



OPTI510R: Photonics

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Announcements

- Homework #4 is assigned, due March 25th

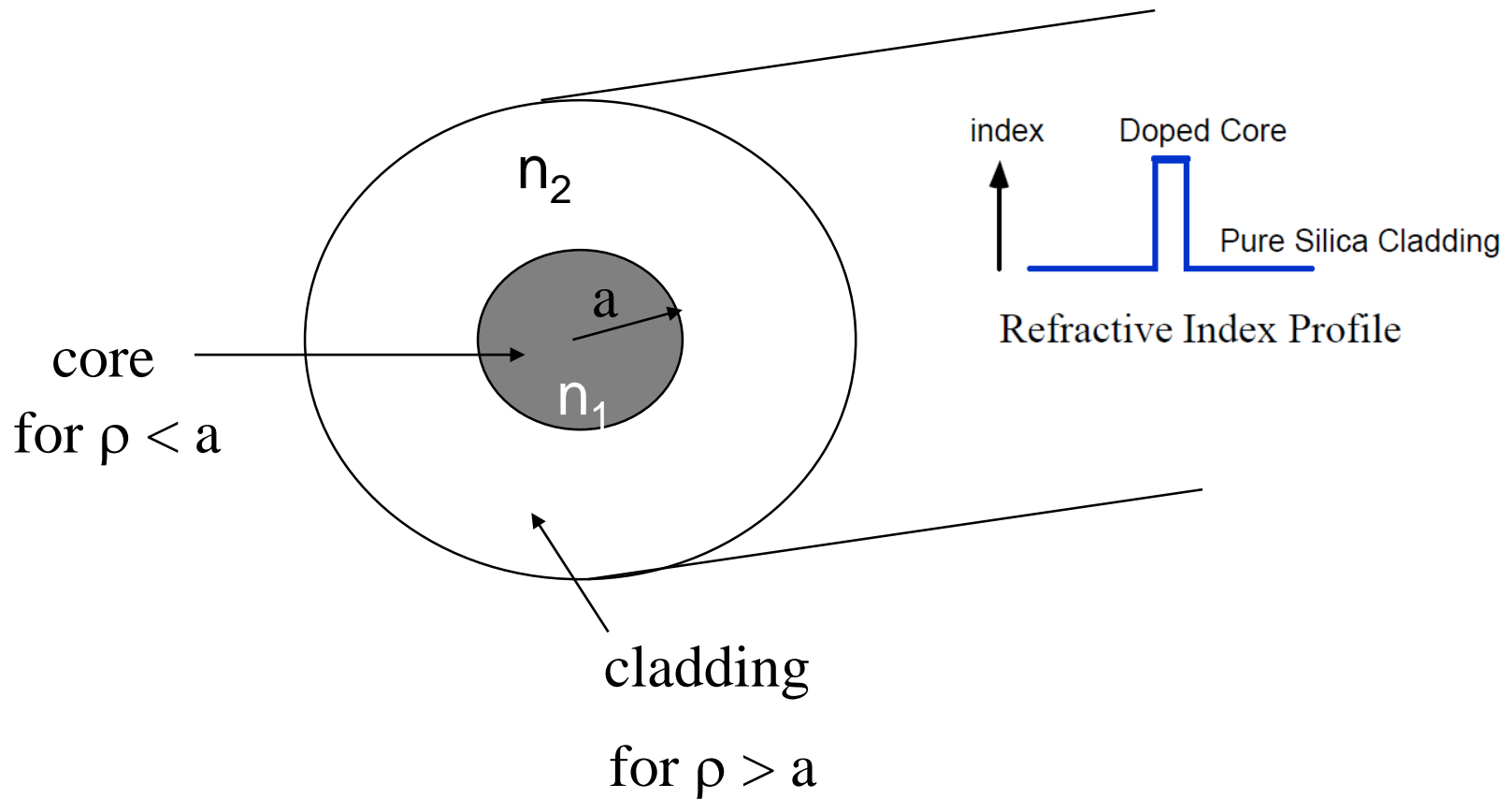


Fiber dispersion and compensation

- Review of fiber modes
- Sources of dispersion
 - » Modal dispersion
 - » Material dispersion
 - » Waveguide dispersion
 - » Polarization dispersion
 - » Nonlinear dispersion
- Dispersion compensation techniques
 - » Dispersion engineered fibers
 - » Pre-chirp technique
 - » Dispersion compensating fibers
 - » Chirped fiber Bragg grating
 - » Tunable dispersion compensation



Guided-wave analysis





Guided-wave analysis

- Maxwell's equations in the Fourier domain lead to

$$\nabla^2 \tilde{\mathbf{E}} + n^2(\omega) k_0^2 \tilde{\mathbf{E}} = 0.$$

$n = n_1$ inside the core but changes to n_2 in the cladding.

- Useful to work in cylindrical coordinates ρ, ϕ, z .

Common to choose E_z and H_z as independent components.

- Equation for E_z in cylindrical coordinates:

$$\frac{\partial^2 E_z}{\partial \rho^2} + \frac{1}{\rho} \frac{\partial E_z}{\partial \rho} + \frac{1}{\rho^2} \frac{\partial^2 E_z}{\partial \phi^2} + \frac{\partial^2 E_z}{\partial z^2} + n^2 k_0^2 E_z = 0.$$

- H_z satisfies the same equation.



Guided-wave analysis

- Use the method of separation of variables:

$$E_z(\rho, \phi, z) = F(\rho)\Phi(\phi)Z(z).$$

- We then obtain three ODEs:

$$d^2Z/dz^2 + \beta^2Z = 0,$$

$$d^2\Phi/d\phi^2 + m^2\Phi = 0,$$

$$\frac{d^2F}{d\rho^2} + \frac{1}{\rho} \frac{dF}{d\rho} + \left(n^2k_0^2 - \beta^2 - \frac{m^2}{\rho^2} \right) F = 0.$$

- β and m are two constants (m must be an integer).

First two equations can be solved easily to obtain

$$Z(z) = \exp(i\beta z), \quad \Phi(\phi) = \exp(im\phi).$$

- $F(\rho)$ satisfies the Bessel equation.



Guided-wave analysis

- General solution for E_z and H_z :

$$E_z = \begin{cases} AJ_m(p\rho) \exp(im\phi) \exp(i\beta z); & \rho \leq a, \\ CK_m(q\rho) \exp(im\phi) \exp(i\beta z); & \rho > a. \end{cases}$$

$$H_z = \begin{cases} BJ_m(p\rho) \exp(im\phi) \exp(i\beta z); & \rho \leq a, \\ DK_m(q\rho) \exp(im\phi) \exp(i\beta z); & \rho > a. \end{cases}$$

$$p^2 = n_1^2 k_0^2 - \beta^2, \quad q^2 = \beta^2 - n_2^2 k_0^2.$$

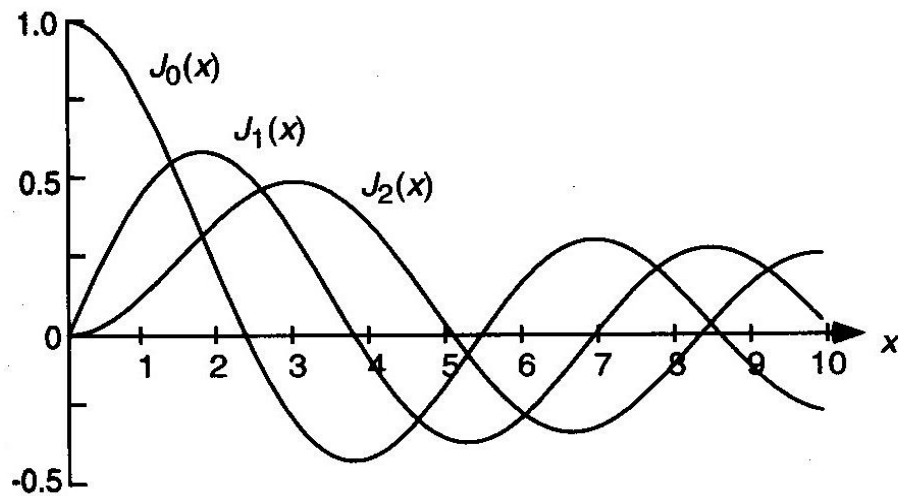
- Other components can be written in terms of E_z and H_z :

$$\begin{aligned} E_\rho &= \frac{i}{p^2} \left(\beta \frac{\partial E_z}{\partial \rho} + \mu_0 \frac{\omega}{\rho} \frac{\partial H_z}{\partial \phi} \right), & E_\phi &= \frac{i}{p^2} \left(\frac{\beta}{\rho} \frac{\partial E_z}{\partial \phi} - \mu_0 \omega \frac{\partial H_z}{\partial \rho} \right), \\ H_\rho &= \frac{i}{p^2} \left(\beta \frac{\partial H_z}{\partial \rho} - \epsilon_0 n^2 \frac{\omega}{\rho} \frac{\partial E_z}{\partial \phi} \right), & H_\phi &= \frac{i}{p^2} \left(\frac{\beta}{\rho} \frac{\partial H_z}{\partial \phi} + \epsilon_0 n^2 \omega \frac{\partial E_z}{\partial \rho} \right). \end{aligned}$$



