

Problem 10)

$$a) \vec{M}(\vec{r}, t) = \frac{M_0 R_1}{r} [\text{Circ}(r/R_2) - \text{Circ}(r/R_1)] \text{Rect}(z/h) \hat{r}$$

$$b) \vec{J}_b^{(e)}(\vec{r}, t) = \frac{1}{\mu_0} \vec{\nabla}_x \vec{M}(\vec{r}, t) = \frac{1}{\mu_0} \frac{\partial M_r}{\partial z} \hat{\phi} = \frac{M_0 R_1}{\mu_0 r} [\text{Circ}(r/R_2) - \text{Circ}(r/R_1)] [\delta(z + \frac{h}{2}) - \delta(z - \frac{h}{2})] \hat{\phi}$$

$$\rho_b^{(m)}(\vec{r}, t) = -\vec{\nabla} \cdot \vec{M}(\vec{r}, t) = -\frac{1}{r} \frac{\partial}{\partial r} (r M_r) = \frac{M_0 R_1}{r} [\delta(r - R_2) - \delta(r - R_1)] \text{Rect}(z/h) \Rightarrow$$

$$\rho_b^{(m)}(\vec{r}, t) = M_0 \left[\frac{R_1}{R_2} \delta(r - R_2) - \delta(r - R_1) \right] \text{Rect}(z/h)$$

c) On the inner and outer cylindrical surfaces the velocity is $R_1 \omega_0$ and $R_2 \omega_0$, respectively. Since $\vec{J}_b^{(m)}(\vec{r}, t) = \rho_b^{(m)}(\vec{r}, t) \vec{v}(\vec{r}, t)$, if we write $\vec{v}(\vec{r}, t) = r \omega_0 \hat{\phi}$, the delta functions present in the expression of $\rho_b^{(m)}$ will ensure that the inner cylinder charges are multiplied with $R_1 \omega_0$, while the outer cylinder charges are multiplied with $R_2 \omega_0$. We will have:

$$\vec{J}_b^{(m)}(\vec{r}, t) = \rho_b^{(m)}(\vec{r}, t) r \omega_0 \hat{\phi} = M_0 \omega_0 [R_1 \delta(r - R_2) - R_1 \delta(r - R_1)] \text{Rect}(z/h) \hat{\phi} \Rightarrow$$

$$\vec{J}_b^{(m)}(\vec{r}, t) = M_0 R_1 \omega_0 [\delta(r - R_2) - \delta(r - R_1)] \text{Rect}(z/h) \hat{\phi}$$

d) Maxwell's 3rd equation: $\vec{\nabla}_x \vec{E}(\vec{r}, t) = -\frac{\partial}{\partial t} \vec{B}(\vec{r}, t) \Rightarrow \vec{\nabla}_x \epsilon_0 \vec{E}(\vec{r}, t) = -\epsilon_0 \frac{\partial \vec{M}}{\partial t} - \mu_0 \epsilon_0 \frac{\partial \vec{H}}{\partial t}$

$$\Rightarrow \vec{\nabla}_x \vec{D}(\vec{r}, t) = -\epsilon_0 \left(\frac{\partial \vec{M}}{\partial t} - \frac{1}{\epsilon_0} \vec{\nabla}_x \vec{P} \right) - \mu_0 \epsilon_0 \frac{\partial \vec{H}(\vec{r}, t)}{\partial t}$$

Comparison with Maxwell's 2nd equation, $\vec{\nabla}_x \vec{B} = \mu_0 \left(\vec{J}_{\text{free}} + \frac{\partial \vec{P}}{\partial t} + \frac{1}{\mu_0} \vec{\nabla}_x \vec{M} \right) + \mu_0 \epsilon_0 \frac{\partial \vec{E}(\vec{r}, t)}{\partial t}$, shows that the bound magnetic current may be defined as $\vec{J}_b^{(m)}(\vec{r}, t) = \frac{\partial \vec{M}}{\partial t} - \frac{1}{\epsilon_0} \vec{\nabla}_x \vec{P}$.

In the present problem $\partial \vec{M} / \partial t = 0$, but $\vec{J}_b^{(m)}$ is associated with $\vec{\nabla}_x \vec{P}$, as follows:

$$\begin{aligned} -\frac{1}{\epsilon_0} \vec{\nabla}_x \vec{P}(\vec{r}, t) &= -\frac{1}{\epsilon_0} \vec{\nabla}_x \left\{ P_0 [\text{Circ}(r/R_2) - \text{Circ}(r/R_1)] \text{Rect}(z/h) \hat{z} \right\} = \frac{P_0}{\epsilon_0} \frac{\partial}{\partial r} [\text{Circ}(r/R_2) - \text{Circ}(r/R_1)] \text{Rect}(z/h) \hat{\phi} \\ &= (P_0 / \epsilon_0) [-\delta(r - R_2) + \delta(r - R_1)] \text{Rect}(z/h) \hat{\phi} \end{aligned}$$

Comparison with $\vec{J}_b^{(m)}(\vec{r}, t)$ in part (c) reveals that $P_0 = -\epsilon_0 M_0 R_1 \omega_0$.