Towards Polarization Enabled Wildfire Detection

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Comprehensive Exam, August 23rd, 2024





For this comp exam...



Optical Physics

• Atmospheric Scattering

Sky Polarization

Optical Engineering

Instrument
Development

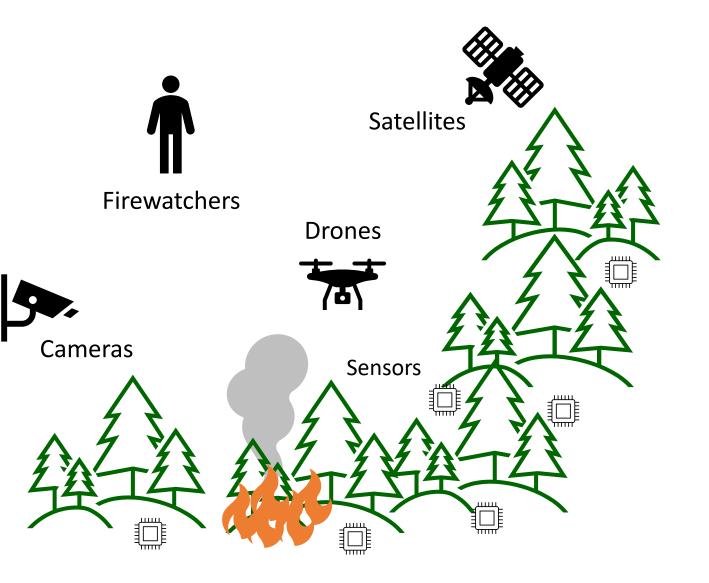
Instrument
Deployment

Image Science

 Polarization Image Analysis

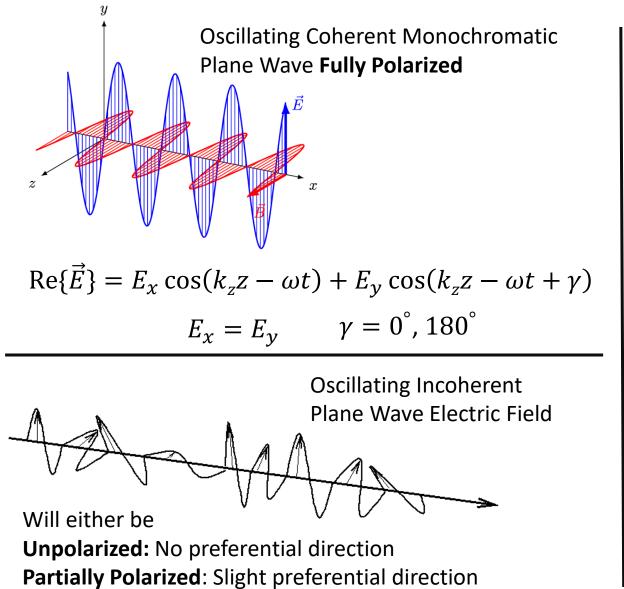
• Singularity Estimation

Disadvantages in Current Wildfire Detection Techniques

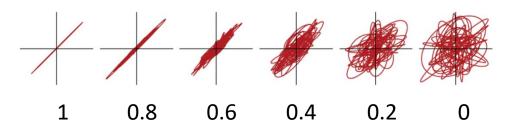


- Low spatial coverage
- Reliance on humans (firewatchers and drones)
- Require the fire or smoke to be in the field of view of the detector
- High rates of false positives from dust, fog, pollution