Bessel function basics

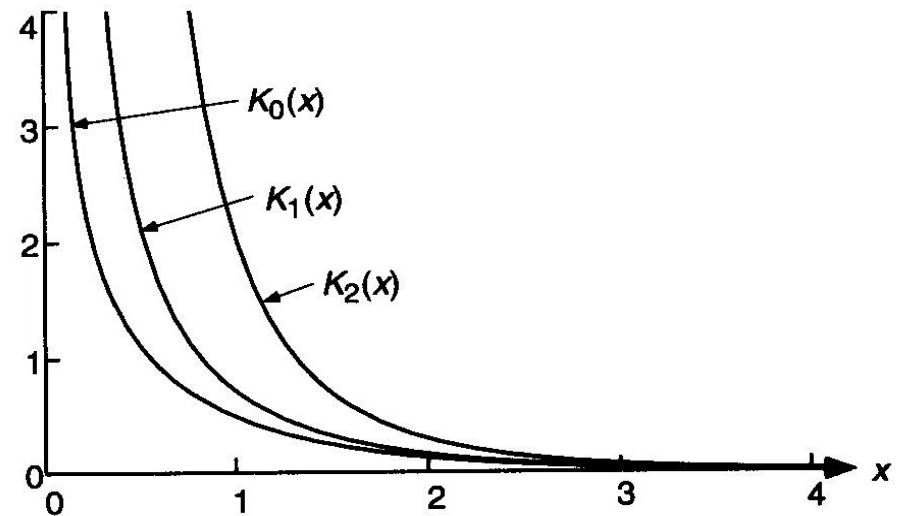
Bessel functions of the first kind



$$u(r) \propto J_l(k_T r)$$

(core)

Modified Bessel functions of the second kind



$$u(r) = K_l(gr)$$

(cladding)



Eigen-value equation

- Boundary conditions: E_z , H_z , E_ϕ , and H_ϕ should be continuous across the *core-cladding interface*.
- Continuity of E_z and H_z at $\rho = a$ leads to $AJ_m(pa) = CK_m(qa)$, $BJ_m(pa) = DK_m(qa)$.

Continuity of E_ϕ and H_ϕ provides two more equations.

- Four equations lead to the eigenvalue equation

$$\begin{aligned} & \left[\frac{J'_m(pa)}{pJ_m(pa)} + \frac{K'_m(qa)}{qK_m(qa)} \right] \left[\frac{J'_m(pa)}{pJ_m(pa)} + \frac{n_2^2}{n_1^2} \frac{K'_m(qa)}{qK_m(qa)} \right] \\ &= \frac{m^2}{a^2} \left(\frac{1}{p^2} + \frac{1}{q^2} \right) \left(\frac{1}{p^2} + \frac{n_2^2}{n_1^2} \frac{1}{q^2} \right) \\ & p^2 = n_1^2 k_0^2 - \beta^2, \quad q^2 = \beta^2 - n_2^2 k_0^2. \end{aligned}$$



Eigen-value equation

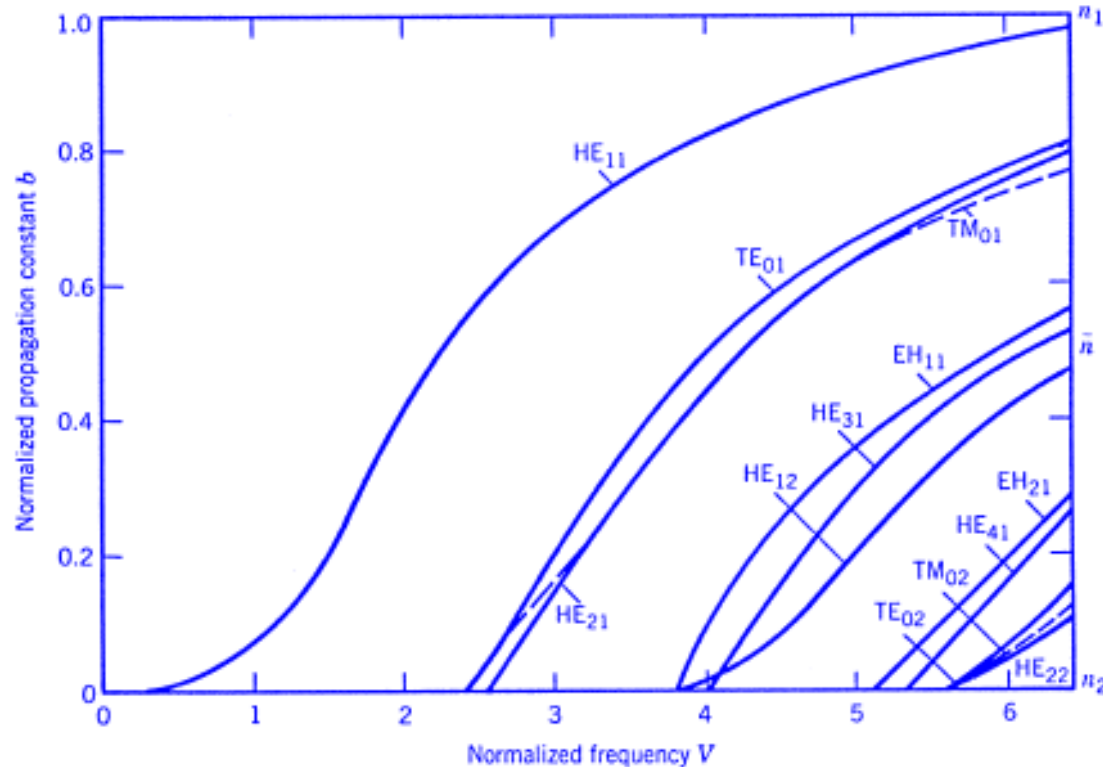
- Eigenvalue equation involves Bessel functions and their derivatives. It needs to be solved numerically.
- Noting that $p^2 + q^2 = (n_1^2 - n_2^2)k_0^2$, we introduce the dimensionless V parameter as

$$V = k_0 a \sqrt{n_1^2 - n_2^2}.$$

- Multiple solutions for β for a given value of V .
- Each solution represents an optical mode.
- Number of modes increases rapidly with V parameter.
- Effective mode index $\bar{n} = \beta/k_0$ lies between n_1 and n_2 for all bound modes.



Eigen-value equation



- Useful to introduce a normalized quantity

$$b = (\bar{n} - n_2) / (n_1 - n_2), \quad (0 < b < 1)$$

- Modes quantified through $\beta(\omega)$ or $b(V)$.



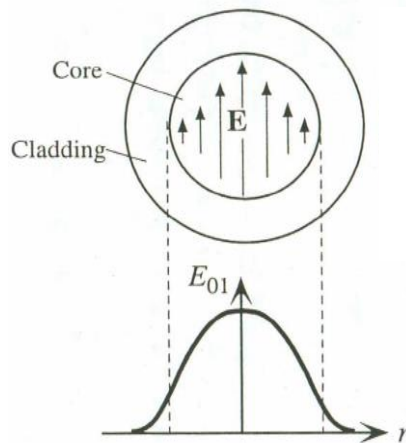
Fundamental modes

- Single-mode fibers require $V < 2.405$ (first zero of J_0).

They transport light through the fundamental HE_{11} mode.

- This mode is almost linearly polarized ($|E_z|^2 \ll |E_x|^2$)

$$E_x(\rho, \phi, z) = \begin{cases} A[J_0(p\rho)/J_0(pa)]e^{i\beta z} ; & \rho \leq a, \\ A[K_0(q\rho)/K_0(qa)]e^{i\beta z}; & \rho > a. \end{cases}$$



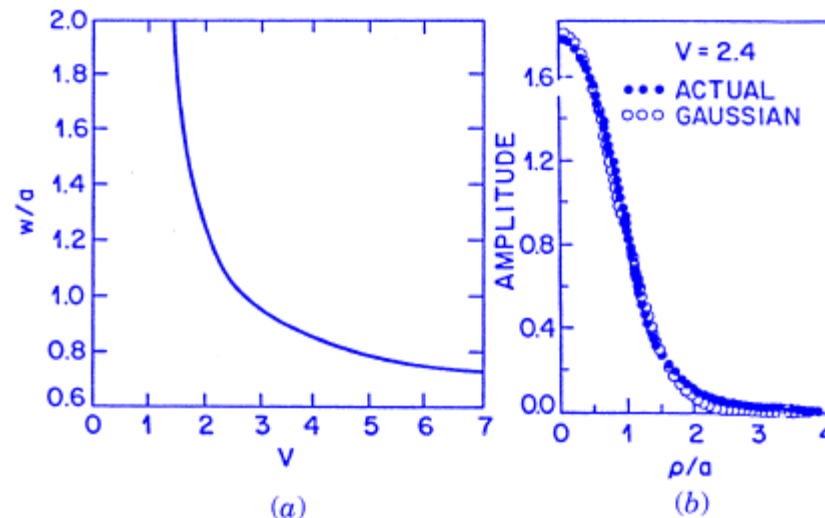


Fundamental modes

- Use of Bessel functions is not always practical.
- It is possible to approximate spatial distribution of HE_{11} mode with a Gaussian for V in the range 1 to 2.5.

$$E_x(\rho, \phi, z) \approx A \exp(-\rho^2/w^2) e^{i\beta z}.$$

- Spot size w depends on V parameter.





Fundamental modes

➤ Spot size: $w/a \approx 0.65 + 1.619V^{-3/2} + 2.879V^{-6}$.

➤ Mode index:

$$\bar{n} = n_2 + b(n_1 - n_2) \approx n_2(1 + b\Delta),$$

$$b(V) \approx (1.1428 - 0.9960/V)^2.$$

➤ Confinement factor:

$$\Gamma = \frac{P_{\text{core}}}{P_{\text{total}}} = \frac{\int_0^a |E_x|^2 \rho \, d\rho}{\int_0^\infty |E_x|^2 \rho \, d\rho} = 1 - \exp\left(-\frac{2a^2}{w^2}\right).$$

$\Gamma \approx 0.8$ for $V = 2$ but drops to 0.2 for $V = 1$.

