Problem 1) a) In free space, $\boldsymbol{D}=\varepsilon_{0} \boldsymbol{E}+\boldsymbol{P}=\varepsilon_{0} \boldsymbol{E}$, and $\boldsymbol{B}=\mu_{0} \boldsymbol{H}+\boldsymbol{M}=\mu_{0} \boldsymbol{H}$. Therefore,

$$
\boldsymbol{\nabla} \cdot \boldsymbol{D}=\varepsilon_{0} \boldsymbol{\nabla} \cdot \boldsymbol{E}=\varepsilon_{0}\left(\partial_{x} E_{x}+\partial_{y} E_{y}+\partial_{z} E_{z}\right)=0
$$

$$
\begin{align*}
\boldsymbol{\nabla} \times \boldsymbol{H} & =\left(\partial_{y} H_{z}-\partial_{z} H_{y}\right) \hat{\boldsymbol{x}}+\left(\partial_{z} H_{x}-\partial_{x} H_{z}\right) \hat{\boldsymbol{y}}+\left(\partial_{x} H_{y}-\partial_{y} H_{x}\right) \hat{\boldsymbol{z}} \\
& =\left(E_{0} / Z_{0}\right)(\omega / c) \sin [(\omega / c) x-\omega t] \widehat{\boldsymbol{y}}-\left(E_{0} / Z_{0}\right)(\omega / c) \cos [(\omega / c) x-\omega t] \hat{\boldsymbol{z}} \\
& =\varepsilon_{0} E_{0} \omega \sin [(\omega / c) x-\omega t] \hat{\boldsymbol{y}}-\varepsilon_{0} E_{0} \omega \cos [(\omega / c) x-\omega t] \hat{\boldsymbol{z}} \\
\partial_{t} \boldsymbol{D}= & \varepsilon_{0} \partial_{t} \boldsymbol{E}=\varepsilon_{0} E_{0} \omega \sin [(\omega / c) x-\omega t] \hat{\boldsymbol{y}}-\varepsilon_{0} E_{0} \omega \cos [(\omega / c) x-\omega t] \hat{\mathbf{z}} .
\end{align*}
$$

Clearly, $\boldsymbol{\nabla} \times \boldsymbol{H}=\boldsymbol{J}_{\text {free }}+\partial_{t} \boldsymbol{D}$ is satisfied.
iii) $\boldsymbol{\nabla} \times \boldsymbol{E}=\left(\partial_{y} E_{z}-\partial_{z} E_{y}\right) \hat{\boldsymbol{x}}+\left(\partial_{z} E_{x}-\partial_{x} E_{z}\right) \hat{\boldsymbol{y}}+\left(\partial_{x} E_{y}-\partial_{y} E_{x}\right) \hat{\boldsymbol{z}}$

$$
=-(\omega / c) E_{0} \cos [(\omega / c) x-\omega t] \hat{\boldsymbol{y}}-(\omega / c) E_{0} \sin [(\omega / c) x-\omega t] \hat{\mathbf{z}}
$$

$$
\partial_{t} \boldsymbol{B}=\mu_{0} \partial_{t} \boldsymbol{H}=\mu_{0}\left(E_{0} / Z_{0}\right) \omega \sin [(\omega / c) x-\omega t] \hat{\mathbf{z}}+\mu_{0}\left(E_{0} / Z_{0}\right) \omega \cos [(\omega / c) x-\omega t] \widehat{\boldsymbol{y}}
$$

$$
=(\omega / c) E_{0} \sin [(\omega / c) x-\omega t] \hat{\boldsymbol{z}}+(\omega / c) E_{0} \cos [(\omega / c) x-\omega t] \hat{\boldsymbol{y}} .
$$

It is seen that Maxwell's $3^{\text {rd }}$ equation, $\boldsymbol{\nabla} \times \boldsymbol{E}=-\partial_{t} \boldsymbol{B}$ is satisfied.
iv) $\boldsymbol{\nabla} \cdot \boldsymbol{B}=\mu_{0}\left(\partial_{x} H_{x}+\partial_{y} H_{y}+\partial_{z} H_{z}\right)=0$.
b) $\mathbb{E}(\boldsymbol{r}, t)=1 / 2 \varepsilon_{0} \boldsymbol{E} \cdot \boldsymbol{E}=1 / 2 \varepsilon_{0} E_{0}^{2}\left\{\cos ^{2}[(\omega / c) x-\omega t]+\sin ^{2}[(\omega / c) x-\omega t]\right\}=1 / 2 \varepsilon_{0} E_{0}^{2}$.

