

Problem 32)

a) In the free-space region between the two cylinders the \vec{E} -field must have zero divergence (i.e., $\nabla \cdot \vec{E} = 0$).

Thus we expect $\vec{E}(r, \theta, t) = \frac{E_0}{r} \sin\left[\frac{2\pi}{\lambda}(z - vt)\right] \hat{r}$.

$$\text{Since } V(z, t) = \int_a^b E_r(r, z, t) dr = E_0 \ln(b/a) \sin\left[\frac{2\pi}{\lambda}(z - vt)\right],$$

We conclude that $E_0 = V_0 / \ln(b/a)$.

The \vec{B} -field in the region between the cylinders must have zero divergence ($\nabla \cdot \vec{B} = 0$) and, moreover, it must satisfy

$\vec{\nabla} \times \vec{H} = \vec{J}$ (ignoring dynamic effects for the time-being.) We

conclude that $\vec{H}(r, \theta, t) = \frac{H_0}{r} \sin\left[\frac{2\pi}{\lambda}(z - vt)\right] \hat{\phi}$. Since

$$\oint \vec{H} \cdot d\vec{e} = I, \text{ we'll have: } 2\pi r \left(\frac{H_0}{r}\right) \sin\left[\frac{2\pi}{\lambda}(z - vt)\right] = I_0 \sin\left[\frac{2\pi}{\lambda}(z - vt)\right].$$

Therefore, $H_0 = \frac{I_0}{2\pi}$. All in all,

$$\vec{E}(r, \theta, t) = \frac{V_0}{\ln(b/a)} \sin\left[\frac{2\pi}{\lambda}(z - vt)\right] \hat{r}$$

$$\vec{H}(r, \theta, t) = \frac{I_0}{2\pi r} \sin\left[\frac{2\pi}{\lambda}(z - vt)\right] \hat{\phi}$$

$$b) \vec{D} \cdot \vec{E} = \frac{1}{\rho} \frac{\partial}{\partial \rho} (\rho E_\rho) = \frac{1}{\rho} \frac{\partial}{\partial \rho} \left\{ \frac{V_0}{\ln(b/a)} \sin[\dots] \right\} = 0 \quad \checkmark$$

$$\vec{D} \cdot \vec{B} = \frac{M_0}{\rho} \frac{\partial}{\partial \phi} (H_\phi) = \frac{M_0}{\rho} \frac{\partial}{\partial \phi} \left\{ \frac{I_0}{2\pi\rho} \sin[\dots] \right\} = 0 \quad \checkmark$$

$$\vec{D} \times \vec{H} = \frac{\partial \vec{D}}{\partial t} \Rightarrow \left(-\frac{\partial}{\partial \phi} H_\phi \right) \hat{\rho} + \frac{1}{\rho} \frac{\partial}{\partial \rho} (\rho H_\phi) \hat{\phi} = \epsilon_0 \frac{\partial}{\partial t} (E_\rho) \hat{\rho} \Rightarrow$$

$$-\frac{I_0}{2\pi\rho} \left(\frac{2\pi}{\lambda} \right) \cos \left[\frac{2\pi}{\lambda} (3 - \tilde{\nu} t) \right] \hat{\rho} + 0 = -\frac{\epsilon_0 V_0}{\ln(b/a)\rho} \left(\frac{2\pi \tilde{\nu}}{\lambda} \right) \cos \left[\frac{2\pi}{\lambda} (3 - \tilde{\nu} t) \right] \hat{\rho}$$

$$\Rightarrow \underbrace{\frac{I_0}{2\pi} = \frac{\epsilon_0 V_0}{\ln(b/a)} \tilde{\nu}}_{\textcircled{1}} \quad \checkmark$$

$$\text{Also } \vec{D} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t} \Rightarrow \left(\frac{\partial}{\partial \phi} E_\rho \right) \hat{\phi} - \frac{1}{\rho} \frac{\partial E_\rho}{\partial \rho} \hat{\rho} = -M_0 \frac{\partial}{\partial t} (H_\phi) \hat{\phi} \Rightarrow$$

$$\frac{V_0}{\ln(b/a)\rho} \left(\frac{2\pi}{\lambda} \right) \cos \left[\frac{2\pi}{\lambda} (3 - \tilde{\nu} t) \right] \hat{\phi} - 0 = \frac{M_0 I_0}{2\pi\rho} \left(\frac{2\pi \tilde{\nu}}{\lambda} \right) \cos \left[\frac{2\pi}{\lambda} (3 - \tilde{\nu} t) \right] \hat{\phi}$$

$$\Rightarrow \underbrace{\frac{V_0}{\ln(b/a)} = \frac{M_0 I_0}{2\pi} \tilde{\nu}}_{\textcircled{2}} \quad \checkmark$$

