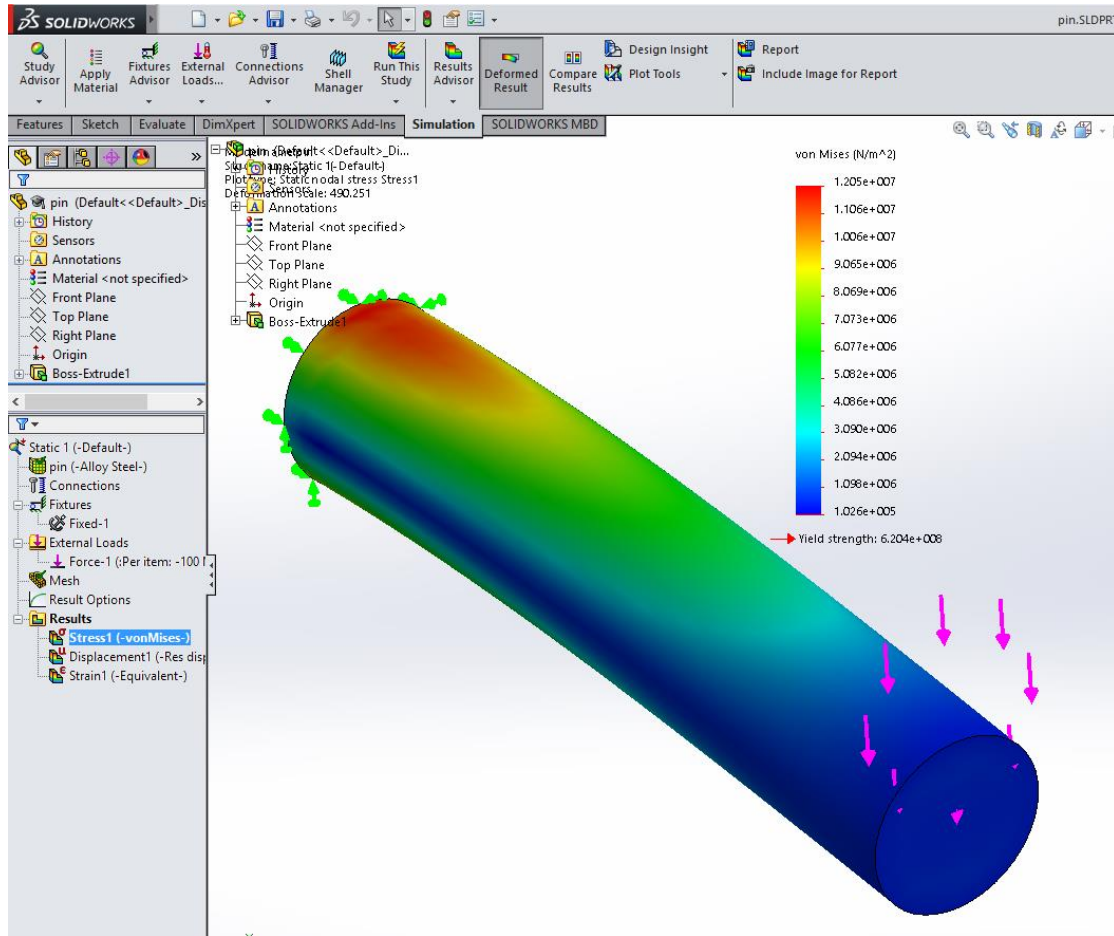
FEA procedure

- ❖ **1. Identify the problem, sketch the structure and loads.**
- ❖ **2. Create the geometry with the FE package solid modeler or a CAD system.**
- ❖ **3. Apply material properties.**
- ❖ **4. Mesh the model.**
- ❖ **5. Apply boundary conditions (constraints and loads) on the model.**
- ❖ **6. Solve numerical equations.**
- ❖ **7. Evaluate the results.**

