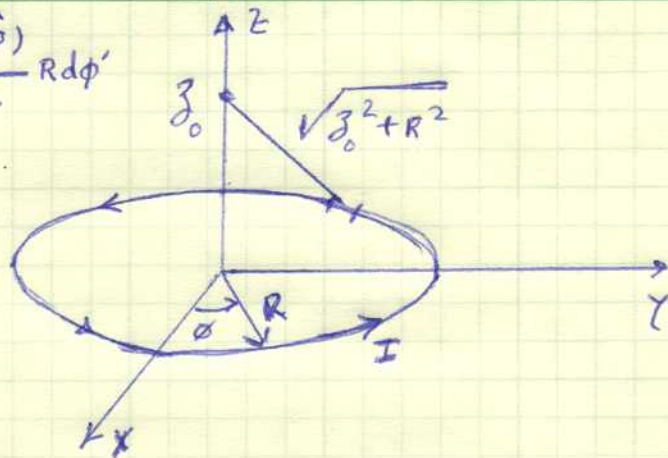


$$\vec{H}(0,0,z_0) = \frac{1}{4\pi} \int_{\phi'=0}^{2\pi} \frac{I \hat{\phi} \times (z_0 \hat{z} - R \hat{\rho})}{(z_0^2 + R^2)^{3/2}} R d\phi'$$

$$= \frac{RI}{4\pi(z_0^2 + R^2)^{3/2}} \int_{\phi'=0}^{2\pi} (z_0 \hat{\rho} + R \hat{z}) d\phi'$$

$$= \frac{R^2 I}{2(z_0^2 + R^2)^{3/2}} \hat{z}$$



In this derivation we have used cylindrical coordinates to express $\vec{J}(\vec{r}')$, \vec{r} , and \vec{r}' as follows:

$$\vec{J}(\vec{r}') dv' = \vec{J}(\vec{r}') ds' d\ell' = (I \hat{\phi}) d\ell' = (I \hat{\phi})(R d\phi') = RI \hat{\phi} d\phi'$$

$$\vec{r} = z_0 \hat{z}$$

$$\vec{r}' = R \hat{\rho}$$

$$|\vec{r} - \vec{r}'| = |z_0 \hat{z} - R \hat{\rho}| = \sqrt{z_0^2 + R^2}$$

We have also used the fact that $\hat{\phi} \times \hat{z} = \hat{\rho}$, $\hat{\phi} \times \hat{\rho} = -\hat{z}$,

$$\text{and } \int_{\phi'=0}^{2\pi} \hat{\rho} d\phi' = 0.$$