Linear Polarization

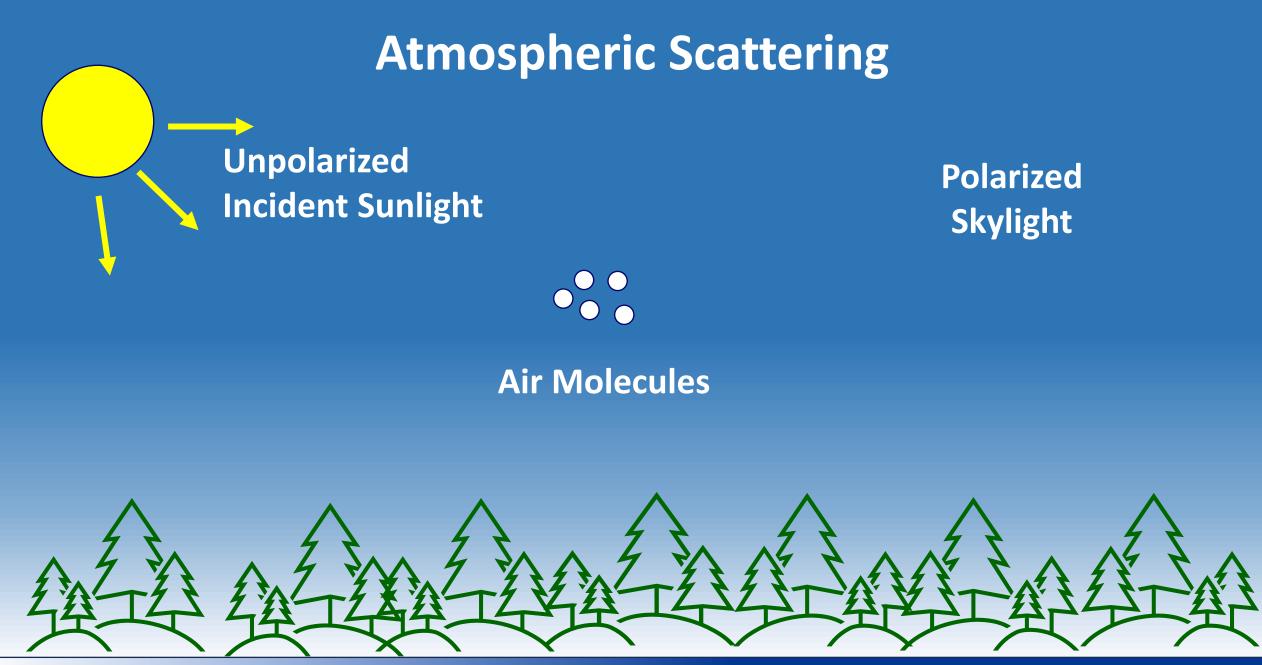


Degree of Linear Polarization: Ratio of Polarized Intensity to Total Intensity

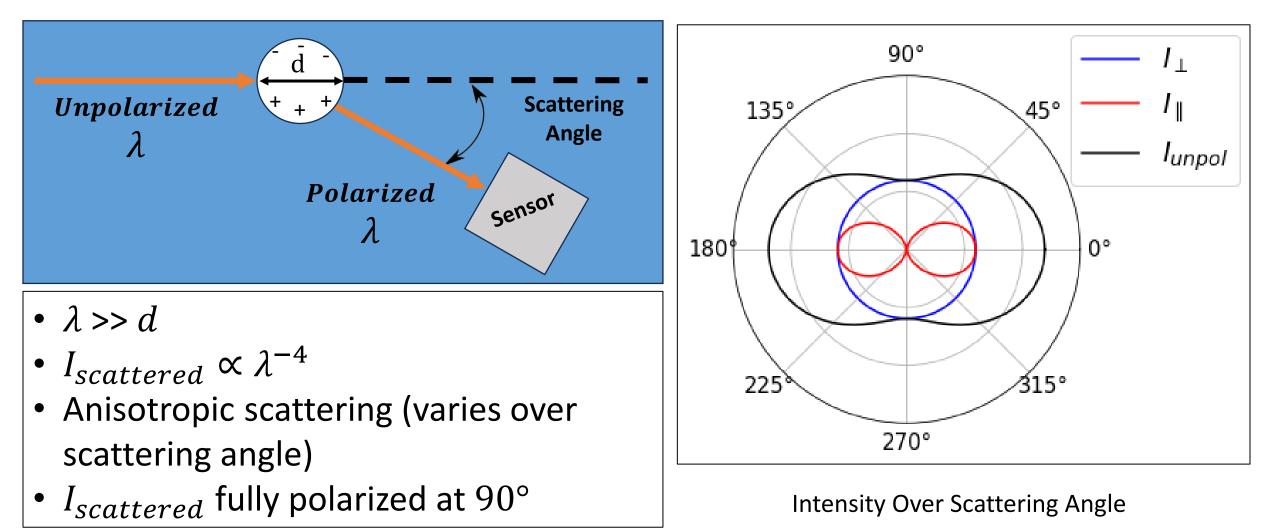


Angle of Linear Polarization: Orientation of the electric field trace from some reference plane