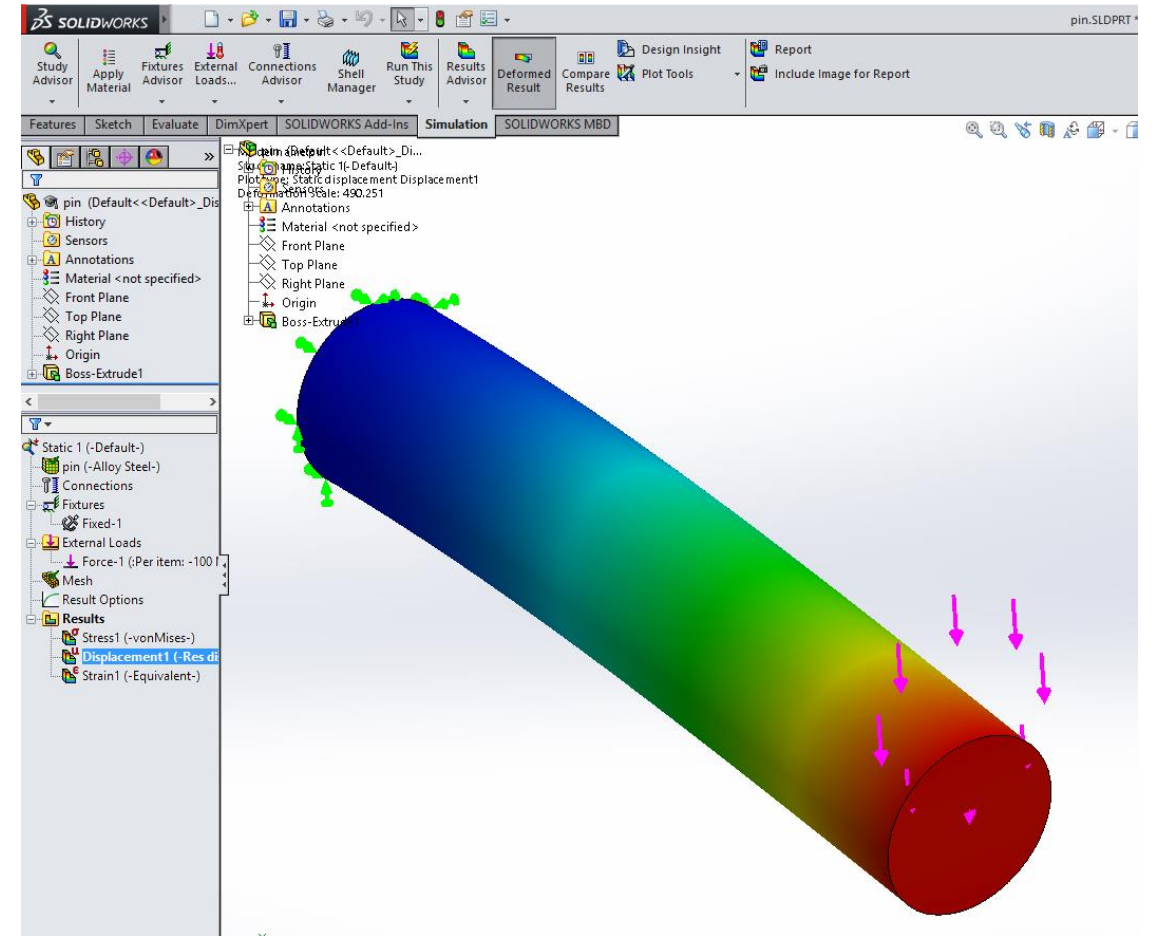
Solidworks Simulation example



Solidworks Simulation example



Stress distribution



Displacement plot

Theoretical background for modal analysis

❖ Equation of motion (assume zero damping)

