

Solutions

Opti 501

Problem 12)

$$\psi(\vec{r}) = \frac{q}{4\pi\epsilon_0} \left(\frac{1}{\sqrt{x^2+y^2+(z-\frac{1}{2}d)^2}} - \frac{1}{\sqrt{x^2+y^2+(z+\frac{1}{2}d)^2}} \right)$$

Now, $x^2+y^2+(z\pm\frac{1}{2}d)^2 = x^2+y^2+z^2 + \frac{1}{4}d^2 \pm zd = r^2 + \frac{d^2}{4} \pm zd$.

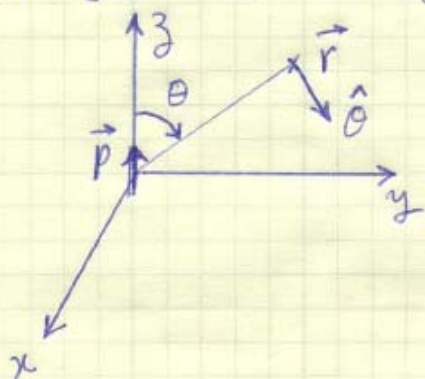
Since $r \gg d$, we drop the term $d^2/4$ from the above expression.

We'll have:

$$\begin{aligned} \psi(\vec{r}) &\approx \frac{q}{4\pi\epsilon_0} \left[(r^2 - zd)^{-1/2} - (r^2 + zd)^{-1/2} \right] \\ &= \frac{q}{4\pi\epsilon_0 r} \left[\left(1 - \frac{zd}{r^2}\right)^{-1/2} - \left(1 + \frac{zd}{r^2}\right)^{-1/2} \right] \end{aligned}$$

We now use the approximation $(1 \pm \epsilon)^{-1/2} \approx 1 \mp \frac{1}{2}\epsilon$ (See HW#1, Problem 10). Thus $\psi(\vec{r}) \approx \frac{q}{4\pi\epsilon_0 r} \left[\left(1 + \frac{zd}{r^2}\right) - \left(1 - \frac{zd}{r^2}\right) \right] = \frac{qdz}{4\pi\epsilon_0 r^3}$

Noting the definition of dipole moment, $\vec{p} = (qd)\hat{z}$, and the



fact that $z = \vec{r} \cdot \hat{z} = r \cos\theta$,

We can write $\psi(\vec{r}) = \frac{\vec{p} \cdot \vec{r}}{4\pi\epsilon_0 r^3}$

In spherical coordinates, the unit vector \hat{r} is written as \vec{r}/r . We may then write: $\psi(\vec{r}) = \frac{\vec{p} \cdot \hat{r}}{4\pi\epsilon_0 r^2}$

Note that the potential function of a point charge is proportional to $1/r$, but the potential function for a dipole drops as $1/r^2$.

The \vec{E} -field is given by $\vec{E} = -\vec{\nabla}\psi$. In spherical coordinates:

$$\begin{aligned}
 \vec{E}(\vec{r}) &= -\frac{\partial \psi}{\partial r} \hat{r} - \frac{1}{r} \frac{\partial \psi}{\partial \theta} \hat{\theta} - \frac{1}{r \sin \theta} \frac{\partial \psi}{\partial \phi} \hat{\phi} \\
 &= -\frac{\partial}{\partial r} \left(\frac{p \cos \theta}{4\pi \epsilon_0 r^2} \right) \hat{r} - \frac{1}{r} \frac{\partial}{\partial \theta} \left(\frac{p \cos \theta}{4\pi \epsilon_0 r^2} \right) \hat{\theta} \\
 &= \frac{p \cos \theta}{2\pi \epsilon_0 r^3} \hat{r} + \frac{p \sin \theta}{4\pi \epsilon_0 r^3} \hat{\theta} = \frac{1}{4\pi \epsilon_0 r^3} (2p \cos \theta \hat{r} + p \sin \theta \hat{\theta}) \\
 &= \frac{1}{4\pi \epsilon_0 r^3} [3p \cos \theta \hat{r} - \underbrace{(p \cos \theta \hat{r} - p \sin \theta \hat{\theta})}_{=\vec{p}}] \\
 &= \frac{3(\vec{p} \cdot \hat{r}) \hat{r} - \vec{p}}{4\pi \epsilon_0 r^3}
 \end{aligned}$$