Scattering Plane: Plane containing the view vector and incident light vector



Rayleigh Scattering by Air Molecules

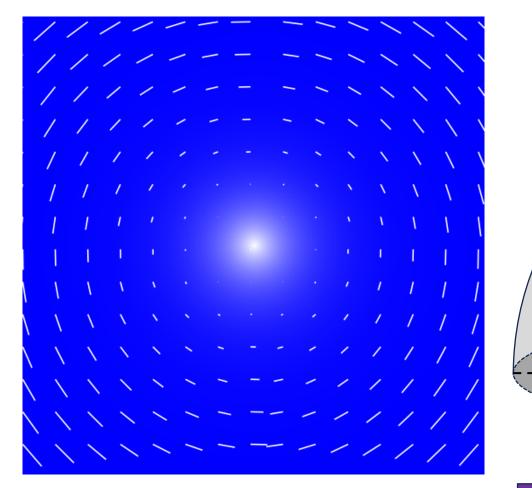


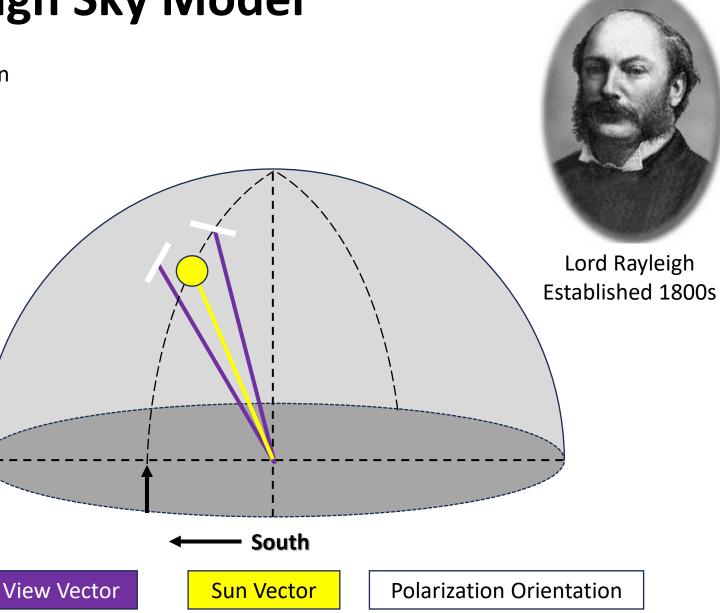
Citations: (1) https://miepython.readthedocs.io/en/latest/

Optical Physics

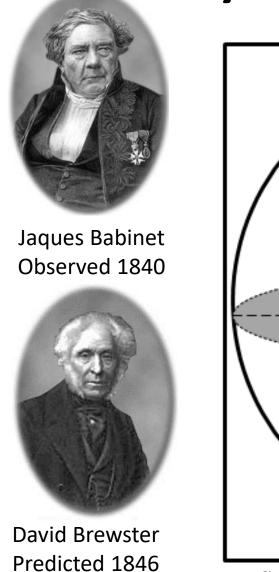
Rayleigh Sky Model

Lines depict the angle and degree of linear polarization

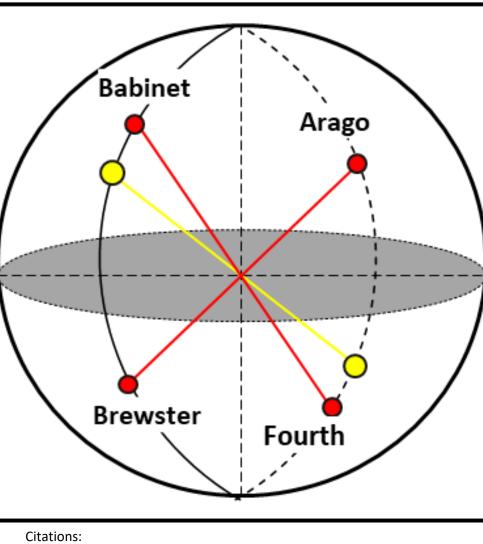




Sky Polarization Neutral Points



Babinet Observed 1847



(1) Berry et al. Polarization singularities in the clear sky" In: New Journal of Physics (2004)



François Arago Observed 1809

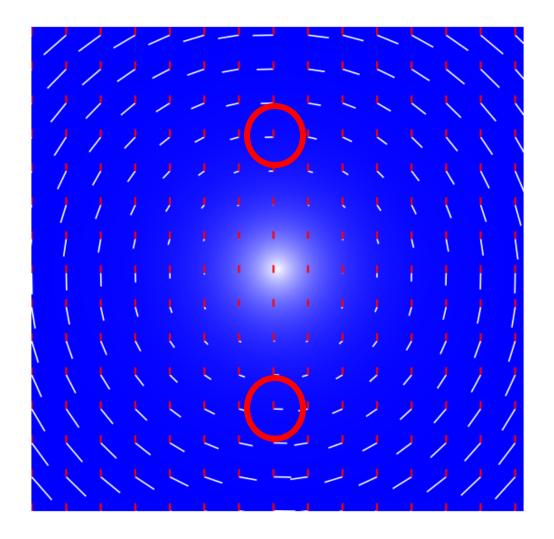


Gábor Horváth Observed 2001

Optical Physics

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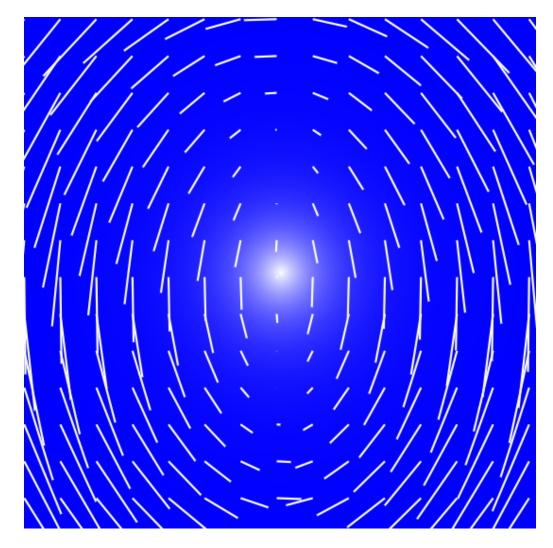
Sky Polarization Neutral Points



Single scattered polarized light incoherently adding with multiple scattered polarized light