$$[M]\{\ddot{u}\} + [K][u] = 0$$

❖ Solving the equation

$$\{u\} = \{\phi\} \sin \omega t$$

$$-\omega^2 [M]\{\phi\} \sin \omega t + [K]\{\phi\} \sin \omega t = 0$$

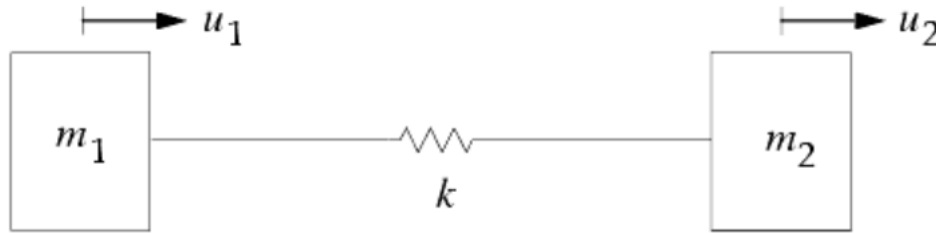
$$([K] - \omega^2 [M])\{\phi\} = 0 \iff [A - \lambda I]x = 0$$

Eigen value problem

$$\det ([K] - \lambda [M]) = 0$$

Simple analytic model

❖ Two mass block connected with a spring



$$[K] = \begin{pmatrix} k & -k \\ -k & k \end{pmatrix} \quad [M] = \begin{pmatrix} m_1 & 0 \\ 0 & m_2 \end{pmatrix}$$

$$[K] - \omega^2 [M] = \begin{pmatrix} k - \lambda m_1 & -k \\ -k & k - \lambda m_2 \end{pmatrix}$$

$$\det([K] - \lambda [M]) = \lambda^2 m_1 m_2 - \lambda k m_2 - \lambda k m_1 \quad \text{where} \quad \lambda = \omega^2$$

Eigen values

$$\left\{ 0, \frac{k m_1 + k m_2}{m_1 m_2} \right\} \quad \text{if } m_1 \neq 0 \wedge m_2 \neq 0$$

Resonant frequency

Eigen functions

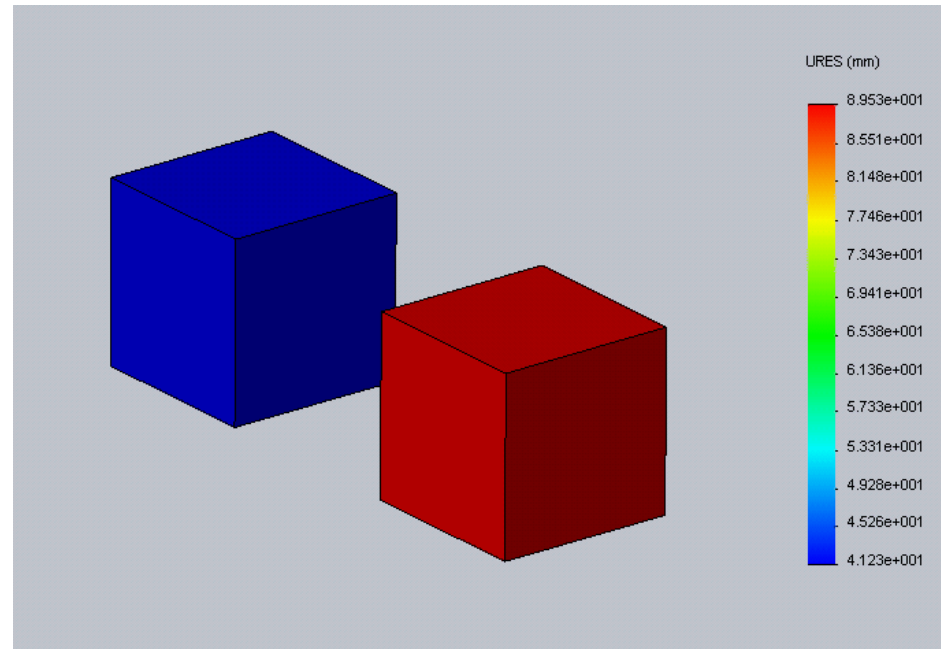
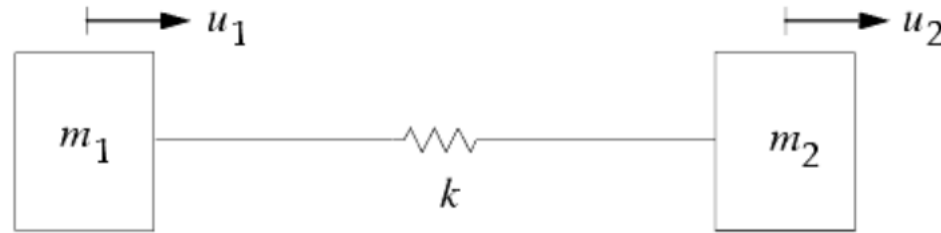
$$\left[\begin{pmatrix} 1 \\ 1 \end{pmatrix} \right] \quad \text{and} \quad \left[\begin{pmatrix} -\frac{m_2}{m_1} \\ 1 \end{pmatrix} \right]$$