$$
\begin{aligned}
& \mathbb{H}(\boldsymbol{r}, t)=1 / 2 \mu_{0} \boldsymbol{H} \cdot \boldsymbol{H}=1 / 2 \mu_{0}\left(E_{0} / Z_{0}\right)^{2}\left\{\cos ^{2}[(\omega / c) x-\omega t]+\sin ^{2}[(\omega / c) x-\omega t]\right\}=1 / 2 \varepsilon_{0} E_{0}^{2} . \\
& \begin{aligned}
\boldsymbol{S}(\boldsymbol{r}, t)=\boldsymbol{E} \times \boldsymbol{H} & =\left(E_{y} H_{z}-E_{z} H_{y}\right) \widehat{\boldsymbol{x}} \\
& =\left(E_{0}^{2} / Z_{0}\right)\left\{\cos ^{2}[(\omega / c) x-\omega t]+\sin ^{2}[(\omega / c) x-\omega t]\right\} \widehat{\boldsymbol{x}}=\left(E_{0}^{2} / Z_{0}\right) \widehat{\boldsymbol{x}} .
\end{aligned}
\end{aligned}
$$

c)

$$
\boldsymbol{\nabla} \cdot \boldsymbol{S}+\partial_{t}(\mathbb{E}+\mathbb{H})=\partial_{x}\left(E_{0}^{2} / Z_{0}\right)+\partial_{t}\left(\varepsilon_{0} E_{0}^{2}\right)=0
$$

Problem 2) The surface-charge-density is $\sigma_{s 0}$, and the surface-current-density, which is the product of the surface charge-density and the local velocity at the cylinder surface, is $\boldsymbol{J}_{s 0}=$ $R \omega \sigma_{s 0} \widehat{\boldsymbol{\varphi}}$. In this problem $\boldsymbol{P}(\boldsymbol{r}, t)=0$ and $\boldsymbol{M}(\boldsymbol{r}, t)=0$. The discontinuity in the perpendicular component of $\boldsymbol{D}$ must, therefore, be equal to $\sigma_{s 0}$ (because $\boldsymbol{\nabla} \cdot \boldsymbol{D}=\rho_{\text {free }}$ ), that is,

$$
D_{\perp}\left(\rho=R^{+}, \varphi, z, t\right)-D_{\perp}\left(\rho=R^{-}, \varphi, z, t\right)=\sigma_{s 0}
$$

or, equivalently,

$$
\varepsilon_{0} E_{\rho}\left(R^{+}, \varphi, z, t\right)-\varepsilon_{0} E_{\rho}\left(R^{-}, \varphi, z, t\right)=\sigma_{s 0}
$$

The perpendicular component of $\boldsymbol{B}$ must be continuous (because $\boldsymbol{\nabla} \cdot \boldsymbol{B}=0$ ). Consequently,

$$
\mu_{0} H_{\rho}\left(R^{+}, \varphi, z, t\right)=\mu_{0} H_{\rho}\left(R^{-}, \varphi, z, t\right) .
$$

Both tangential components of $\boldsymbol{E}$ must be continuous (because $\boldsymbol{\nabla} \times \boldsymbol{E}=-\partial_{t} \boldsymbol{B}$ ). Therefore,

$$
\begin{aligned}
& E_{\varphi}\left(R^{+}, \varphi, z, t\right)=E_{\varphi}\left(R^{-}, \varphi, z, t\right) . \\
& E_{z}\left(R^{+}, \varphi, z, t\right)=E_{z}\left(R^{-}, \varphi, z, t\right)
\end{aligned}
$$

The tangential component of $\boldsymbol{H}$ that is parallel to the surface current is also continuous (because $\boldsymbol{\nabla} \times \boldsymbol{H}=\boldsymbol{J}_{\text {free }}+\partial_{t} \boldsymbol{D}$ ), that is,

$$
H_{\varphi}\left(R^{+}, \varphi, z, t\right)=H_{\varphi}\left(R^{-}, \varphi, z, t\right)
$$

However, the tangential component of $\boldsymbol{H}$ that is orthogonal to the surface current has a discontinuity equal to the surface current density, that is,

$$
H_{z}\left(R^{+}, \varphi, z, t\right)-H_{z}\left(R^{-}, \varphi, z, t\right)=-J_{s, \varphi}(\rho=R, \varphi, z, t)=-R \omega \sigma_{s 0} .
$$

In the preceding equation, the rotation of the hollow cylinder, seen from above, is assumed to be counterclockwise. The right-hand rule then dictates the sign of the discontinuity of $H_{z}$.

