

2006 IEEE Medical Imaging Conference

Short Course on Image Quality

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Schedule

- Intro - KJ Myers
- Stochastic Models of Objects and Images - HH Barrett
- Classification Tasks - KJ Myers
- Estimation Tasks - MA Kupinski
- Psychophysics: Experimental Methods and Data Analysis - BD Gallas
- Computational Methods – MA Kupinski
- Applications in Nuclear Medicine - EC Frey

Objective Assessment of Image Quality

- What information is desired from the image?
- What objects will be imaged?
- How will the information be extracted?
- What measure of performance will be used?

What information is desired from the image?

- We call this the TASK
- TASK: Given an image, make an inference about the patient

Two types of inferences

- Classification = labeling
 - Tumor detection (present vs. absent)
 - Malignant vs. benign lesion
 - Is object from H_1 or H_2 ?
- Parameter estimation = quantitation
 - Tumor size, tumor localization
 - Tracer uptake
 - Degree of stenosis

What measure of performance will be used?

- Figure of merit
- Desirable properties:
 - Quantitative
 - Objective
 - Scalar
 - Calculable

Figures of Merit for Classification

- Receiver Operating Characteristic curve
- Average error rate
- Average cost of decisions made
 - Bayes' risk
- Error bounds

Figures of Merit for Estimation

- Bias, variance
- Mean-square error (MSE)
- Ensemble MSE
- Error bounds

How will the information be extracted?

- Observer = decision-making strategy
- Options
 - Human
 - Anthropomorphic model
 - Computer-aided diagnosis (CAD)
 - Best linear detector/estimator
 - Ideal detector/estimator

Ideal Classifier

- Captures all information in the data
- Adds no noise or additional uncertainty
- Test statistic is the likelihood ratio:

$$\Lambda(\mathbf{g}) = \frac{\text{pr}(\mathbf{g} | H_2)}{\text{pr}(\mathbf{g} | H_1)}$$

- Test statistic can be a nonlinear function of the data

Ideal Estimators

- θ : vector of unknown parameters

- ML estimation:
$$\hat{\mathbf{e}}_{\text{ML}} = \underset{\mathbf{e}}{\text{arg max}} \text{pr}(\mathbf{g} | \mathbf{e})$$

- Estimator can be nonlinear in \mathbf{g}

Ideal observers

- Estimation

$$\hat{\mathbf{e}}_{\text{ML}} = \underset{\mathbf{e}}{\text{arg max}} \text{pr}(\mathbf{g} | \mathbf{e})$$

- Classification

$$\Lambda(\mathbf{g}) = \frac{\text{pr}(\mathbf{g} | H_2)}{\text{pr}(\mathbf{g} | H_1)}$$

Both require knowledge of pdf for data conditioned on the object class!

Optimal linear classifier

- Hotelling observer
- Computes test statistic t

$$t = \mathbf{w}_{Hot}^t \mathbf{g} \quad (13.197)$$

where $\mathbf{w}_{Hot} = \mathbf{K}_g^{-1} \Delta \bar{\mathbf{g}}$ (13.177)

Optimal linear estimator

- Generalized Wiener estimator
- Computes linear estimate $\hat{\theta}$

$$\hat{\theta} = \bar{\theta} + \mathbf{W}^t [\mathbf{g} - \bar{\mathbf{g}}]$$

where $\mathbf{W}^t = \mathbf{K}_{\theta, \bar{\mathbf{g}}} \mathbf{K}_g^{-1}$. (13.391)

Optimal linear observers

- Estimation

$$\hat{\theta} = \bar{\theta} + \mathbf{W}^t [\mathbf{g} - \bar{\mathbf{g}}]$$

$$\mathbf{W}^t = \mathbf{K}_{\theta, \bar{\mathbf{g}}} \mathbf{K}_{\mathbf{g}}^{-1}$$

- Classification

$$t = \mathbf{w}_{Hot}^t \mathbf{g}$$

$$\mathbf{w}_{Hot} = \mathbf{K}_{\mathbf{g}}^{-1} \Delta \bar{\mathbf{g}}$$

Both require knowledge of mean, covariance of \mathbf{g} !

What objects will be imaged?