Orthogonal states add to unpolarized light at the neutral point

Sky Polarization Neutral Points

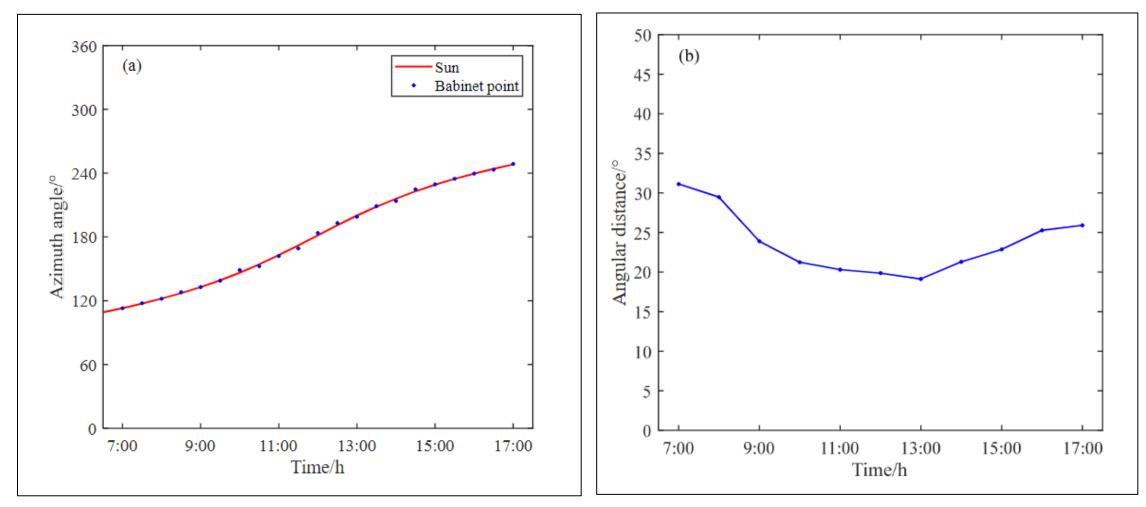


Net polarization pattern: Tangential about the Sun with the addition of two singularities

At neutral point:

- All orthogonal polarization states are equal
- Angle of linear polarization flips above and below neutral point

Neutral Point Location Diurnal Dependence



Reported Babinet and Sun Azimuth over 10 hours. λ unknown, but within visible spectrum.

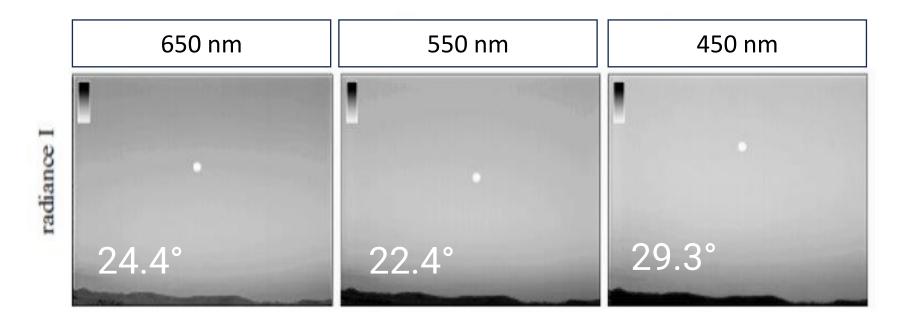
Reported Difference in Babinet and Sun Altitude over 10 hours. λ unknown, but within visible spectrum.

Citations: (1) Gui and Wei, "Modeling method of skylight polarization patterns based on distribution of neutral point". In Computer Vision, Image and Deep Learning. (2023)

Optical Physics

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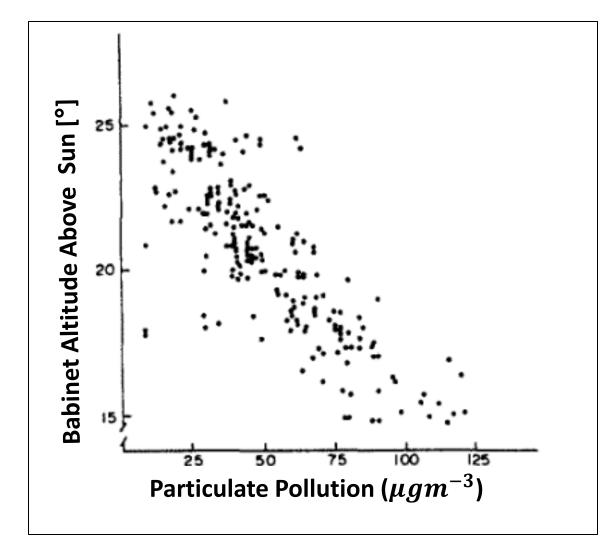
Neutral Point Location Wavelength Dependence