Problem 3) The surface-charge-density is $\sigma_{s 0}$, and the surface-current-density, which is the product of the surface charge-density and the local velocity at the sphere's surface, is $\boldsymbol{J}_{s 0}=$ $(R \sin \theta) \omega \sigma_{s 0} \widehat{\boldsymbol{\varphi}}$. In this problem $\boldsymbol{P}(\boldsymbol{r}, t)=0$ and $\boldsymbol{M}(\boldsymbol{r}, t)=0$. The discontinuity in the perpendicular component of $\boldsymbol{D}$ must, therefore, be equal to $\sigma_{s 0}$ (because $\boldsymbol{\nabla} \cdot \boldsymbol{D}=\rho_{\text {free }}$ ), that is,

$$
D_{\perp}\left(r=R^{+}, \theta, \varphi, t\right)-D_{\perp}\left(r=R^{-}, \theta, \varphi, t\right)=\sigma_{s 0}
$$

or, equivalently,

$$
\varepsilon_{0} E_{r}\left(R^{+}, \theta, \varphi, t\right)-\varepsilon_{0} E_{r}\left(R^{-}, \theta, \varphi, t\right)=\sigma_{s 0} .
$$

The perpendicular component of $\boldsymbol{B}$ must be continuous (because $\boldsymbol{\nabla} \cdot \boldsymbol{B}=0$ ). Consequently,

$$
\mu_{0} H_{r}\left(R^{+}, \theta, \varphi, t\right)=\mu_{0} H_{r}\left(R^{-}, \theta, \varphi, t\right) .
$$

Both tangential components of $\boldsymbol{E}$ must be continuous (because $\boldsymbol{\nabla} \times \boldsymbol{E}=-\partial_{t} \boldsymbol{B}$ ). Therefore,

$$
\begin{aligned}
& E_{\theta}\left(R^{+}, \theta, \varphi, t\right)=E_{\theta}\left(R^{-}, \theta, \varphi, t\right) \\
& E_{\varphi}\left(R^{+}, \theta, \varphi, t\right)=E_{\varphi}\left(R^{-}, \theta, \varphi, t\right)
\end{aligned}
$$

The tangential component of $\boldsymbol{H}$ that is parallel to the surface current is also continuous (because $\boldsymbol{\nabla} \times \boldsymbol{H}=\boldsymbol{J}_{\text {free }}+\partial_{t} \boldsymbol{D}$ ), that is,

$$
H_{\varphi}\left(R^{+}, \theta, \varphi, t\right)=H_{\varphi}\left(R^{-}, \theta, \varphi, t\right)
$$

However, the tangential component of $\boldsymbol{H}$ that is orthogonal to the surface current has a discontinuity equal to the surface current density, that is,

$$
H_{\theta}\left(R^{+}, \theta, \varphi, t\right)-H_{\theta}\left(R^{-}, \theta, \varphi, t\right)=J_{s, \varphi}(\rho=R, \theta, \varphi, t)=(R \sin \theta) \omega \sigma_{s 0}
$$

In the preceding equation, the rotation of the spherical shell, seen from above, is assumed to be counterclockwise. The right-hand rule then dictates the sign of the discontinuity of $H_{\theta}$.

Problem 4) a) Consider a closed surface inside the metallic host that encloses the cavity. Since the $E$-field everywhere on this closed surface must vanish, the integral of the $E$-field over the closed surface will be zero. According to Maxwell's $1^{\text {st }}$ equation, the total charge inside the closed surface must vanish, that is, the overall charge induced on the walls of the cavity must be equal in magnitude and opposite in sign to the charge $q$ that has been placed inside the cavity.
b) The above argument indicates that, when the charge $q$ is removed from the cavity, the overall induced charge on the walls of the cavity must go to zero. However, the argument based on Maxwell's $1^{\text {st }}$ equation does not say anything at all about the distribution of charge-density over the walls. In other words, it is still possible to have equal amounts of positive and negative charge at different locations on the wall.

Now, the $3^{\text {rd }}$ of Maxwell's equations, $\boldsymbol{\nabla} \times \boldsymbol{E}=0$, must also be satisfied in this electrostatic problem. Since the $E$-field lines originate on positive charges and terminate on negative charges, if we define a closed loop that starts on a positive charge at some point on the cavity wall, follows an $E$-field line until it reaches a negative charge elsewhere on the cavity wall, then closes the path by going through the metallic host (where the $E$-field is zero), then the integral of the $E$ field around such a loop will not vanish. Given that the satisfaction of Maxwell's $3^{\text {rd }}$ equation is mandatory, we conclude that separated positive and negative charges cannot exist anywhere on the cavity walls, once the charge $q$ is taken out of the cavity.