- What is at the input to the system?
 - What set(s) of patients?
 - Biology, chemistry, physics...

Properties we can image

- Acoustic reflectance
 - Medical ultrasound
- Concentration
 - Nuclear medicine
 - MRI (spin density)
 - MRS
- Field strength
 - Biomagnetic imaging
- Attenuation
 - Film densitometry
 - Transmission x-ray
- Scattering properties
 - medical ultrasound
- Electric, magnetic properties
 - Impedance tomography
 - MRI (magnetization)
 - MRI (spin relaxation)
- Source strength
 - Fluorescence microscopy
- Index of refraction
 - Phase-contrast microscopy
- Gene expression
 - DNA chips, microarrays

Objects are continuous functions

- Nuclear medicine: Object is 3D distribution of radiopharmaceutical; 4D if we consider time variation
- X-ray imaging: Object is 3D distribution of x-ray absorption and scattering coefficients (vector valued)
- Written as $f(\mathbf{r})$ or $f(\mathbf{r},t)$ or \mathbf{f}

Digital images are discrete data sets

- We write the data as a vector \mathbf{g}
- Elements of \mathbf{g} are written g_{ij} or g_m
- Index contains voxel label, including detector location, projection angle, time, etc.

Imaging is a process that maps the object to the data

- We write this as: $\mathbf{g} = \mathcal{H} \mathbf{f} + \mathbf{n}$
- \mathcal{H} is the mapping (system operator)
 - May be nonlinear
- \mathbf{n} is the measurement noise (a vector)
 - Not necessarily additive

Which \mathcal{H} is best?

- Need models/measures of \mathcal{H} to characterize the data

Definitions of probability

- | | |
|---|--|
| ■ Frequentists | ■ Bayesians |
| – Relative frequency of occurrence | – Not simply a frequency |
| – Games of chance (e.g., roll of a die) | – No need to verify with multiple trials |
| – Multiple experimental trials | – Degree of belief |

Conditional probability of the image data

- $\text{pr}(\mathbf{g}|\mathbf{f})$: essential for optimal inference
- Describes randomness in data \mathbf{g} for fixed object \mathbf{f}
- In principle, could repeat observations of same object to determine $\text{pr}(\mathbf{g}|\mathbf{f})$

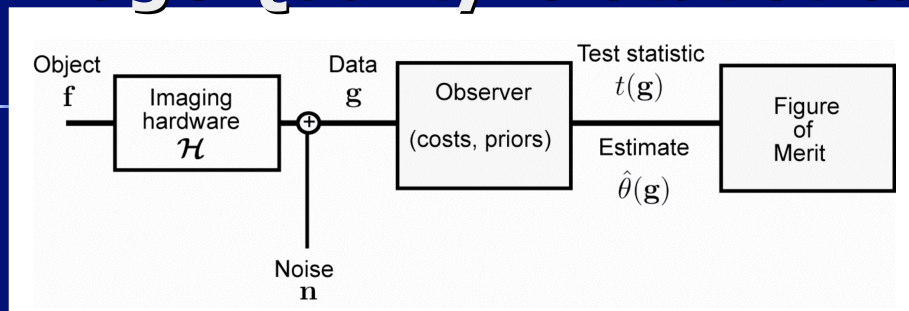
Role of Prior Information

- Prior: $\text{pr}(\mathbf{f} | H_i)$ or $\text{pr}(\theta)$
- State of knowledge before imaging
- Data are noisy; often have better inference by enforcing what we know about the object in advance

How to determine prior?

- Difficulty is dimensionality: How to determine $\text{pr}(\mathbf{f})$ by frequentist means?
 - May make headway on lower-dimensional problem, e.g., rate parameter
- Bayesian answer:
 - Prior isn't a relative frequency
 - It captures a belief (e.g., smoothness)

Image Quality is Statistical



- The observer computes a test statistic or estimate: $t(\mathbf{g})$ or $\hat{\theta}(\mathbf{g})$. Inference may involve a Bayesian prior.
- The inferential process is repeated using many realizations of objects and noise.
- Analyze statistics of $t(\mathbf{g})$ or $\hat{\theta}(\mathbf{g})$ to determine a figure of merit. → Frequentist performance measure!