Arago Neutral Point Position from Anti-Sun

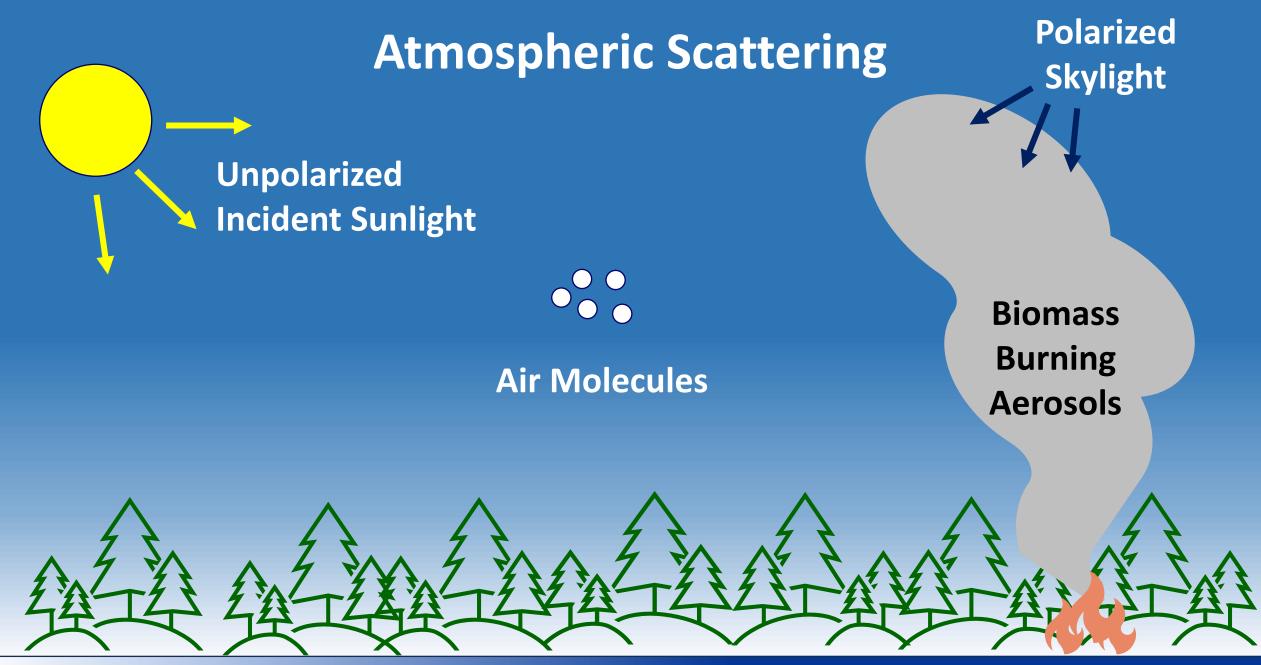
Citations: (1) Gui and Wei, "Modeling method of skylight polarization patterns based on distribution of neutral point". In Computer Vision, Image and Deep Learning. (2023)

Neutral Point Location Aerosol Loading Dependence

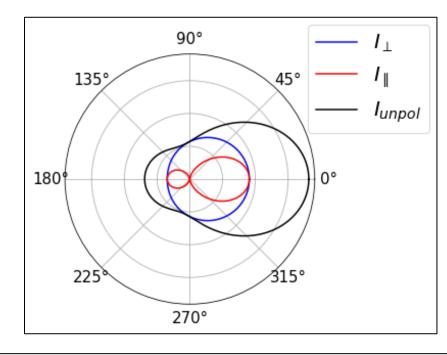


Reported Babinet altitudes relative to the Sun at a 30° altitude at different levels of pollution $\lambda = 546.4 nm$. Shows dependence on aerosol loading

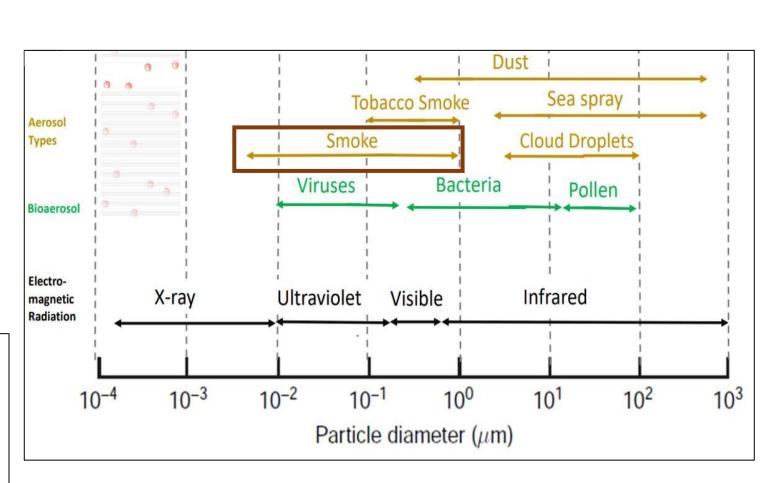
Citations (1) C. Bellvar, "Influence Of Particulate Pollution On The Positions Of Neutral Points In The Sky At Seville" (1986)



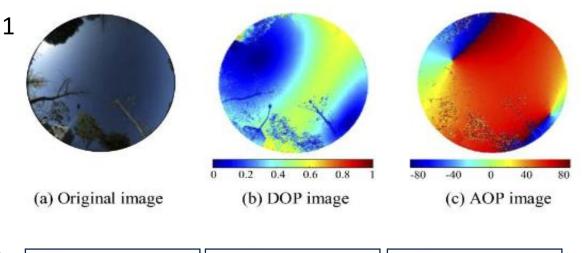
Mie Scattering by Aerosols

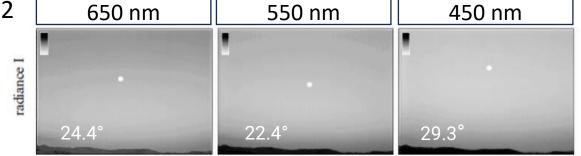


- $\lambda \simeq > d$
- *I_{scattered}* no simple relationship
- Strong forward scattering
- No set polarization pattern