➤ Mode properties completely specified if V parameter is known



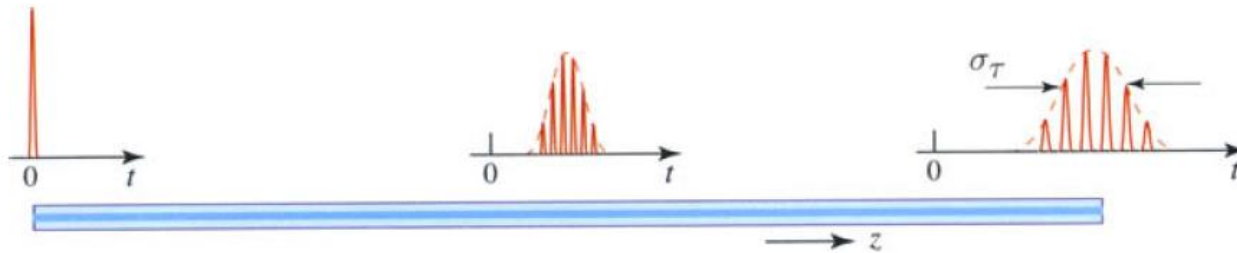
Sources of dispersion in optical fiber

- Modal dispersion
 - Occurs in multimode fibers coming from differences in group velocity for different modes
- Material dispersion
 - Results from the wavelength dependence of the bulk refractive index
- Waveguide dispersion
 - Results from the wavelength dependence of the effective index in a waveguide
 - Material + waveguide dispersion is termed chromatic dispersion
- Polarization mode dispersion
 - Results from the fact that different polarizations travel at different speeds due to small birefringence that is present
- Nonlinear dispersion – an example is self-phase modulation



Modal dispersion

- Modal dispersion occurs in multimode fibers as a result of differences in the group velocities of the various modes.
- A single pulse of light entering an M-mode fiber spreads into M pulses.



- Estimate of pulse spread
$$\sigma_\tau = \frac{1}{2} \left(\frac{L}{v_{\min}} - \frac{L}{v_{\max}} \right),$$

– Where v_{\min} and v_{\max} are the smallest and largest group velocity of the modes.

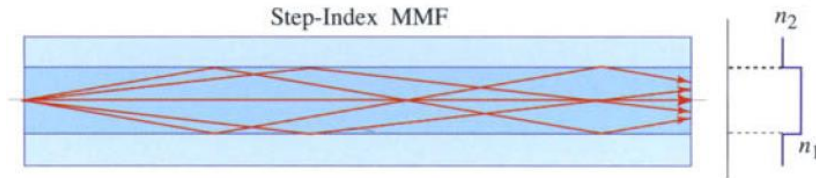


Modal dispersion

- For multimode step-index fiber,

$$v_{\min} \approx c_1(1 - \Delta), \quad v_{\max} \approx c_1, \quad \Delta = (n_1^2 - n_2^2) / 2n_1^2 \quad (\text{see chapter 9 S\&T})$$

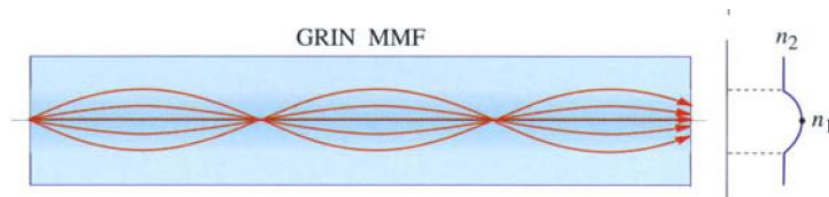
$$\sigma_\tau \approx \frac{L\Delta}{2c_1}$$



- For multimode graded-index fiber,

$$v_{\min} \approx c_1(1 - \Delta^2 / 2), \quad v_{\max} \approx c_1, \quad \Delta = (n_1^2 - n_2^2) / 2n_1^2 \quad (\text{see chapter 9 S\&T})$$

$$\sigma_\tau \approx \frac{L\Delta^2}{4c_1}$$





Material dispersion

- Spread of wave packet after traveling a distance L through a dispersive material

$$\Delta\tau = \frac{L}{c} (N_g(\lambda_1) - N_g(\lambda_2)) = \frac{L}{c} \Delta N_g = \frac{L}{c} \frac{dN_g}{d\lambda} \Delta\lambda$$

$$\text{Since } \frac{dN_g}{d\lambda} = \frac{d}{d\lambda} \left(n - \lambda \frac{dn}{d\lambda} \right) = -\lambda \frac{d^2n}{d\lambda^2}$$

$$\text{We get } \Delta\tau = -\lambda \frac{d^2n}{d\lambda^2} \frac{L}{c} \Delta\lambda \quad \text{where}$$

$$D_M = -\frac{\lambda}{c} \frac{\partial^2 n}{\partial \lambda^2} \text{ is the material dispersion parameter}$$

$$\Delta\tau = D_m * L * \Delta\lambda$$



Waveguide dispersion

In single-mode fibers the group delay, τ_g , determines the transit time of a pulse traveling through a unit length of fiber. To get the waveguide dispersion we want to express the group delay in terms of normalized parameters, b and V :

Normalized propagation constant:

$$b = \frac{\beta/k_0 - n_{clad}}{n_{core} - n_{clad}}.$$

Normalized frequency:

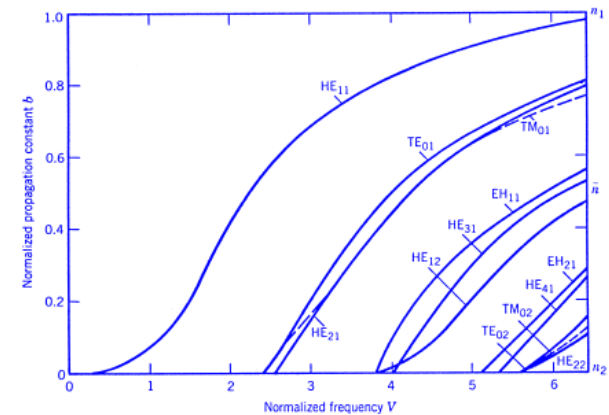
$$V = \frac{2\pi a}{\lambda_0} \sqrt{n_{core}^2 - n_{clad}^2}$$

$$\tau_g = \frac{d\beta}{d\omega} = \frac{d\beta}{dk_0} \frac{dk_0}{d\omega} = \frac{1}{c} \frac{d\beta}{dk_0}.$$

Using normalized parameters :

$$\frac{d\beta}{dk_0} = \frac{d\beta}{dV} \frac{dV}{dk_0} = \frac{d\beta}{dV} \frac{V}{k_0}.$$

We get : $\tau_g = \frac{1}{c} \frac{d\beta}{dk_0} = \frac{1}{c} \frac{V}{k_0} \frac{d\beta}{dV}.$





Waveguide dispersion

Defining $\Delta = \frac{n_{core} - n_{clad}}{n_{core}}$ and with $\beta = [b(n_{core} - n_{clad}) + n_{clad}]k_0 \approx k_0 n_{clad} (1 + b\Delta)$ (when Δ is small),

$$\begin{aligned} \rightarrow \tau_g &= \frac{1}{c} \frac{V}{k_0} \frac{d}{dV} [k_0 n_{clad} (1 + b\Delta)] \\ &= \frac{1}{c} \frac{V}{k_0} \frac{d(k_0 n_{clad})}{dV} + \frac{1}{c} \frac{V}{k_0} \frac{d(b\Delta k_0 n_{clad})}{dV} \end{aligned}$$

τ_m : material delay τ_w : waveguide delay

$$\tau_w = \frac{1}{c} \frac{V}{k_0} \frac{d(b\Delta k_0 n_{clad})}{dV}. \text{ Noting that } V = \sqrt{2\Delta n_{clad}} k_0 a, \text{ we get :}$$

$$\tau_w = \frac{1}{c} n_{clad} \Delta \frac{d(bV)}{dV}, \text{ from which we get the waveguide dispersion}$$

$$\frac{d\tau_w}{dV} = \frac{1}{c} n_{clad} \Delta \frac{d^2(bV)}{dV^2}. \text{ With } dV = a \sqrt{n_{core}^2 - n_{clad}^2} dk_0 \text{ and } d\lambda = -\lambda \frac{dk_0}{k_0},$$

we finally get :

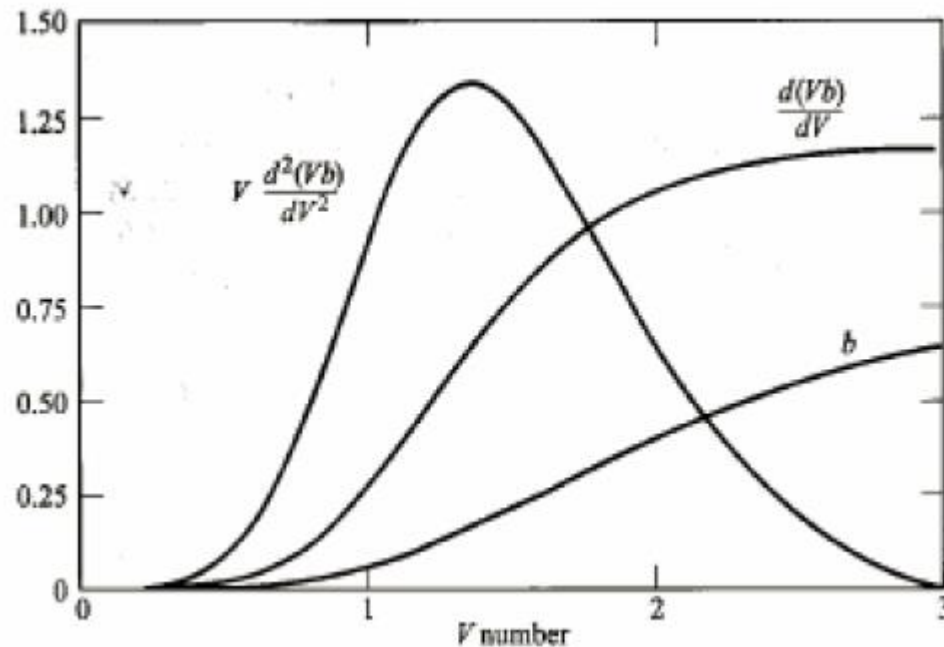
$$\frac{d\tau_w}{d\lambda} = -\frac{n_{clad} \Delta}{c \lambda} V \frac{d^2(bV)}{dV^2}. \quad \text{Waveguide dispersion!}$$

Note: Here we have neglected the dependence of Δ on k_0 , which is negligibly small.



