

Problem 22)

a) Cartesian Coordinates: $f(\vec{r}) = f(x, y, z)$

$$f(\vec{r}_0 + \Delta \vec{r}) = f(\vec{r}_0) + \frac{\partial f}{\partial x} \Delta x + \frac{\partial f}{\partial y} \Delta y + \frac{\partial f}{\partial z} \Delta z$$

$$\Rightarrow \Delta f = f(\vec{r}_0 + \Delta \vec{r}) - f(\vec{r}_0) = \left(\frac{\partial f}{\partial x} \hat{x} + \frac{\partial f}{\partial y} \hat{y} + \frac{\partial f}{\partial z} \hat{z} \right) \cdot (\Delta x \hat{x} + \Delta y \hat{y} + \Delta z \hat{z})$$

Defining $\vec{\nabla} f(\vec{r}) = \frac{\partial f}{\partial x} \hat{x} + \frac{\partial f}{\partial y} \hat{y} + \frac{\partial f}{\partial z} \hat{z}$,

We can write the above expression as follows:

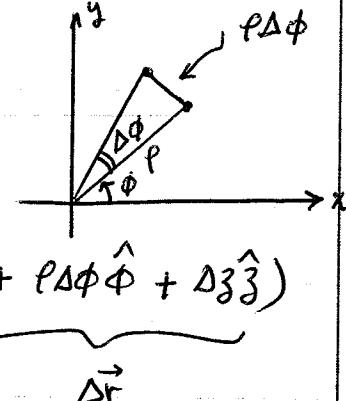
$$\Delta f = \vec{\nabla} f \cdot \Delta \vec{r}$$

Now, the above dot-product is equal to $|\vec{\nabla} f| |\Delta \vec{r}| \cos \theta$, where $|\vec{\nabla} f|$ is the magnitude (or length) of $\vec{\nabla} f$, $|\Delta \vec{r}|$ is the magnitude of $\Delta \vec{r}$, and θ is the angle between $\vec{\nabla} f$ and $\Delta \vec{r}$. If we fix the length of $\Delta \vec{r}$, we'll find that Δf is maximized when $\theta = 0^\circ$. Therefore, $|\vec{\nabla} f| = \max(\frac{\Delta f}{\Delta r})$ for a fixed $|\Delta \vec{r}|$, and the direction of $\vec{\nabla} f$ is the same as the direction of $\Delta \vec{r}$ for which Δf is a maximum.

b) Cylindrical Coordinates: $f(\vec{r}) = f(r, \phi, z) \Rightarrow$

$$f(\vec{r}_0 + \Delta \vec{r}) = f(\vec{r}_0) + \frac{\partial f}{\partial r} \Delta r + \frac{\partial f}{\partial \phi} \Delta \phi + \frac{\partial f}{\partial z} \Delta z$$

$$= f(\vec{r}_0) + \underbrace{\left(\frac{\partial f}{\partial r} \hat{r} + \frac{\partial f}{\partial \phi} \hat{\phi} + \frac{\partial f}{\partial z} \hat{z} \right)}_{\vec{\nabla} f} \cdot \underbrace{(\Delta r \hat{r} + r \Delta \phi \hat{\phi} + \Delta z \hat{z})}_{\Delta \vec{r}}$$



The rest of the argument is the same as in Part (a).

c) Spherical Coordinates: $f(\vec{r}) = f(r, \theta, \phi) \Rightarrow$

$$f(\vec{r}_0 + \Delta \vec{r}) = f(\vec{r}_0) + \frac{\partial f}{\partial r} \Delta r + \frac{\partial f}{\partial \theta} \Delta \theta + \frac{\partial f}{\partial \phi} \Delta \phi$$

$$= f(\vec{r}_0) + \underbrace{\left(\frac{\partial f}{\partial r} \hat{r} + \frac{\partial f}{\partial \theta} \hat{\theta} + \frac{\partial f}{\partial \phi} \hat{\phi} \right)}_{\vec{\nabla} f} \cdot \underbrace{(\Delta r \hat{r} + r \sin \theta \Delta \phi \hat{\theta} + r \sin \theta \cos \phi \Delta \phi \hat{\phi})}_{\Delta \vec{r}}$$