Neutral Point Measurements from Literature





Arago Neutral Point Position from Anti-Sun

- Fisheye lenses
- Sun occulting
- Visible wavelengths

Citations: (1) Fan et al. "Neutral point detection using the AOP of polarized skylight patterns". In: Opt. Express 29.4 (Feb. 2021) (2) Horvath et al. In: Polarized Light in Animal Vision (2004)

Optical Engineering

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<u>Ultraviolet Linear Stokes Imaging Polarimeter</u>

Back-Illuminated CMOS

355 nm +/- 10nm Bandpass

25 mm lens IFOV = 0.0062°, 22.68 arcseconds

Rotating Linear Polarizer

Max Exposure 1s



Optical Engineering

Choice of Imaging Optics





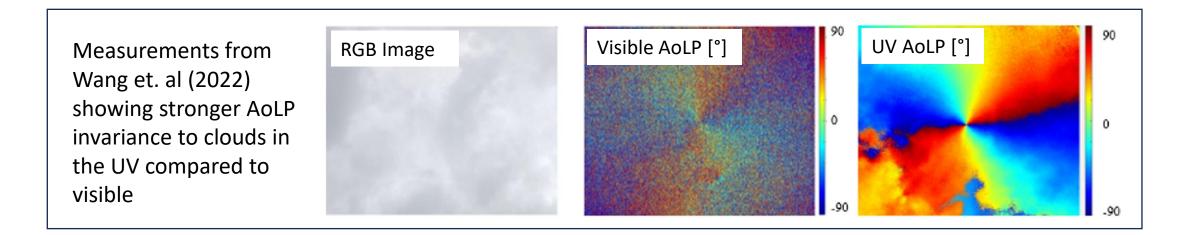
Sensor Type	Back-Illuminated CMOS
Sensor Pixel Number and Size	2848 (H) x 2848 (V) 2.74 um x 2.74 um
Sensor Size	7.78 mm x 7.78 mm
ADC	12 Bit, Dynamic Range (0-4095)
Lens Focal Length	25 mm
Lens FOV	17.68°, 63648 arcseconds IFOV: 0.0062°, 22.32 arcseconds

Optical Engineering

Choice of Wavelength

- For UV light cloud interactions, $\lambda \ll d$
 - Results in angle of polarization (AoLP) invariance to cloud cover





Citations: (1) Li et. al "Ultraviolet-visible light compass method based on local atmospheric polarization characteristics in adverse weather conditions". In Applied Optics (2022)

Optical Engineering

DeLeon Comp Exam

Polarimeter Data Products

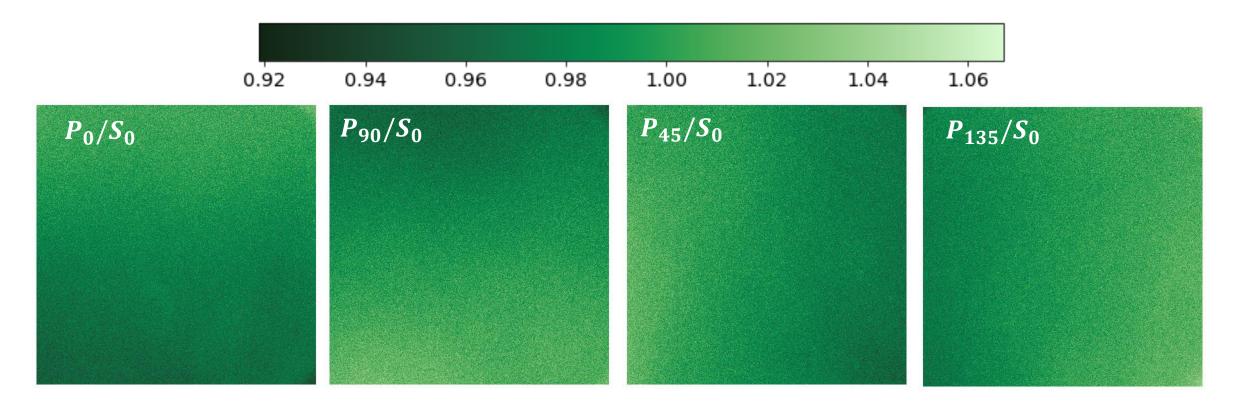
- Imaging Polarimetry \rightarrow obtains images of polarized flux at different orientations, P_{ϕ}
- From flux images the Linear Stokes Parameters are calculated,

$$\mathbf{S} = \begin{pmatrix} S_0 \\ S_1 \\ S_2 \end{pmatrix} = \begin{pmatrix} P_0 + P_{90} \\ P_0 - P_{90} \\ P_{45} - P_{135} \end{pmatrix}$$

From the Linear Stokes Parameters, Degree of Linear Polarization (DoLP) and Angle of Linear Polarization (AoLP) are calculated,

$$DoLP = \left(\frac{\sqrt{s_1^2 + s_2^2}}{s_0}\right) * 100 \,[\%]. \quad AoLP = \frac{1}{2} \tan^{-1} \frac{s_2}{s_1} \,[^\circ].$$

