Solutions

Problem 4.44) a) Because of symmetry, the *H*-field cannot depend on *x* or *z*. Take a rectangular loop $\ell_x \times \ell_y$ parallel to the *xy*-plane and write the integral form of Ampere's law, $\nabla \times H = J_{\text{free}}$, for this loop. The contributions of ℓ_y to the loop integral cancel out, leaving only the contributions of ℓ_x on opposite sides of the current sheet. Therefore, $2H_x\ell_x=J_{so}\ell_x$, where $J_{so}\ell_x$ is the current crossing the loop. The magnitude of the *H*-field is thus independent of *y*, although its direction depends on whether *y* is positive or negative. Taking the right-hand rule into account, the final result is

$$\boldsymbol{H}(\boldsymbol{r},t) = -\frac{1}{2}\operatorname{sign}(\boldsymbol{y})J_{so}\hat{\boldsymbol{x}}$$



Note: Using symmetry and Maxwell's 4th equation, $\nabla \cdot \boldsymbol{B} = 0$, it is easy to see why H_y must be zero everywhere: Take a cylinder whose axis is parallel to y and which the xz-plane cuts in the middle, then use the fact that the net flux of \boldsymbol{H} into or out of the cylinder must be zero. Similarly, Maxwell's 2nd equation can be used to show that H_z is independent of y; the argument parallels that used above to evaluate H_x , except that the rectangular loop is now chosen in the yz-plane. Since H_z is already known to be independent of x and z, we conclude that it must be constant through the entire space. Showing that H_z is identically zero, however, requires the full solution of Maxwell's equations, which is done in part (b).

b) Fourier transforming the current density $J(\mathbf{r},t) = J_{so}\delta(y)\hat{z}$ yields

$$\boldsymbol{J}(\boldsymbol{k},\omega) = \int_{-\infty}^{\infty} J_{so}\delta(y)\,\hat{\boldsymbol{z}}\exp[-\mathrm{i}(\boldsymbol{k}\cdot\boldsymbol{r}-\omega t)]\,\mathrm{d}\boldsymbol{r}\,\mathrm{d}\boldsymbol{t} = (2\pi)^3 J_{so}\delta(k_x)\,\delta(k_z)\,\delta(\omega)\hat{\boldsymbol{z}}\,.$$

The *H*-field is thus given by

$$H(\mathbf{r},t) = \mu_0^{-1} \mathbf{B}(\mathbf{r},t) = \mu_0^{-1} \nabla \times \mathbf{A}(\mathbf{r},t) = (2\pi)^{-4} \int_{-\infty}^{\infty} \frac{i\mathbf{k} \times \mathbf{J}(\mathbf{k},\omega)}{k^2 - (\omega/c)^2} \exp[i(\mathbf{k} \cdot \mathbf{r} - \omega t)] d\mathbf{k} d\omega$$
$$= \frac{iJ_{so}}{2\pi} \int_{-\infty}^{\infty} \frac{(\mathbf{k} \times \hat{\mathbf{z}}) \,\delta(k_x) \delta(k_z) \delta(\omega)}{k^2 - (\omega/c)^2} \exp[i(\mathbf{k} \cdot \mathbf{r} - \omega t)] d\mathbf{k} d\omega$$
$$= \frac{iJ_{so}}{2\pi} \int_{-\infty}^{\infty} \frac{k_y \hat{\mathbf{y}} \times \hat{\mathbf{z}}}{k_y^2} \exp(ik_y y) dk_y = iJ_{so} \hat{\mathbf{x}} (2\pi)^{-1} \int_{-\infty}^{\infty} \frac{\exp(ik_y y)}{k_y} dk_y = -\frac{1}{2} \operatorname{sign}(y) J_{so} \hat{\mathbf{x}}.$$