Waveguide dispersion

b , $d(Vb)/dV$ and $V \frac{d^2(Vb)}{dV^2}$ as a function of the V number:

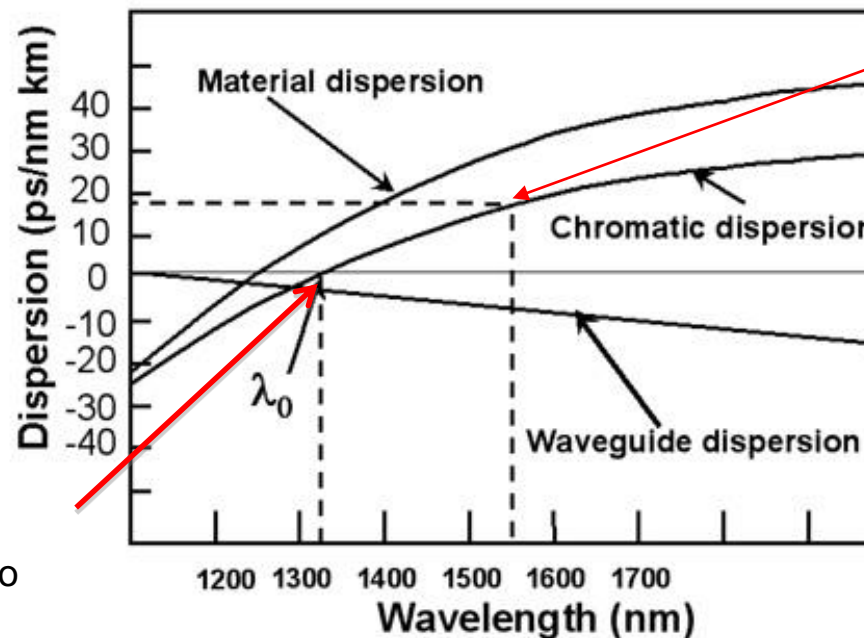




Chromatic dispersion of SMF

- Chromatic dispersion is the combination of material and waveguide dispersion in single-mode fiber (made of fused silica)

$$D = \underbrace{-\frac{\lambda}{c} \frac{d^2 n_{core}}{d\lambda^2}}_{(D_{Material})} - \underbrace{\frac{n_{core} \Delta}{c \lambda} V \frac{d^2 (Vb)}{dV^2}}_{(D_{Waveguide})}$$



at 1.55 μm ,
 $D = +17 \text{ ps/km-nm}$

at 1.312 μm ,
dispersion is zero



Dispersive pulse broadening

Group velocity: $v_g = (d\beta / d\omega)^{-1}$

Pulse broadening ΔT when spectral width of the pulse is $\Delta\omega$:

$$\Delta T = \frac{dT}{d\omega} \Delta\omega = \frac{d}{d\omega} \left(\frac{L}{v_g} \right) \Delta\omega = L \frac{d^2\beta}{d\omega^2} \Delta\omega$$

$$\frac{d^2\beta}{d\omega^2}$$

is the Group Velocity
Dispersion (GVD) parameter

With $\omega = 2\pi c / \lambda$ and $\Delta\omega = \left(-2\pi c / \lambda^2 \right) \Delta\lambda$

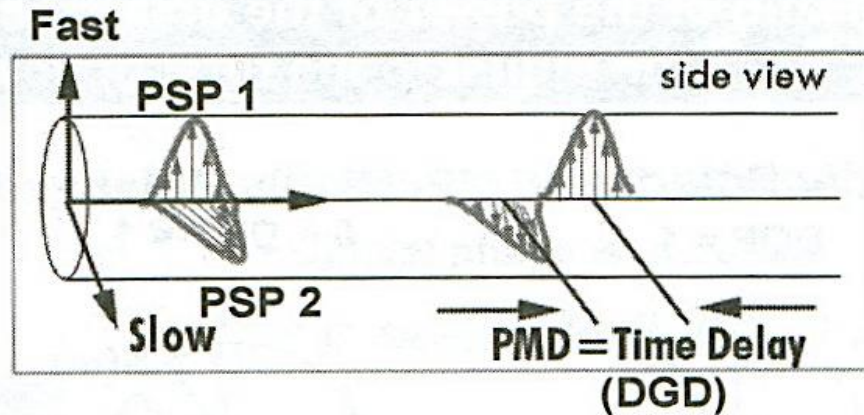
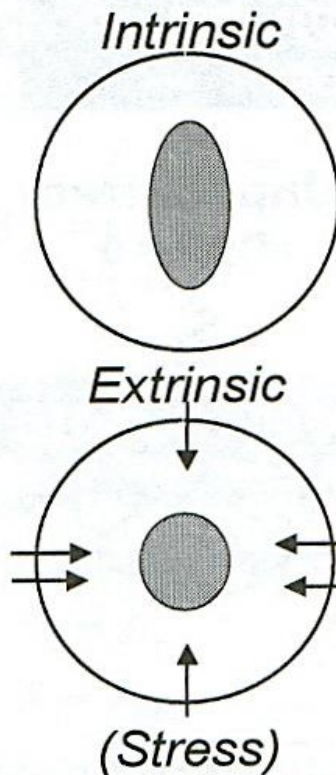
We get: $\Delta T = \frac{d}{d\lambda} \left(\frac{L}{v_g} \right) \Delta\lambda = DL \Delta\lambda$

Here D is the *dispersion parameter*:
[expressed in units of ps/(km-nm)]

$$D = \frac{d}{d\lambda} \left(\frac{1}{v_g} \right) = -\frac{2\pi c}{\lambda^2} \frac{d^2\beta}{d\omega^2}$$

Polarization mode dispersion (PMD)

LP_{01} has two polarization modes - Degeneracy is removed by birefringence.

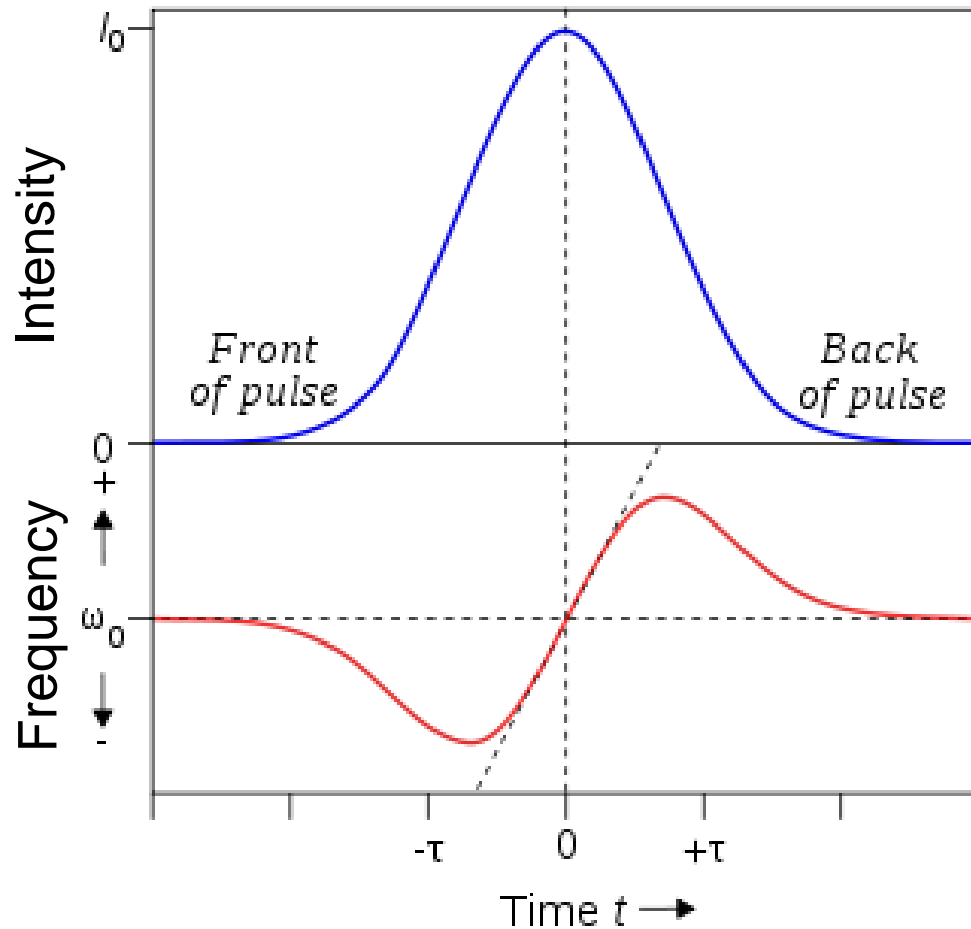


Time delay between two principal-states-of-polarization (PSP) is called the differential-group-delay (DGD).

$$\delta\tau = \frac{|N_y - N_x|L}{c_0}$$

Fiber birefringence causes different polarizations to propagate at different speeds