Replacing for $\frac{V_0}{\ln(b/a)}$ from Eq.12) into Eq.(11) alone yields:

$$\frac{I_0}{2\pi} = \epsilon_0 \frac{M_0 I_0}{2\pi} \tilde{\nu}^2 \Rightarrow 1 = M_0 \epsilon_0 \tilde{\nu}^2 \Rightarrow \underbrace{\tilde{\nu} = 1/\sqrt{M_0 \epsilon_0}}$$

Substituting for $\tilde{\nu}$ into either Eq.(11) or Eq.(12) yields :

$$\underbrace{I_0 = \frac{2\pi V_0}{\ln(b/a) \sqrt{M_0 \epsilon_0}}}_{\textcircled{3}}$$

c) At the outer surface of inner cylinder :

$$\sigma(\beta, t) = \epsilon_0 E_\rho (\rho = a, \beta, t) = \frac{\epsilon_0 V_0}{a \ln(b/a)} \sin \left[\frac{2\pi}{\lambda} (3 - \tilde{\nu} t) \right] \quad \checkmark$$

$$\vec{J}_s(z, t) = H_\phi(\rho=a, z, t) \hat{z} = \frac{I_0}{2\pi a} \sin\left[\frac{2\pi}{\lambda}(z - \nu t)\right] \hat{z} \quad \checkmark$$

Similarly, at the inner surface of the outer cylinder:

$$\vec{J}(z, t) = -\epsilon_0 E_\rho(\rho=b, z, t) = \frac{-\epsilon_0 V_0}{b \ln(b/a)} \sin\left[\frac{2\pi}{\lambda}(z - \nu t)\right] \hat{z} \quad \checkmark$$

$$\vec{J}_s(z, t) = -H_\phi(\rho=b, z, t) \hat{z} = -\frac{I_0}{2\pi b} \sin\left[\frac{2\pi}{\lambda}(z - \nu t)\right] \hat{z} \quad \checkmark$$

d) Charge per unit length of each cylinder = $\pm \frac{2\pi \epsilon_0 V_0}{\ln(b/a)} \sin\left[\frac{2\pi}{\lambda}(z - \nu t)\right]$

Capacitance per unit length = $C = \text{charge/voltage} = \frac{2\pi \epsilon_0}{\ln(b/a)}$ ✓

Magnetic flux per unit length = $\int_a^b H_\phi(\rho, z, t) d\rho$

$$= \frac{\mu_0 I_0}{2\pi} \ln(b/a) \sin\left[\frac{2\pi}{\lambda}(z - \nu t)\right] = \Phi$$

Total current of each cylinder = $\pm I_0 \sin\left[\frac{2\pi}{\lambda}(z - \nu t)\right]$

Inductance per unit length = $L = \text{magnetic flux}/\text{current} = \frac{\mu_0 \ln(b/a)}{2\pi}$ ✓

Therefore: $L C = \frac{2\pi \epsilon_0}{\ln(b/a)} \cdot \frac{\mu_0 \ln(b/a)}{2\pi} = \mu_0 \epsilon_0$ ✓

Note that at each point on the cylinder surfaces, charge is locally conserved, namely, $\vec{D} \cdot \vec{J}_s + \frac{\partial \sigma}{\partial t} = 0$. For example, on the surface of the inner cylinder we have:

$$\vec{D} \cdot \vec{J}_s + \frac{\partial \sigma}{\partial t} = \frac{I_0}{2\pi a} \left(\frac{2\pi}{\lambda}\right) \cos\left[\frac{2\pi}{\lambda}(z - \nu t)\right] + \frac{\epsilon_0 V_0}{a \ln(b/a)} \left(-\frac{2\pi \nu}{\lambda}\right) \cos\left[\frac{2\pi}{\lambda}(z - \nu t)\right]$$

$$= 0 \Rightarrow I_0 = \frac{2\pi \epsilon_0 V_0}{\ln(b/a)} \nu = \frac{2\pi V_0}{\ln(b/a) \sqrt{\mu_0 \epsilon_0}}, \text{ which is the same as Eq.(3).}$$