Rigid body motion

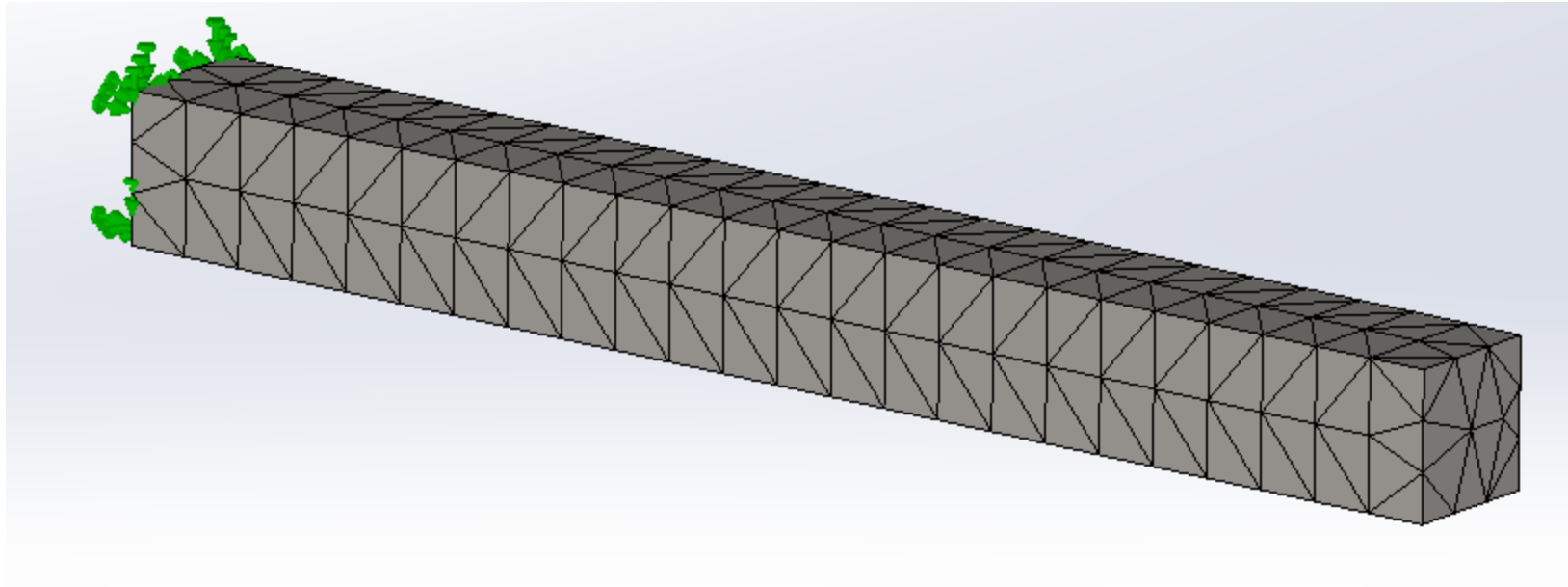
Mode shape

Simple analytic model

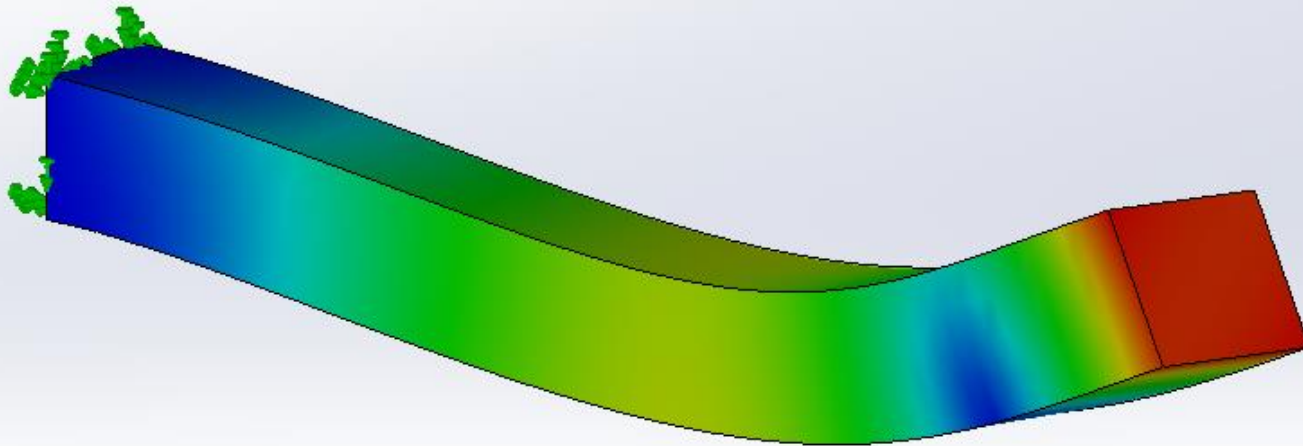
❖ Two mass block connected with a spring



Target model – Modal frequency analysis



Target model – Modal frequency analysis



4th order mode shape for example

List Modes

Study name: Frequency 1

Mode No.	Frequency(Rad/sec)	Frequency(Hertz)	Period(Seconds)
1	2080.9	331.19	0.0030194
2	2081	331.2	0.0030194
3	12469	1984.5	0.00050391
4	12472	1985	0.00050378
5	17866	2843.5	0.00035168

Close Save Help



Modeling Tips

- **Tip #1 Understand the physics of the problem and always start with a sketch. Before you model have a plan and know:**
 - What you are going to model and what results do you need?
 - How you are going to develop your model?
 - How you are going to support the model and apply loads?
- **Tip #2 Start simple and increase complexity as required.**
 - When modeling systems – start with a single optical element.
- **Tip #3 Build simple test models for understanding.**
 - Check for load and boundary condition accuracy
 - Above depends on the type of analysis you are running
 - Check for mesh accuracy – do convergence studies
- **Tip #4 Always request reaction forces in the output.**
 - For models with both structural and gravity loads, turn off gravity and check your reaction forces. Do they match the applied load?
 - Turn on gravity. Is the increase in reaction force consistent with the gravity load? Is the direction correct?

Modeling Tips

- **Tip #5 Understand your constraints and use care not to over constrain the model.**
 - Are all six (6) rigid body translations and rotations accounted for?
 - A model with too few constraints causes a singular stiffness matrix.
 - An over constrained model creates alternate load paths.
 - When in doubt, release constraints and add soft springs.
- **Tip #6 Study the deformed shape. Does it look correct?**
 - Properly modeled, symmetric loads and constraints will produce symmetric results.
 - Always generate a symmetric mesh for optical surfaces. Automatic mesh generators rarely produce a symmetric mesh.
- **Tip #7 As a starting point, there must be enough elements to accurately predict the deformed shape.**
 - Use a minimum of 4 elements through the height or thickness or sections subjected to bending.
 - Do simple convergence studies to determine an acceptable mesh density.
- **Tip #8 An accurate stress analysis requires more elements than an accurate displacement analysis.**
 - Increase the mesh density for accurate stress analysis.
 - Check nodal stress in surrounding elements sharing a common node.



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Modeling Tips

- **Tip #9 Check, check and recheck your model and results.**
 - Do hand calculations and back of the envelope calculations to verify results.
 - Assume the results are wrong until proven correct.
- **Tip #10 When in trouble – get help.**
 - Consult a senior analyst for help and tips