Neutral Point Position Estimation



$$\bar{r}_{\phi} = \frac{1}{J} \sum_{j=0}^{J} \left[\frac{P_{\phi}}{S_0} \right]_{lj} \quad \phi \in [0^{\circ}, 90^{\circ}],$$

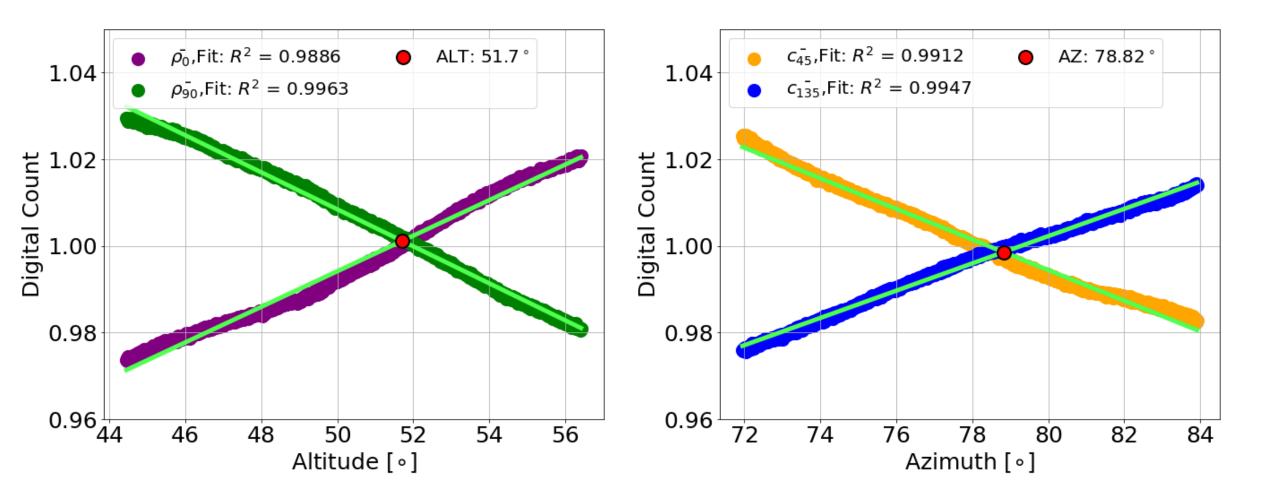
$$\bar{c}_{\phi} = \frac{1}{L} \sum_{l=0}^{L} \left[\frac{P_{\phi}}{S_0} \right]_{lj} \quad \phi \in [45^{\circ}, 135^{\circ}].$$

Row Average

Column Average

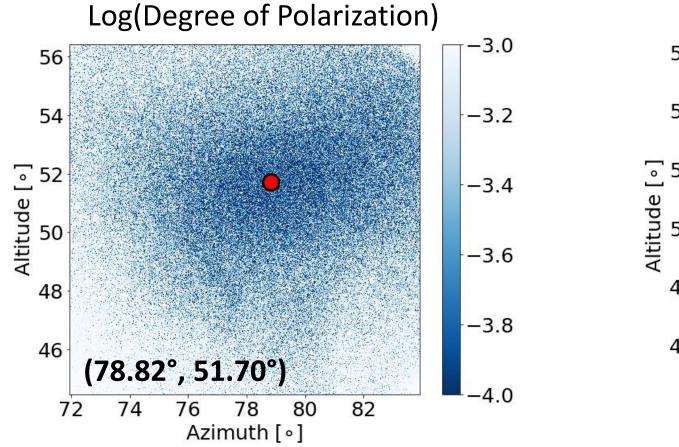
Image Science

Neutral Point Position Estimation

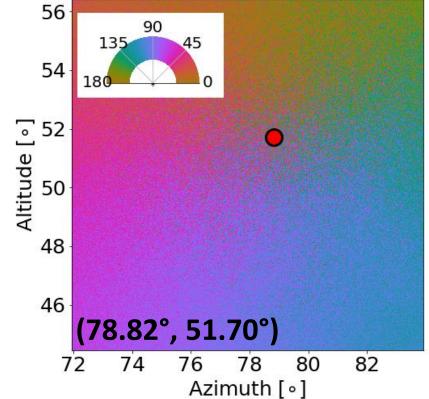


Babinet Neutral Point Measurement

O (AZ: 77.14°, ALT: 29.64°), λ = 355 nm +/- 10 nm



Angle of Linear Polarization [°]



Summary & Future Work

Wildfire Detection

Optical Physics

- Atmospheric Scattering
- Sky Polarization

Optical Engineering

- Instrument Development
- Instrument Deployment

Image Science

- Polarization Image Analysis
- Singularity Estimation

- □ Measurement of Babinet over many days
- Correlate Babinet position with time of day
- □ Monitor changes in Babinet with aerosol loading
- □ Simulate Babinet position under different
 - atmosphere conditions
- Use simulation and measurements to develop a specification for how much Babinet changes with aerosol loading