Nonlinear dispersion: Self phase modulation



$$n(t) = n_0 + n_2 I(t)$$

$$\omega(t) = \omega_0 - \frac{2pL}{I_0} \frac{dn(I)}{dt}$$

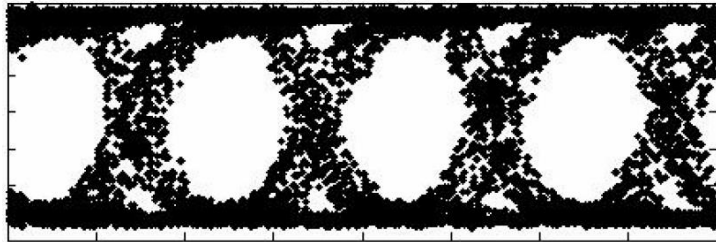
Nonlinearity results in creating a frequency chirp in the pulse. For a Gaussian pulse we have

$$\omega(t) = \omega_0 + \frac{4pLn_2I_0}{I_0 t^2} t \exp\left(-\frac{t^2}{\tau^2}\right)$$



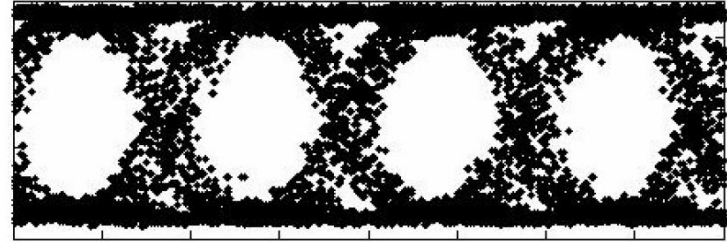
Dispersive pulse broadening

0km



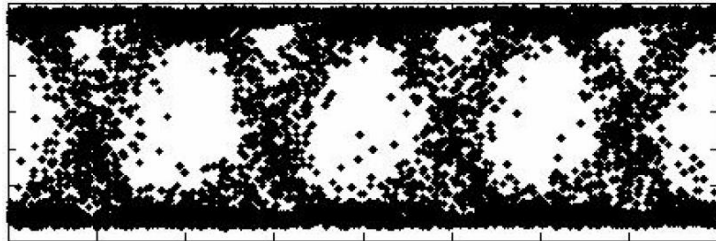
(a)

20km



(b)

40km



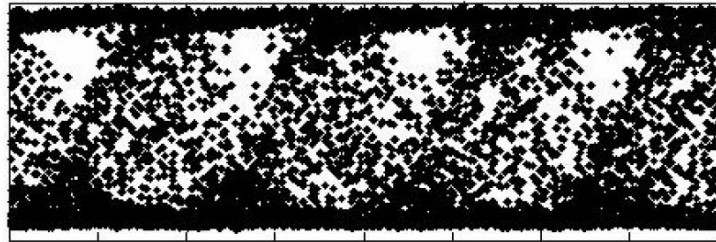
(c)

60km



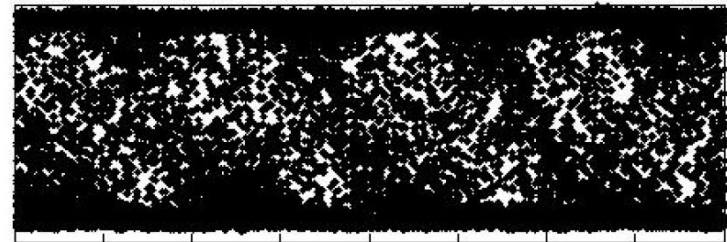
(d)

120km



(e)

240km



(f)



Dispersion compensation

- Pre-chirp technique
- Dispersion engineered fibers
- Dispersion compensating fibers
- Chirped fiber Bragg grating
- Tunable dispersion compensation

Pre-chirp technique

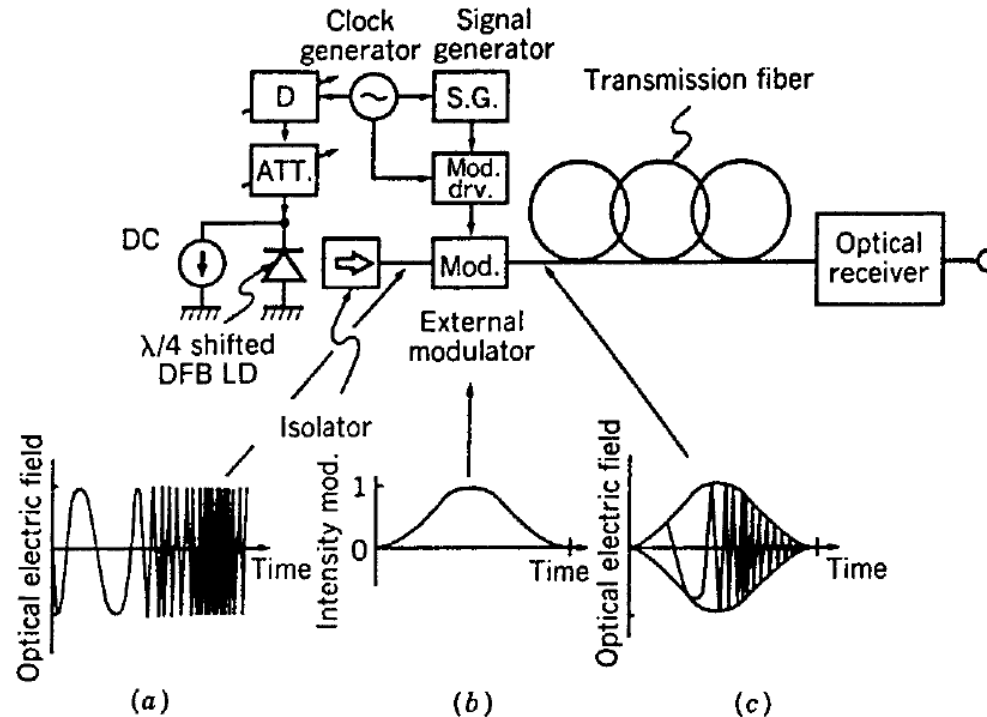
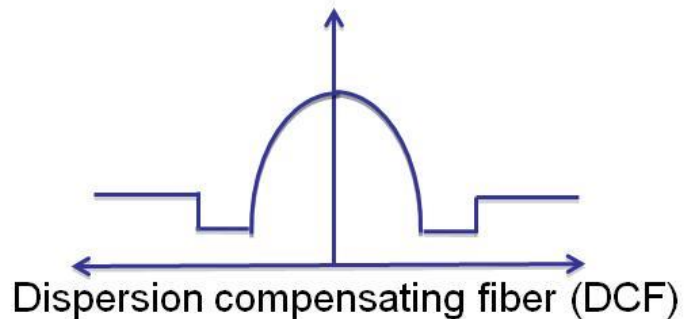
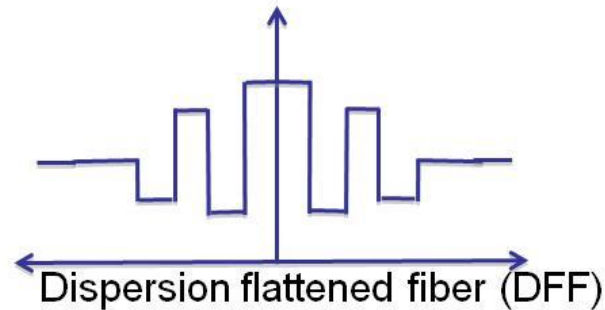
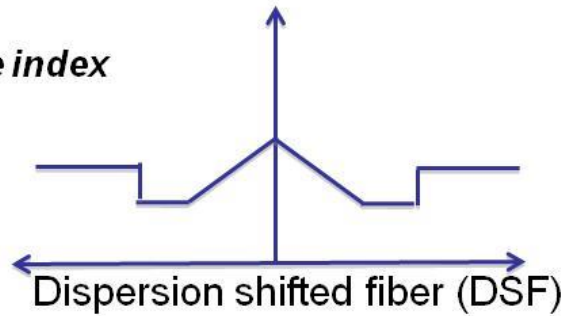


Figure 7.1: Schematic of the prechirp technique used for dispersion compensation: (a) FM output of the DFB laser; (b) pulse shape produced by external modulator; and (c) prechirped pulse used for signal transmission. (After Ref. [9]; ©1994 IEEE; reprinted with permission.)

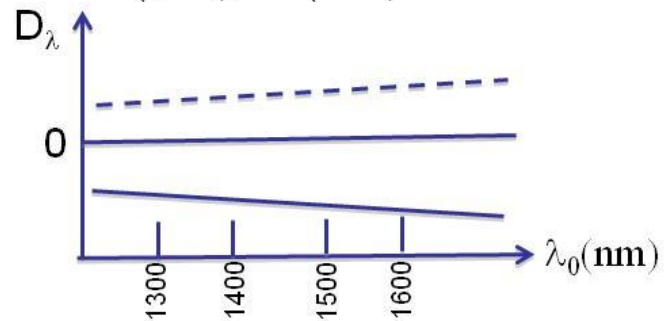
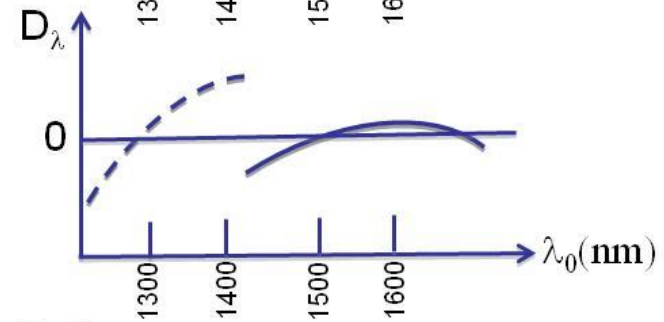
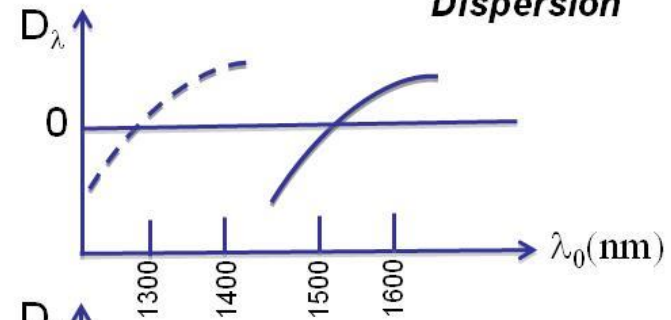


Dispersion engineered fiber

Refractive index profiles

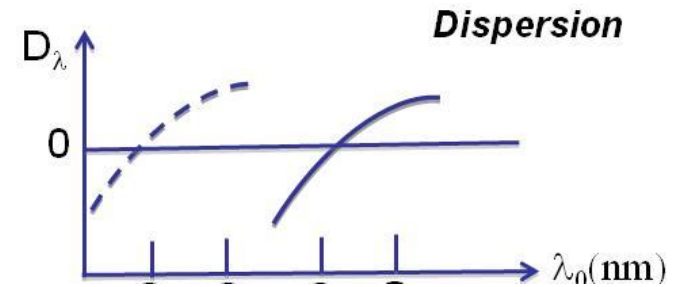
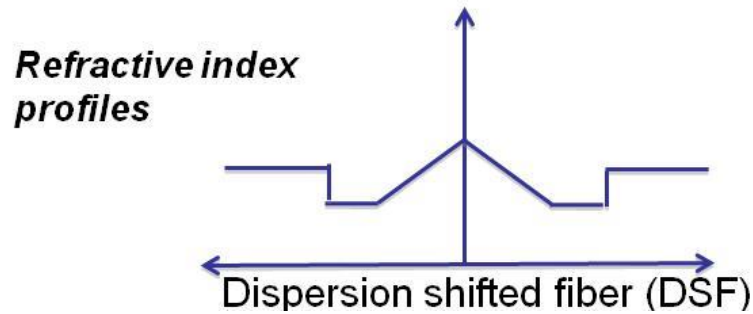


Dispersion

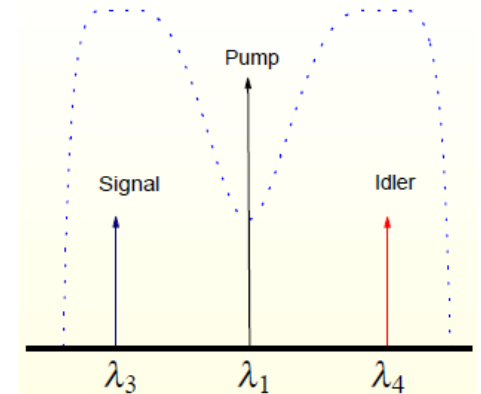




Dispersion engineered fiber

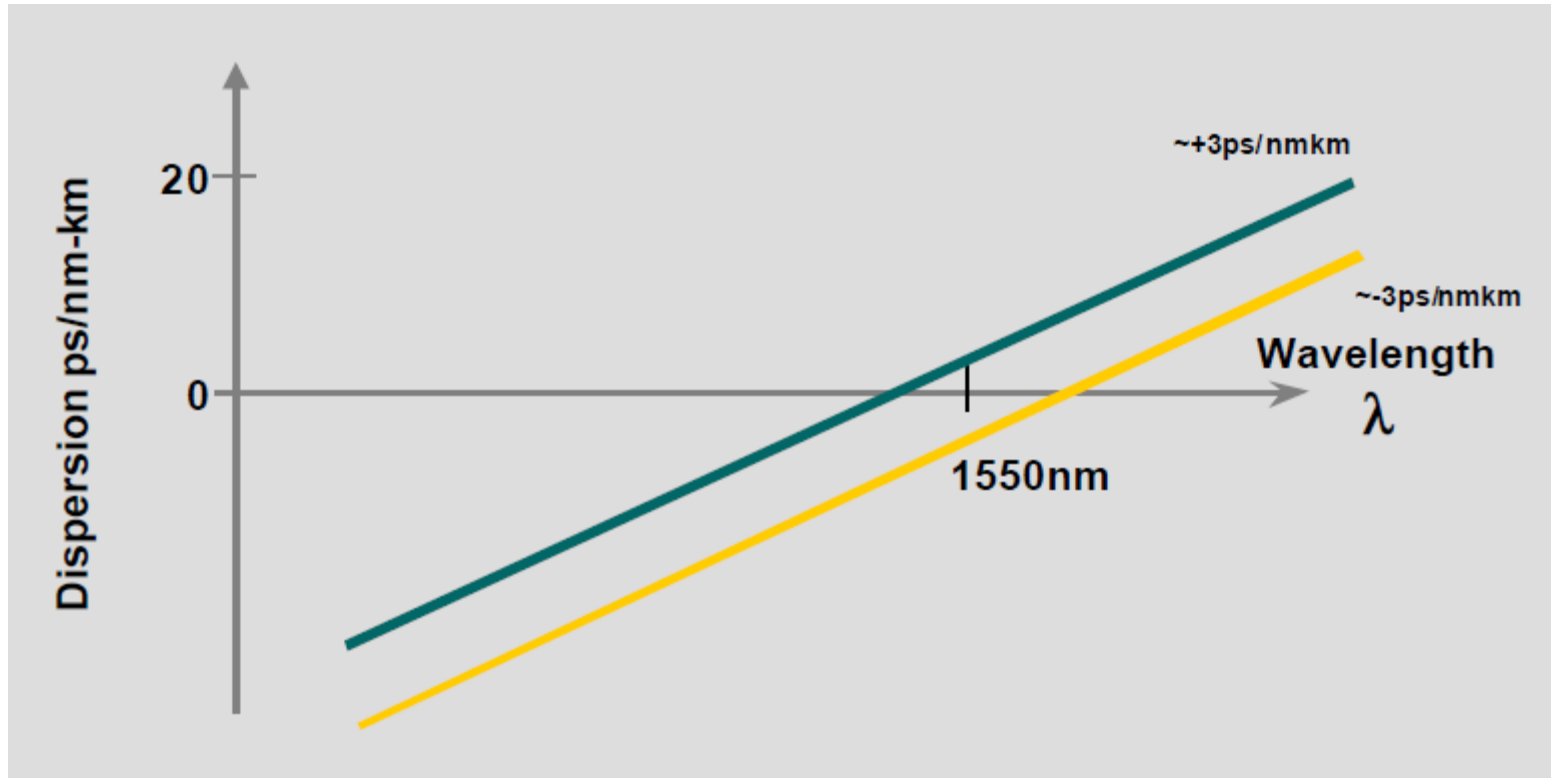


- No dispersion at 1550nm
- But strong Four-Wave-Mixing cross-talk
- Need non-zero dispersion shifted fibers





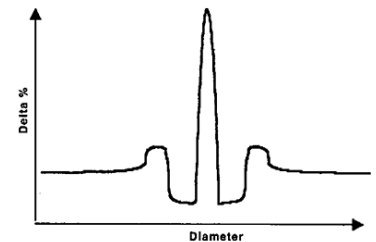
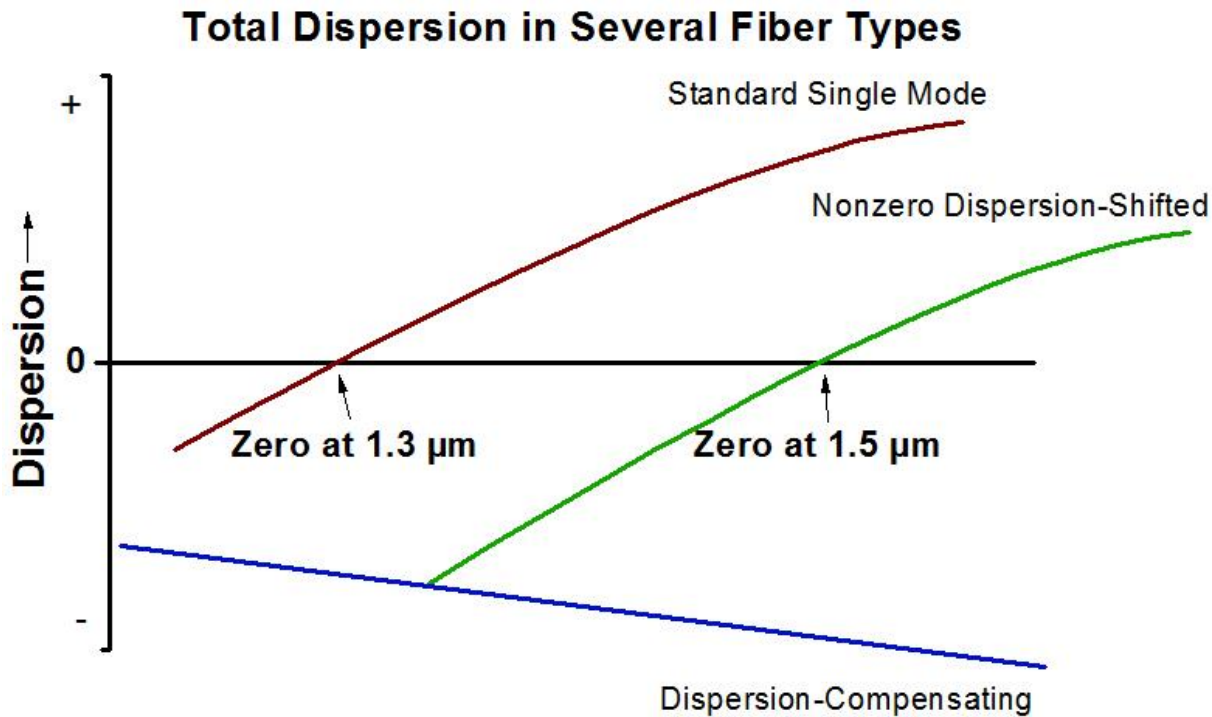
Dispersion engineered fiber