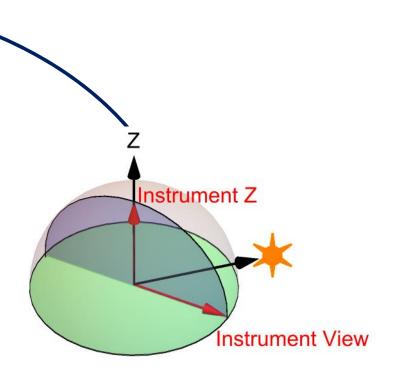
Start of backup slides

Sun Moves on Average: 0.0042°/second

ULTRASIP Measurement Time:

1s exposure/image Four images in 6 seconds

Sun would move 0.025° over the measurement time or 4 pixels

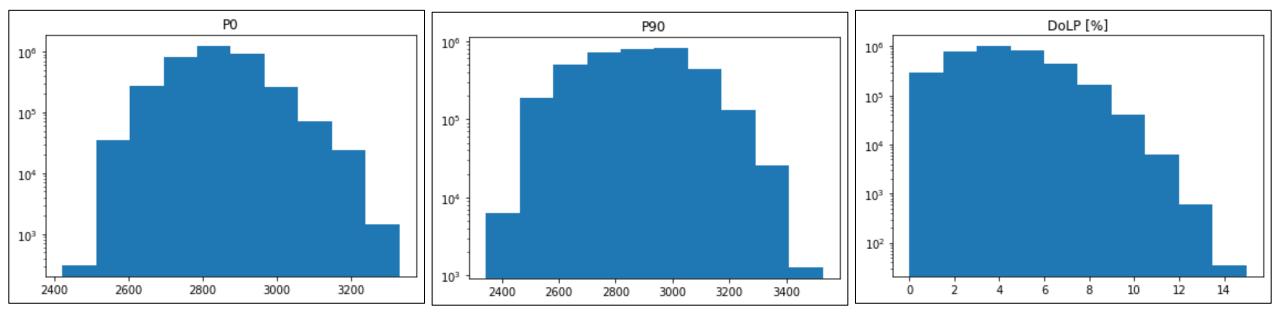


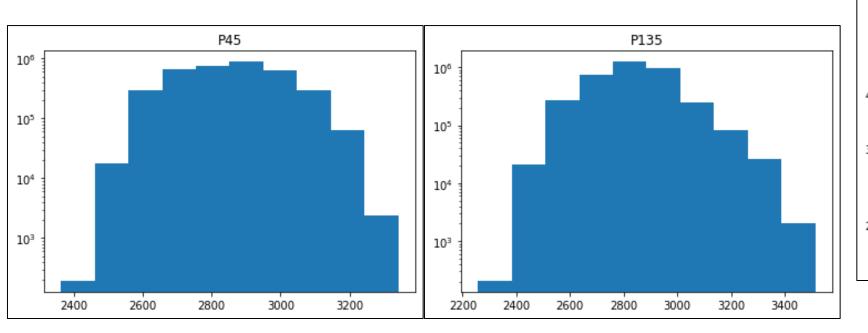


Degree resolution 0.01°

Optical Engineering

Sun Tracking





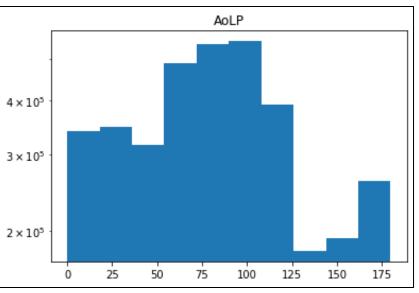


Image Science

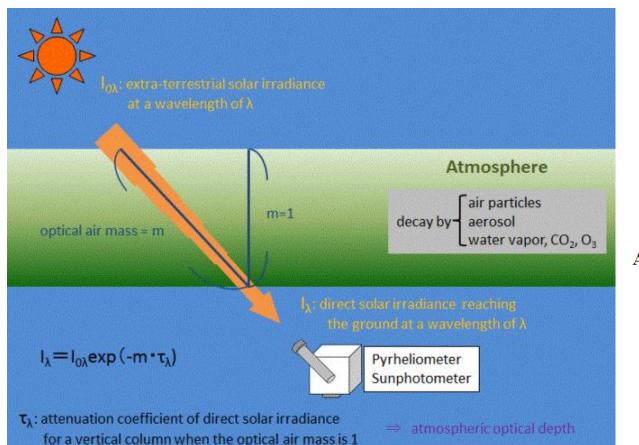
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$$V = egin{bmatrix} 1 & x_1 \ 1 & x_2 \ 1 & x_3 \ dots & dots \ 1 & x_M \end{bmatrix} \qquad (V^TV) \mathbf{a} = V^T \mathbf{y}$$

Solve for **a** such that minimized the residual sum of squares

$$\min_{\mathbf{a}} \|V\mathbf{a} - \mathbf{y}\|^2$$

Aerosol Optical Depth



a dimensionless number that measures how much light is lost due to the presence of solid and liquid particles in the air, such as dust, sand, smoke, and volcanic ash

0.1 or lower = clear sky, 1 = hazy