Non-zero dispersion shifted fibers



Dispersion compensating fibers

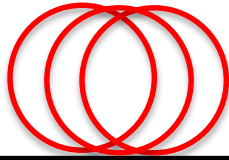


Typical index profile
of a DCF

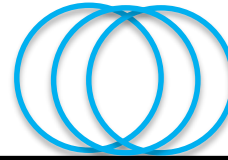


Dispersion compensating fibers

Standard fiber



Dispersion compensating fiber



$$\beta_{21}L_1 + \beta_{22}L_2 = 0, \text{ or}$$

$$D_1L_1 + D_2L_2 = 0.$$



DCF modules

Advantage:

- Fiber format
- Low cost
- Broadband

Disadvantage:

- Small mode field diameter
- Higher loss

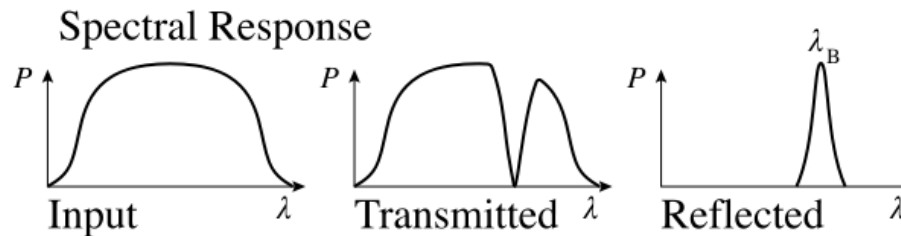
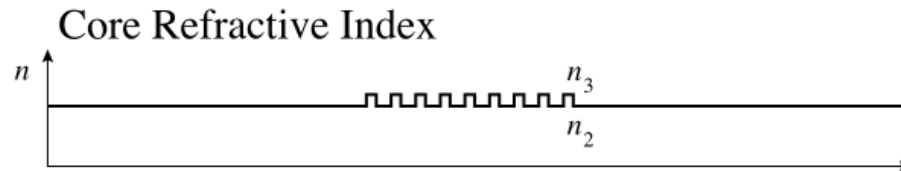
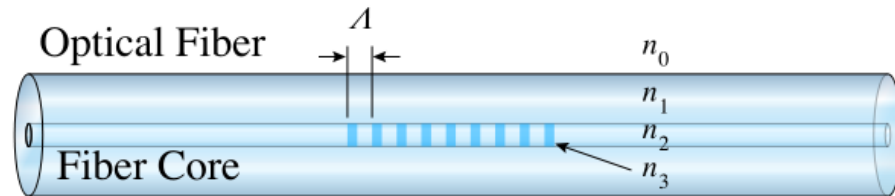


Chirped fiber Bragg grating

Fiber Bragg Grating

Bragg condition:

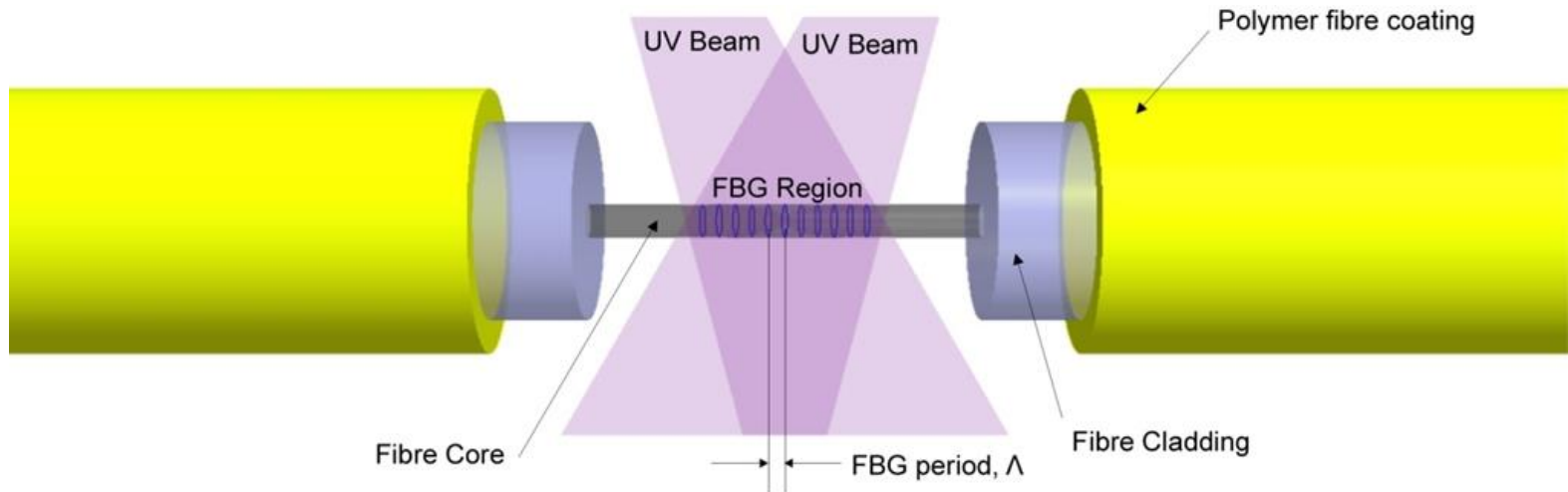
$$\lambda_B = 2n_e\Lambda$$





Chirped fiber Bragg grating

How to make fiber Bragg gratings?





Types of fiber Bragg grating

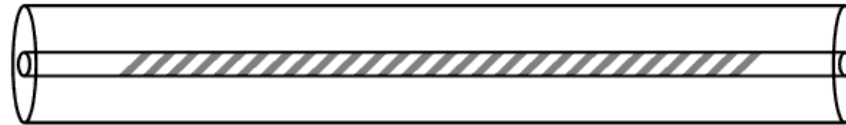
1) Uniform Fiber Bragg Grating



2) Chirped Fiber Bragg Grating



3) Tilted Fiber Bragg Grating

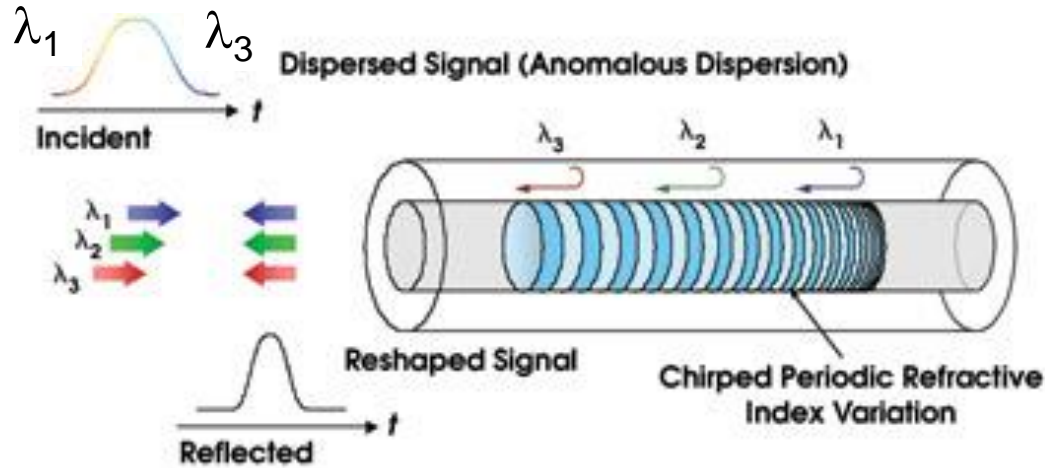


4) Superstructure Fiber Bragg Grating





Chirped fiber Bragg grating



Advantage:

- Low cost
- Low loss

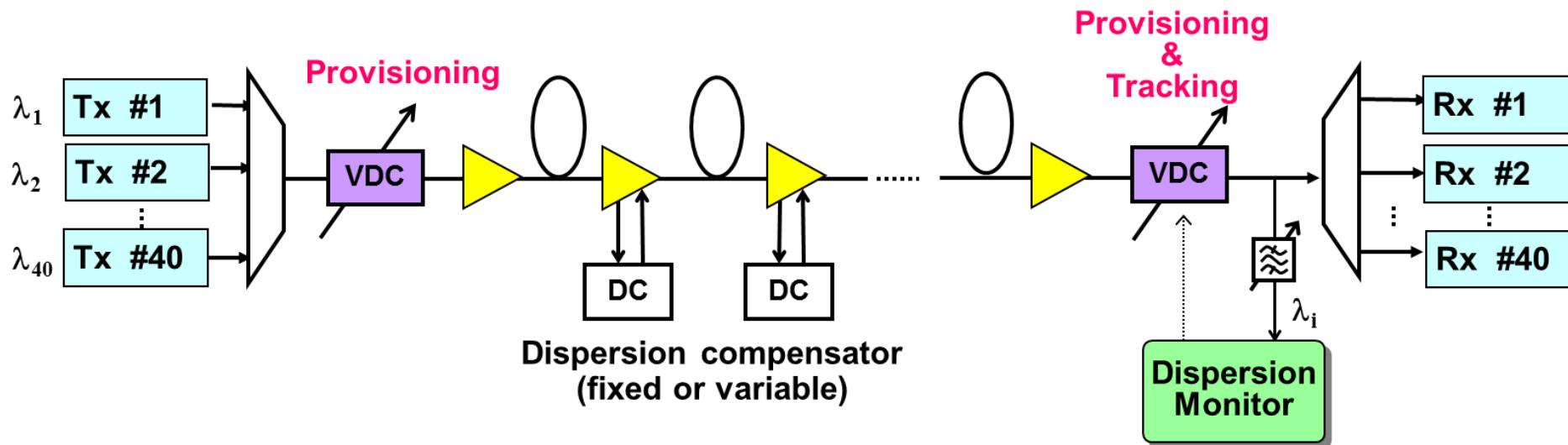
Disadvantage:

- Narrow band



Tunable dispersion compensation

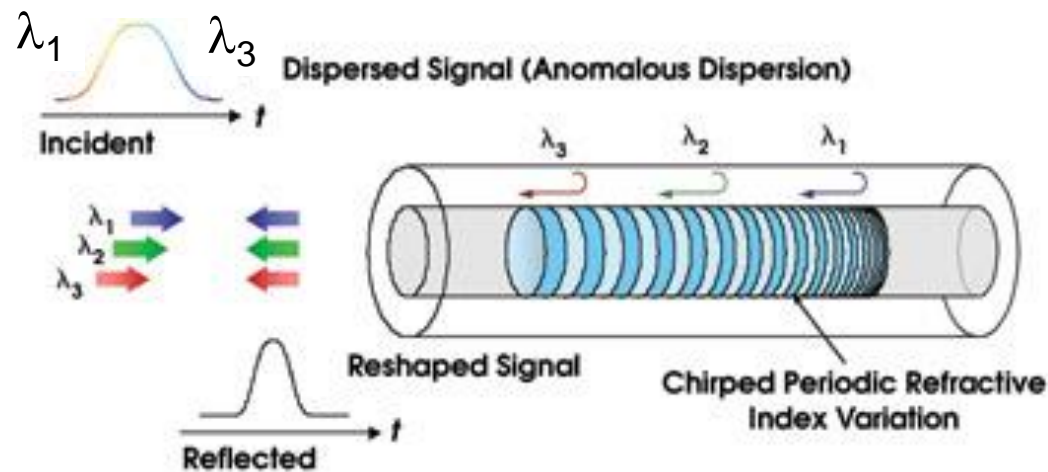
- Provide adjustable dispersion
- Compensate residual dispersion





Tunable dispersion compensation

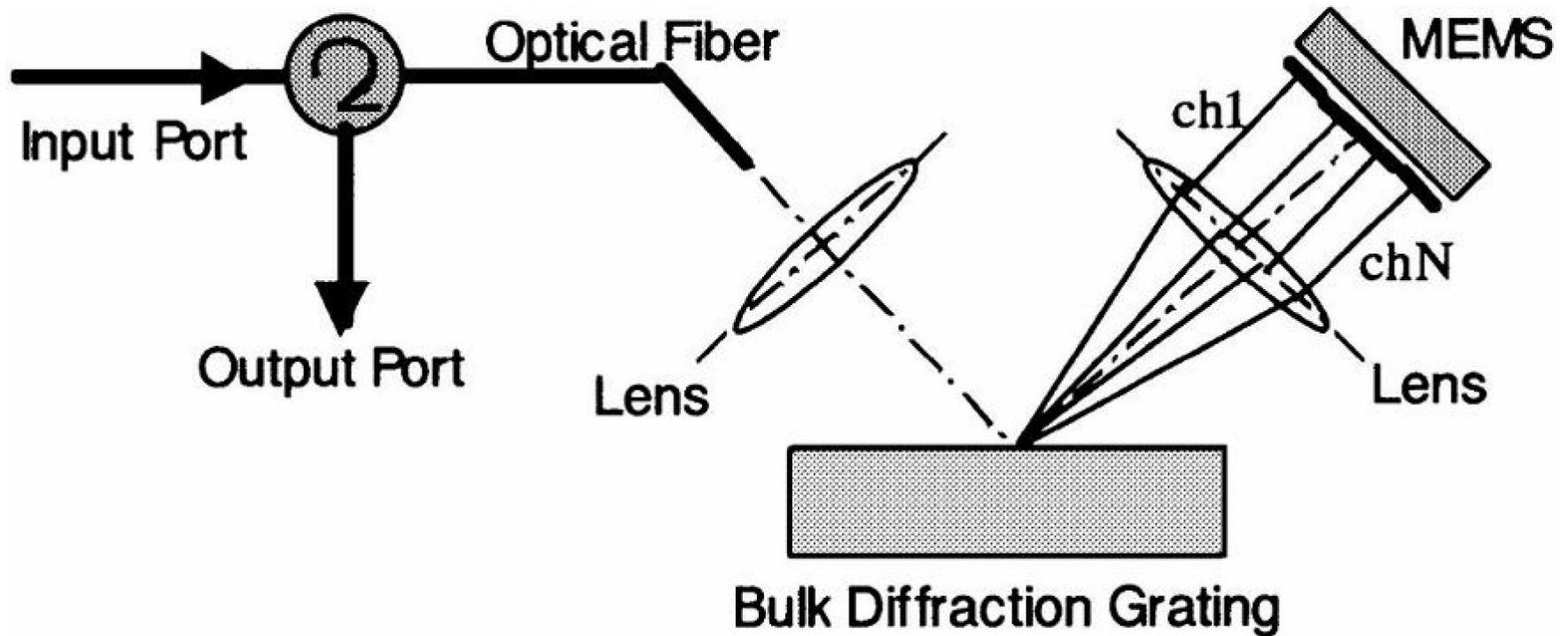
- Provide adjustable dispersion
- Compensate residual dispersion



Mechanical stretching

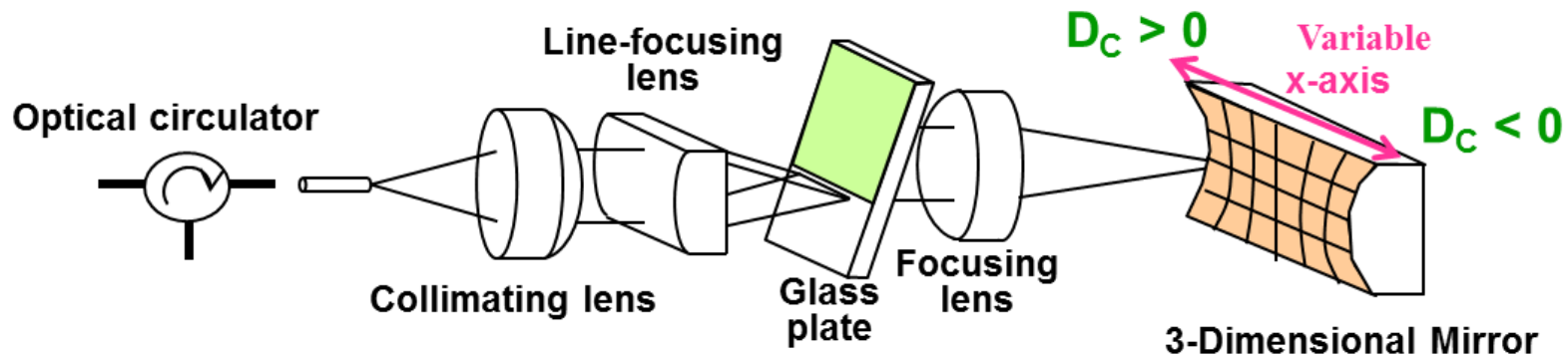


Tunable dispersion compensation

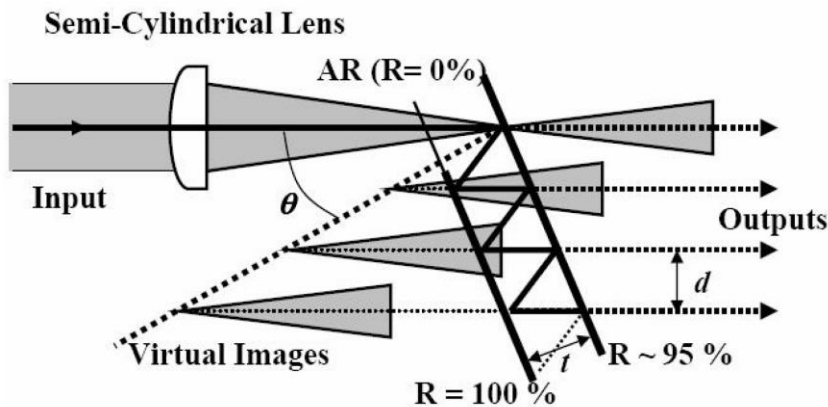


Tunable dispersion compensation

VIPA variable dispersion compensator



VIPA : Virtually Imaged Phased Array

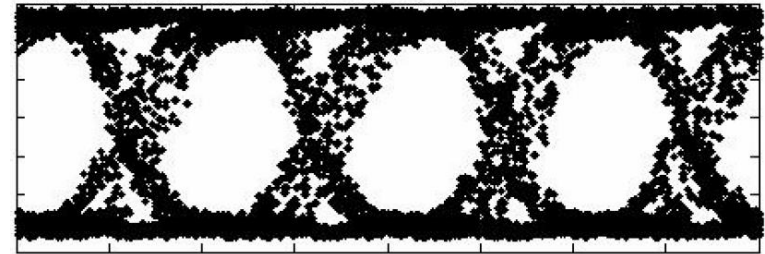




Tunable dispersion compensation



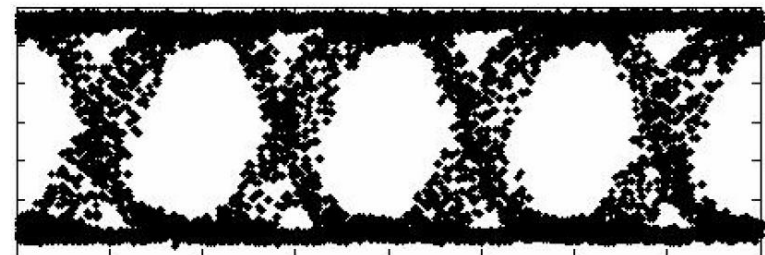
(a)



(b)



(c)



(d)



(f)